

CHAPTER 14: TECHNICAL SPECIFICATION OF CONTROL AND RELAY PANEL

14.1 TECHNICAL SPECIFICATIONS FOR CONTROL & RELAY PANELS:

- a) This Section is intended to cover the design, manufacture, assembly, testing at manufacturer's works and erection, testing & commissioning of Indoor Relay and Control Panels.
- b) The Control and Relay Panels required are for control and protection of the Power Transformers and Feeders according to requirements. The supply shall include all accessories, special tools, supporting steels, spare parts, drawings, relevant software, instruction manuals etc. The panels shall be supplied complete with all accessories as specified and completely assembled and all internal wiring completed.
- c) The sub-stations shall have automation as per IEC 61850 protocol in Bay & Station level. The bidder has to supply the C&R panels to match the requirement of Sub-station Automation System (SAS) as specified in the subsequent chapter, **from the same manufacturer**.
- d) **The manufacturer/supplier of Control and Relay Panels shall necessarily be an OEM (Original Equipment Manufacturer) of Numerical Protective Relays, Bay Control Units and Sub Station Automation System (SAS), having registered servicing unit in India.**
- e) Design and fabrication of Control & Protection Panels for mounting the relay and relay assemblies along with all necessary accessories like switches, indicating lamps etc. and wiring up of the same to provide self contained and ready to use protection as per this specification.
- f) Complete testing at manufacturer's works of the relays and protection schemes **including SAS** after mounting and fully wiring up in the Control & Protection Panels.

14.2 STANDARDS:

All equipment and all component parts supplied under this specification shall conform in all respects to the latest issue of relevant IEC and Indian Standard Specifications except where specified otherwise in this specification. Equipment meeting any other authoritative standards which ensure an equal or better quality may also be acceptable.

14.3 SERVICE CONDITIONS:

The plant and materials supplied shall be suitable for operation under the following climatic and other conditions as mentioned in chapter 2 of this Bid document:

14.4 TYPE TEST REPORTS.

14.4.1 Equipment, which have never been tested for critical performance, shall not be accepted. In such cases, a promise or agreement by a bidder to have the equipment tested after award of a contract is not acceptable.

14.4.2 All Bids must be accompanied by the full Type Test Certificates of equipment offered. Such type test certificates shall be acceptable only if:

- i) Tests are conducted in KEMA/NABL accredited laboratory, *for GOOSE messaging etc as per relevant IEC 61850 Standards*.

- ii) Inter-operability Tests are conducted in manufacturer's own laboratory. In this case (i) the laboratory must have ISO 9000 (or its equivalent) series certification; and (ii) tests have been witnessed by technically qualified representatives of earlier Indian clients of Central/State Transmission Utilities.
- iii) The Validity of the Type Test Reports of CRP, Relays, BCUs and Energy Meters shall be as per CEA's "Guidelines for the Validity Period of Type Tests Conducted on Major Electrical Equipment in Power Transmission System", File No CEA-PS-14-80/1/2019-PSETD Division-Part (2).

14.5 TYPE OF PANEL

14.5.1 All simplex panels shall be swing type with front glass door with locking arrangement. The **Minimum number** of Panels shall be as per Table 1 below:

Table -1

	400kV	220kV	132kV	33kV
Feeder Panel	4 Nos if SWLR	2 Nos	2 Nos	1 No
Bus Coupler/Tie Breaker/Sectionalizer Panel	2 No	1 No	1 No	1 No
Reactor Panel	2 No			
Bus Bar Protection panel	4 Nos	2 Nos		
Transformer Panel	400/220/33kV AT	220/132kV AT	132/33kV PT	
	3Nos (Minimum)	2Nos (Minimum)	2 Nos (Minimum)	

14.5.2 Swing type Simplex Control and Relay Panels shall consist of vertical swing front panels with equipment mounted thereon and having front glass door. As there will be no rear door, manufacturer shall have to keep suitable swing angle, for maintenance & testing of equipment, circuitry inspection etc. Panel front shall have lockable glass door.

14.5.3 These panels shall be of the **Simplex type** with the following approximate dimensions:

- i. Height: 2250mm + 15mm anti-vibration pad + 50 mm (base)
- ii. Depth: 800mm to 1000 mm
- iii. Width: 800 mm to 1000 mm
- iv. Operating Height: 1800 mm

14.5.4 For 33kV feeder, panel shall be of simplex type and it should accommodate one 33kV feeder in a single cubicle and one BCU will control single 33kV feeder.

14.6 CONSTRUCTIONAL FEATURES:

- a) The panels shall be completely metal enclosed to ensure a dust, moisture and vermin proof atmosphere. The enclosure shall provide a degree of protection not less than IP 54 in accordance with IS-2147/IEC-60529.
- b) Panels shall be rigid free standing and floor mounting type and comprise of structural frames enclosed completely with specially selected texture finished, cold rolled sheet steel of thickness not less than 3.15 mm for weight bearing members of the panels

such as base frame, front sheet and door frames and not less than 2.0 mm for sides, door top and bottom portions. There shall be sufficient reinforcement to provide level surfaces, resistance to vibration and rigidity during transportation and installation.

- c) All joints shall be made flush and all edges shall be bent at right angles and rounded. All structural members shall be bolted or welded together. Necessary arrangement shall be provided for bolting together the adjacent panels as well as for fastening them to the floor. The opening required for mounting the equipment shall be punched or cut and filed smooth.
- d) All doors, removable covers and panels shall be sealed all around with synthetic rubber gaskets Neoprene/EPDM generally conforming to provision of IS 11149. However, XLPE gaskets can also be used for fixing protective toughened glass doors. Ventilating louvers, if provided shall have screens and filters. The screens shall be made of either brass or GI wire mesh.
- e) Panels shall have additional rolled channel plinth at the bottom with smooth bearing surface. The panels shall be fixed on the embedded foundation channels with intervening layers of anti-vibration strips made of shock absorbing materials which shall be supplied by the contractor.

14.7 MOUNTING OF EQUIPMENTS:

- a) All equipment on and in the panels shall be mounted and completely wired to the terminal blocks ready for external connection. All equipment on the front panels shall be mounted flush. Terminal markings shall be clearly visible.
- b) Bay level intelligent electronic devices (IED) BPU for protection and control (BCU) and the Managed Ethernet Switch shall be housed in the C&R panels installed in the local control room.

14.8 INTERNAL WIRING:

- a) Panels shall be supplied completely with interconnecting wiring provided between all electrical devices mounted and wired in the panels and between the devices and terminal blocks for the devices to be connected to equipment outside the panels. When panels are located adjacent to each other all inter panel wiring and connections between the panels shall be furnished and wiring shall be carried out internally. These adjacent inter panel wiring shall be clearly indicated in the drawing furnished by the supplier.
- b) Bay level intelligent electronic devices (IED) for protection, control (BCU) and the Managed Ethernet Switch shall be housed in the C&R panels installed in the local control room.
 - i) All Circuits except instrument transformers **and incoming AC/DC Supply** circuits: 1.5 sq. mm. per lead.
 - ii) Instrument transformers circuit: 2.5 sq. mm. per lead.
- c) Auxiliary bus wiring for AC and DC supplies, voltage transformer circuits, annunciation circuits and other common services shall be provided near the top of the panel running throughout the entire length of the panels.
- d) Wire terminals shall be made with solder less clamping type of tinned copper lugs, which firmly grip the conductor and insulation. Insulated sleeves shall be provided at all the wire terminations. Engraved core identification plastic ferrules marked to correspond with panel wiring diagram shall be fitted at both ends of each wire.

Ferrules shall fit tightly on the wires and shall not fall off when the wire is disconnected from blocks.

- e) Interconnections to adjacent panels shall be brought out to a separate set of terminals blocks located near the slots or holes meant for taking the interconnecting wires. Arrangement shall permit easy interconnection to adjacent panels at site and wires for this purpose shall be provided by the supplier looped and bunched properly inside the panel.
- f) A laminated copy of total schematics is to be fixed on the inside of door.

14.9 TERMINAL BLOCKS:

- a) All internal wiring to be connected to the external equipment shall terminate on terminal blocks, preferably vertically mounted on the side of each panel. Terminal blocks shall be of 1100 volts grade and have 10 amps continuous rating, moulded piece, complete with insulated barriers, stud type terminals, washers, nuts and lock nuts. Terminal block designs include a white fibre-marking strip with clear plastic/silicon chip on terminal covers. Marking on the terminal strips shall correspond to block and terminal number on the wiring diagram.
- b) Terminal blocks for current transformer and voltage transformer secondary leads shall be provided with test links and isolating facilities. Current transformer secondary leads shall also be provided with short-circuiting and earthing facilities.
- c) At least 20% spare terminals shall be provided on each panel and these terminals shall be uniformly distributed on all terminal blocks.
- d) There shall be a minimum clearance of 250 mm between first row of terminal blocks and associated cable gland plates. Also, the clearance between two rows of terminal blocks shall be a minimum of 150 mm. A steel strip shall be connected between adjacent terminal block rows at 450-mm intervals for support of incoming cables.

14.10 PAINTING:

- a) All Sheet steelwork shall be phosphated in accordance with IS 6005.
- b) Oil grease, dirt and warp shall be thoroughly removed by emulsion cleaning. Rust and scale shall be removed by pickling with dilute acid followed by washing with running water, rinsing with slightly alkaline hot water and drying.
- c) After phosphating, thorough rinsing shall be carried out with clean water followed by final rinsing with dilute dichromate solution and oven drying. The phosphate coating shall be sealed with application of 2 (two) coats of ready mixed, stoving type zinc chromate primer. The first coat may be 'flash dried' while the second shall be stoved.
- d) After application of the primer, two coats of finishing synthetic enamel paint shall be applied, each coat followed by stoving. The second finishing coat shall be applied after completion of tests. Exterior Paint shall be texture finishing with RAL 7032 paint shade.
- e) Each coat of primer and finishing paint shall be of a slightly different shade to enable inspection of the painting.
- f) The inside of the panels shall be glossy white.
- g) A small quantity of finishing shall be supplied minor touching up required at site after installation.

14.11 NAME PLATES AND MARKINGS:

- a) All equipment mounted on front and rear side as well as equipment mounted inside the panel shall be provided with individual nameplates with equipment designation engraved. Also, on the top of each panel on front as well as rear side large and bold name plates shall be provided for circuit /feeder designation.
- b) All front mounted equipment shall be also provided at the rear with individual name plates engraved with Tag numbers corresponding to the one shown in the panel internal wiring to facilitate easy tracing of the wiring. The nameplates shall be mounted directly by the side of the respective equipment and shall not be hidden by the equipment wiring.
- c) Nameplates shall be made of non-rusting metal or 3 ply lamincord. Nameplates shall be black with white engraved lettering.

14.12 MISCELLANEOUS ACCESSORIES:

- a) A 240 Volts, single-phase plug points shall be provided in the interior of each cubicle with ON-OFF switch for connection of headlamp.
- b) Each panel shall be provided with a LED lighting fixtures for the interior illumination of the panel complete with all fittings, i.e. lamp, switch (controlled by panel door)
- c) Each control panel shall be provided with necessary arrangements for receiving, distributing, isolating and fusing of D.C. and A.C. supplies of various control, AC & DC supervision, signalling, lighting and space heater circuits. MCBs of requisite capacity with fail indicators shall be used, HRC fuse is not acceptable. The main input A.C. and D.C. circuits will be protected with miniature circuit breakers.
- d) Pistol Grip Trip Switch shall be provided.

14.13 EARTHING:

- a) All panels shall be equipped with an earth bus securely fixed along with inside base of the panels. The materials and the sizes of the bus bar shall be at least **25X6 mm copper**. When several panels are mounted joining each other, the earth bus shall be made continuous and necessary connectors and clamps for this purpose shall be included in the scope of supply. Provisions shall be made for extending the earth bus bar to future adjoining panels on either side.
- b) All metallic cases of equipment shall be connected to the earth bus by independent copper wires of size not less than 2.5 sq. mm. Earthing wire shall be connected on terminals with suitable clamp connectors and soldering shall not be permitted.
- c) PT and CT secondary neutrals or common lead shall be earthed at one place only at the terminal blocks, where they enter the panels.

14.14 RECORDING METERS (ABT TRIVECTOR METERS):

14.14.1 General

- a) All meters shall be housed in dust proof, moisture resistant, black finished cases and shall be suitable for tropical use. They shall be accurately adjusted and calibrated at works and shall have means of calibration, check and adjustment at site.
- b) All these instruments and meters shall be flush mounted type and back connected, suitable for front panel mounting.
- c) The ABT meters shall be SAMAST compatible as per specification given in subsequent chapter.

- d) The meters should be compatible to IEC62052-11 and IEC62053-22, IEC62053-24, IS14697, IS15959.
- e) The manufacturer shall provide Performance Certificate from CTU/STU of successful operation of minimum 3 years as on BID Opening.

14.15 RELAYS:

14.15.1 General

- a) All relays shall conform to the requirements of IS 3231/ IEC 60255/ IEC 61000 or other relevant standards. The relay firmware/software shall be of the latest version.
- b) All protective relays shall be numerical type and communication protocol shall be IEC 61850. Further, test levels of EMI as indicated IEC 61850 shall be applicable to these relays.
- c) Two sets of relevant software (latest version) for relay configuration & setting, maintenance etc to be supplied to each station. The numeric relay and software shall be upgradable.
- d) The protective relays shall be suitable for efficient and reliable operation of the protection scheme described in the specification. Necessary auxiliary relays and timers required for interlocking schemes for multiplying of contacts suiting contact duties of protective relays and monitoring of control supplies and circuits etc. also required for the complete protection schemes described in the specification shall be provided. All protective relays shall be provided with at least two pairs of potential free isolated output contacts. Auxiliary relays and timers shall have pairs of contacts as required to complete the scheme contacts shall be silver faced with spring action. Relay case shall have adequate number of terminals for making potential free external connections to the relay's coils and contacts, including spare contacts.
- e) Relays shall be suitable for flush or semi-flush mounting with connectors from rear.
- f) All draw out cases or plug in type modular cases will have proper testing facilities. The testing facilities provided on the relays shall be specifically stated in the bid. All protective relays shall be with proper online testing facilities without isolation from TB where inputs viz CT/ PT and DC are wired. All main relays shall be provided with test plug to test the relay online & required test handle may be invariably indicated. Necessary test plug shall be in the supplier's scope of supply and shall be supplied loose. Unless otherwise specified all auxiliary relays and timers shall be supplied either in non-draw out cases or plug in type modular cases.
- g) All A.C. relays shall be suitable for operation at 50 Hz. A.C. Voltage operated relays shall be suitable for 110 volts VT secondary and current operated relays for 1Amp. CT secondary. DC auxiliary relays and timers shall be designed for 110 volts/ 220 volts DC and shall operate satisfactorily between 70% and 110% of rated voltage. Voltage operated relays shall have adequate thermal capacity for continuous operation.
- h) All Protective relays, auxiliary relays and timers except the lockout relays and interlocking relays shall be provided with self-reset type contacts. All protective relays, trip relays and timers shall be provided with externally/ electrically reset positive action operation indicators provided with proper inscription. All protective relays which do not have built-in hand reset operation indicators shall have additional auxiliary relays with operating indicators for this purpose. Similar separate operating indicators (auxiliary relays) shall also be provided in the trip circuits of protections located outside the board such as Buchholz relays, temperature protection etc.

- i) No control relays that shall trip the circuit breaker when the relays are de-energized shall be employed in the circuits.
- j) All relays shall withstand a test voltage of 2.5 kV, 50 Hz rms. voltage for one second. In case of static relays, the Clause 14.28.1.I shall be applicable.
- k) Auxiliary seal-in unit provided in the protective relays shall preferably be of shunt reinforcement type. If series relays are used the following shall be strictly ensured:
 - (i) The operating time of the series seal-in unit shall be sufficiently shorter than that of the trip coil relay in series with which it operates to ensure definite operation of the flag indicator of the relay.
 - (ii) Seal - in unit shall obtain adequate current for operation when one or more relays operate simultaneously.
 - (iii) Impedance of the seal-in unit shall be small enough to permit satisfactory operation of the trip coil on trip relays when D.C. supply is minimum.
 - (iv) Trip-circuit seal-in is required for all trip outputs, irrespective of the magnitude of the interrupted current. The trip-circuit seal-in logic shall not only seal-in the trip output(s), but also the relevant initiation signals to other scheme functions, (e.g. initiate signals to the circuit-breaker failure function, reclosing function etc.), and the alarm output signals.
 - (v) Two methods of seal-in are required, one based on the measurement of AC current, catering for those circumstances for which the interrupted current is above a set threshold, and one based on a fixed time duration, catering for those circumstances for which the interrupted current is small (below the set threshold).
 - (vi) For the current seal-in method, the seal-in shall be maintained until the circuit-breaker opens, at which time the seal-in shall reset and the seal in method shall not now revert to the fixed time duration method. For this seal-in method, the seal-in shall be maintained for the set time duration. For the line protection schemes, this time duration shall be independently settable for single- and three-pole tripping.
 - (vii) Seal-in by way of current or by way of the fixed duration timer shall occur irrespective of whether the trip command originates from within the main protection device itself (from any of the internal protection functions), or from an external device with its trip output routed through the main protection device for tripping. Trip-circuit seal-in shall not take place under sub-harmonic conditions (e.g. reactor ring down).
- l) Whenever solid state auxiliary relays are used the following requirements shall be met with:
 - i) The printed circuit cards shall be of fibre glass type and the contact shall be gold plated. All connectors with the connector pegs shall be through wire wrapping. All solder joints on the printed circuit boards shall be encapsulated or covered with varnish.

- ii) The components shall be loaded by less than half of their rated values. The resistor shall be of carbon composition or metal oxide type and the capacitors shall be plastic film or tantalum type. Stringent measures including shielding of long internal wiring should be taken to make relays immune to voltage spikes. Relays must withstand 5kW, 1x150 microsecond, 0.5 Joule source energy impulse test or 1.5 MHz damp oscillations with initial value of 2.5 kV decaying to half the initial value in 6 microseconds with internal source impedance of 150 ohms.
- iii) The supplier shall ensure that the terminals of the contacts of the relays are readily brought out for connectors as required in the final approved scheme.
- iv) DC /DC converter shall be provided in the solid state protective relays wherever necessary in order to provide a stable auxiliary supply for relay operation. Provision of DC cell in the protective relays as relievable stand-by power supplies will however not be acceptable.
- m) Provision shall be made for easy isolation of trip circuits of each relay for the purpose of testing and maintenance.
- n) All Spare pair of contacts of all IEDs and Alarm Relays shall be wired to Terminal Blocks exclusively for Employer's use.
- o) All relays and their drawings shall have phase indications as R-Red, Y-Yellow, B-Blue.
- p) The bidder shall include in his bid a list of installations where the relays quoted have been in satisfactory operation.

14.15.2 General Specification of Numerical Relays

- a) Numerical Relays shall be provided for the following applications:
 - i) Distance Protection (Main I & Main II) of different make and model for 400KV and 220 kV lines.
 - ii) Distance protection for 132 kV lines.
 - iii) Back up directional over current and earth fault relays for 132 kV Lines.
 - iv) Back up non directional over current (3 O/C) and earth fault relays for 33kV lines
 - v) Bus Bar Protection.
 - vi) Integrated Numerical Transformer Differential Protection as Main –I & Main-II of different make **and model** with non-directional overcurrent and earth fault function with high set units for power and autotransformers/ reactors.
 - vii) Reactor Protection.
 - viii) *Line Differential Protection*

(viii) 3 winding transformer protection relay for Main-1 & Main-2 shall be provided for all the transformers under the scope of this bid

- b) All Numerical Relays should have following minimum features.
 - i) Relays shall be communicable on IEC61850 protocol without any protocol converter. Certificate from KEMA confirming interoperability, Goose messaging &

publishing as per IEC61850 standard shall be submitted along with the tender. The relay shall have suitable communication facility for future connectivity to SCADA.

- ii) Relays shall have one no. front RJ45 or USB port (for RS 232 port Converter to USB shall be supplied for each substation along with spare) for Local Relay Parameterization and Two nos. rear FO port for connectivity to SAS over IEC61850 protocol.
- iii) The relay shall have self-communication port monitoring feature and failure shall generate alarm.
- iv) The relay shall have sufficient battery back up to keep the internal clock running for at least 2 years in absence of auxiliary supply. The capacitor discharging power is not sufficient and won't be accepted. Proper battery back must be provided.
- v) Should have minimum 12 configurable LEDs for 132kV and above voltage class.
- vi) Should have minimum **24 Binary Inputs and 32 Binary Outputs**. Moreover, the relays shall have minimum 30% BI & BO as spare after fulfilment of scheme requirement.
- vi) All BI/BOs shall be site configurable
- vii) Shall have front minimum 3 lines LCD display with Alpha numeric keypad.
- viii) Numerical relays are to be provided with built in Event / Disturbance / Fault Recorder features.
- ix) The bidder shall bring out in the bid that the Numerical relays providing different protection features / application in a single unit if any one of the application/ features goes out of service the other feature/application (s) will remain unaffected.
- x) The relays shall be site configurable (Including logic development)
- xi) Configured features & set values shall be in non-volatile memory
- xii) Must have real time clock for time stamping of events/ disturbances with time synchronization inputs (GPRS etc.). Time synchronisation through SNTP compatible.
- xiii) The major component cards shall be hot swappable and front or rear loading.
- xiv) The relays should have self-diagnostic features identifying area of fault or failure of a particular component or card.
- xv) Shall have in built Circuit Breaker Failure protection based on undercurrent detection and/or circuit breaker auxiliary contact status. Provision shall be given to initiate the breaker fail logic using a digital input from external protection devices.
- xvi) Relay shall have inbuilt PRP ports.

- xvii) Relays shall have redundant communication channels for Protection Communication.
- c) Hardware based measurement shall not be acceptable.
- d) The relay should have high immunity to electrical and electromagnetic interference.
- e) The same relay shall be provided with both 1A CT inputs and shall be site selectable.
- f) It shall be possible to energise the relay from either AC or DC auxiliary supply. Auxiliary dc supply shall be suitable for both 110 and 220 Volt and shall be site selectable.
- g) Be capable of performing basic instrumentation functions and displaying various instantaneous parameters like Voltage, current, active power, reactive power, phase sequence etc. in primary values. Additionally, all sequence current and voltage values shall be displayed on-line. Also the direction of power flow shall be displayed.
- h) Extensive disturbance recording facility shall be available for at least up to 10 seconds to capture maximum possible information. Necessary software shall be provided for retrieving and analysing the records.
- i) Facility for developing customised logic schemes inside the relay based on Boolean logic gates and timers should be available. Facility for renaming the menu texts as required by operating staff at site should be provided.
- j) Must have additional feature of local breaker back up protection
 - i) The relay shall have built in Circuit Breaker Supervision Functions.
 - ii) The relay shall be able to detect any discrepancy found between NO & NC contacts of breaker.
 - iii) The relay shall monitor number of breaker trip operations.
 - iv) The relay shall also monitor the breaker operating time.
- k) The relays shall have the following tools for fault diagnostics:
 - i) Fault record (shall be function of IED): – The relay shall have the facility to store fault records with information on cause of trip, date, time, trip values of electrical parameters.
 - ii) Event record (shall be function of IED): – The relay shall have the facility to store time stamped event records with 1ms resolution.
 - iii) Disturbance records (shall be function of IED): – The relay shall have capacity to store disturbance records of at least 10 sec. duration and sampling rate per cycle shall be more than 15.
- l) It shall be possible to preserve stored information in the event of an auxiliary supply failure with the help of a battery backup.
- m) The relay settings shall be provided with password protection.
- n) It shall be possible to change the relay setting from the front panel using the key pads/ Work station of SAS and Laptop.

- o) The relay shall have comprehensive self-diagnostic feature. This feature shall continuously monitor the healthiness of all the hardware and software elements of the relay. Any failure detected shall be annunciated through an output watchdog contact. The fault diagnosis information shall be displayed on the LCD. These records shall also be retrieved from local as well as remote terminal through the communication port.
- p) The Numerical Relays shall be provided with 2 sets of common support software (latest version) compatible with latest version of Windows OS which will allow easy settings of relays in addition to uploading of event, fault, disturbance records, and measurements to Station HMI/ DR Work Station. The relay settings shall also be changed from local or remote using the same software.
- q) In case of line protection and transformer/reactor protection, the features like fault recorder, disturbance recorder and event logging function as available (including if available as optional feature) in these relays shall be supplied and activated **at no extra cost to the owner**.
- r) The manufacturer shall have to provide up-graded support software if any within 10 years span.

14.16 Transmission Line Protection :

14.16.1 Line Differential Protection Relay (If Applicable)

Main I and Main II Line Differential Protection shall be of **different make and model**.

The relay shall have all the features as per Distance protection relay over and above following features

1. It shall be working on phase segregated Current Differential protection principle.
2. It shall have multiple slope characteristic (preferably) to have stability against CT saturation and heavy through faults as well as sensitivity for internal faults.
3. It shall measure Differential as well as restrain current continuously and shall display the same as measurement.
5. It shall communicate to remote end through IEEE C37.94 format.
6. It shall have redundant communication channels for protection communication.
7. It shall communicate analogue as well as digital signals to remote end.
8. It shall have various communication options for remote communication i.e. mono-mode / multi-mode for direct communication / communication through multiplexer.
9. It shall have Line charging current compensation feature for better sensitivity.

10. Distance protection function can be utilized as independent or as back up of Differential protection in case of failure of remote communication. . It shall have a full scheme distance protection scheme to provide independent protection in parallel with the differential scheme in case of a communication channel failure for the differential scheme. The distance protection then provide protection for the entire line including the remote end back up capability either in case of a communications failure or via use of an independent communication channel to provide a fully redundant scheme of protection (that is a second main protection scheme). Eight channels for intertrip and other binary signals are available in the communication between the IEDs. The auto-reclose for single-, two- and/or three phase reclosing includes priority circuits for multi-breaker arrangements. It co-operates with the synchronism check.
11. It shall communicate time coordinated current signals for remote communication to execute Line differential protection algorithm accurately. Time synchronization through GPS shall also be possible.
12. It shall monitor individual communication links continuously and switchover to standby link after preset time in case of failure of one link.
13. It shall supervise individual telegrams.
14. It shall detect reflected telegrams.
15. It shall detect change in communication It shall measure delay time for remote end along with dynamic compensation of the same in differential protection algorithm.
17. It shall also supervise maximum permissible delay time.
18. It shall generate alarm for heavily disturbed communication link. Technical Parameters
 - A. Line Differential Protection setting:
 1. Minimum operating current - 20 to 200% of I_n
 2. Slope (Single/dual) - 10 to 100%
 3. End section (Single/dual) - 20 to 1000% of I_n
 4. Highset operating current - 100 to 5000% of I_n
 5. 2 nd Harmonic blocking - 5 to 100 %
 6. Typical operating time - 25 ms
 7. Operating time for high set - 15 to 20 ms
 8. Charging current comp. – Selectable
 - B. Remote communication:
 9. Analogue signal transfer – Minimum 3 Nos.

10. Binary signal transfer - Minimum 8 Nos
11. Remote Communication module
Dual modules suitable for
 - a) 1300 nm - multi-mode
 - OR
 - b) 1300 / 1550 nm – mono-mode
 (finalized during detailed engineering)
12. Synchronization mode - GPS / Echo (finalized during detailed engineering)
13. Time delay alarm - 5 to 500 ms, step 5 ms (for communication fail)
14. Time delay - 5 to 500 ms, step 5 ms (for switching to redundant channel)
15. Asymmetric delay - - 20 to +20 ms, step 1 ms (When echo mode is used)
16. Max. Transmission delay – 0 to 40 ms, step 1 ms

14.16.2 Distance Protection Relay

- i) The distance protection relay shall be fully numerical using microprocessors and be based on a non-switched scheme.
- ii) The distance protection relay shall have at least three completely independent non switched forward directional zones, one extended zone and a reverse directional zone protection.
- iii) Have non-switched measurement, which implies processing of six possible fault loops (six –loop measurement).
- iv) The protection algorithm shall utilize fault voltages and currents, as well as the superimposed voltages and currents to arrive at a secure trip decision in the shortest possible time with reliability, selectivity and full sensitivity to all types of faults online.
- v) Have polygonal characteristics with independently adjustable reactive and resistive reaches for maximum selectivity and maximum fault resistance coverage. The zones shall have independent settable earth fault compensation factors to cater to adjacent lines with different zero sequence to positive sequence ratios.
- vi) Selection shall be so that the first zone of the relay can be set to about 80% - 85% of the protected line without any risk of non-selective tripping.
- ix) The second and third zone elements shall provide backup protection in the event of the carrier protection or the first zone element failing to clear the fault, zone-2 shall cover full protected section plus 50 % of the next section, zone-3 shall normally cover the two adjacent sections completely. The zones must have independent time settings.
- x) Shall have resetting time of less than 55 milli-seconds (including the resetting time of trip relays)
- xi) All the zones shall have setting such that they can detect the fault online from minimum 0.3 km to 500 km.

- xii) The maximum fault current could be as high as 63kA but the minimum fault current could be as low as 20% of rated current. The starting and measuring relays characteristics should be satisfactory under these extreme varying conditions.
- xiii) The relay shall use the memory voltage for proper directional discrimination at close in 3 phase fault which shall be based on positive sequence voltages. The directional discrimination and phase selection based on negative sequence measurement techniques is not acceptable.
- xiv) Have adequate number of forward zones (minimum three) and a reverse zone. The zone reach setting ranges shall be sufficient to cover line lengths appropriate to each zone. Carrier aided scheme options such as permissive under reach, overreach, & blocking and non-carrier aided schemes of zone 1 extension and Loss of load accelerated tripping schemes shall be available as standard. Weak in feed logic and current reversal guard also shall be provided.
- xv) In case the carrier channel fails, one out of the non-carrier-based schemes cited above should come into operation automatically to ensure high speed and simultaneous opening of breakers at both ends of the line.
- xvi) Shall have suitable number of potential free contacts for Carrier Aided Tripping, Auto Reclosing, CB Failure, Disturbance/Fault recorder and Data Acquisition System.
- xvii) Have a maximum operating time up to trip impulse to circuit breaker (complete protection time including applicable carrier and trip relay time) for SIR 0.01-4: as 40ms at the nearest end and 60ms at the other end of line & for SIR 4-15: as 45ms at the nearest end and 65ms at the other end of line with carrier transmission time taken as 20ms. Isochronic curves shall be provided in support of operating times.
- xviii) Shall have an independent Directional Earth Fault (DEF) protection element to detect highly resistive faults as a built in feature. This element shall have an inverse time/definite time characteristic.
- xix) Has logic to detect loss of single /two-phase voltage input as well as three-phase voltage loss during energisation and normal load conditions. The voltage circuit monitoring logic in addition to blocking the distance protection element, enable an emergency over current element to provide a standby protection to the feeder until the re-appearance of voltage signal.
- xx) The VT fuse failure function shall function properly irrespective of the loading on the line. In other words, the function shall not be inhibited during operation of line under very low load conditions.
- xxi) Have necessary logic to take care of switch-on-to-fault condition. Energisation of transformers at remote line ends and the accompanying inrush current shall not cause any instability to the operation of relay.
- xxii) Have power swing blocking and Out of Step protection feature, with facilities for fast detection of power swing selective blocking of zones settable unblocking criteria for earth faults, phase faults and three phase faults. It shall be on the principle of measurement of the rate of impedance vector change and monitoring of the vector path. It should have the Earth fault detection feature, which shall override power swing blocking and allow the relay to operate for trip as per zone detection. The relay shall be blocked for the set time for the first PS sensed and remain unblocked for the set time for the successive PS.
- xxiii) Be suitable for single pole or three pole tripping. However, relays offered for 132 kV lines provided with mechanically ganged circuit breakers, single pole tripping need not to be provided.
- xxiv) Be suitable for both bus PT or Line PT/ CVT supply.
- xxv) Shall have in built Trip circuit supervision facility to monitor both pre- and post close supervision facilities. An alarm shall be generated.
- xxvi) Shall have in built broken conductor detection by way of level detector or negative sequence measurement.
- xxvii) Shall have df/dt functions.
- xxviii) Shall have multistage under frequency setting options.

- xxix) The sensitivity of the logic shall not be affected during operation under low load.
- xxx) Shall have a fault locator with an accuracy of $\pm 3\%$. The display should be in kilometres and preferably in percentage impedance too. The fault locator should have built in mutual compensation for parallel circuit.
- xxx i) Have mutual zero sequence compensation factor setting. The relay shall have facility to select different group settings to cater for mutual coupling on account of multi circuit line conditions. The minimum no. of group should be four.
- xxxii** Have at least 24 no of programmable BI and 32 no of programmable BO contact to cater for DR/SER carrier aided tripping auto re-closing etc.
- xxxii) The distance relays shall have a built-in auto-reclose function with facilities for single pole / three pole / single and three pole tripping. It shall be possible to trigger the A/R function from an external protection. A voltage check function which can be programmed for deadline charging/dead bus charging / check synchronising shall be included. However, the relay shall support independent A/R scheme.
- xxxiii) Shall have additional features to provide under/ over voltage protection.
- xxxiv) Shall have additional features to provide under frequency protection
- xxxv) Shall have memory circuits with defined characteristics in all three phases to ensure correct operation during close-up 3 phase faults and other adverse conditions and shall operate instantaneously when circuit breaker is closed to zero-volt 3 phase fault.
- xxxvi) The protective relays shall be suitable for use with capacitor voltage transformers having non electronic damping and transient response as per IEC.
- xxxvii) Shall have a continuous current rating of two times of rated current. The voltage circuit shall be capable of operation at 1.2 times rated voltage. The relay shall be also capable of carrying a high short time current of 70 times rated current without damage for a period of 1 sec.
- xxxviii) Must have a current reversal guard feature.
- xxxix) Shall have Stub Protection function with current setting minimum range of 1 to 3 pu with definite time delay setting, minimum range of 0 to 100 msec
- xl) Have feature of load encroachment blinder to safeguard the protection trip during heavy line loading condition.

14.16.3 Integrated Numerical Transformer Protection Relay

a) GENERAL REQUIREMENTS:

- i) Shall be stable during magnetising inrush and over fluxing conditions. Stabilization under inrush conditions shall be based on the presence of second harmonic components in the differential currents.
- ii) Shall have saturation discriminator as an additional safeguard for stability under through fault conditions.
- iii) Shall have zero sequence current filtering, which may be deactivated separately for each winding, for special applications.
- iv) Shall have software to take care of the angle & ratio correction of CT inputs.
- v) Shall have all output relays suitable for both signals and trip duties

b) FUNCTIONAL DESCRIPTIONS:

The integrated Numerical Transformer Protection Scheme shall have following functional qualities:

1) Differential protection:

- i) The relay shall be biased differential protection with triple slope tripping characteristics with faulty phase identification / indication. The range for the differential pick-up shall be from 0.1 to 2.5 p.u. Its operating time shall not exceed 30 ms at 5 times rated current.
- ii) The relay shall have two adjustable bias slopes from 20 % to 150 % and slope from 40% to 150 %, to provide maximum sensitivity for internal faults with high stability for through faults
- iii) The relay shall have an unrestrained high set element to back up the biased differential function and the setting range for it shall have a minimum setting of 5pu and a maximum setting of 30pu.
- iv) The relay shall have the second harmonic restraint feature for stability under transformer inrush condition. The setting shall be 15-25%.
- v) Further, the fifth harmonic blocking for stability under transient over fluxing condition shall be provided.
- vi) Have suitable non-linear resistors along with stabilizing resistor for CT Circuit to limit peak voltage during in-zone faults in case of high impedance type.
- vii) Have a fault recording feature to record graphic form of instantaneous values of following analogue channels during faults and disturbances for the pre fault and post fault period: **Current in all three windings in nine analogue channels plus three analogue channels for Backup protection in case of 400kV class/ 220kV Class (In case of loaded tertiary) or 9 analogue channels for lower voltage transformers and voltage in three channel.**
- viii) The Disturbance recorder function built in the Differential Protection IED shall have the facility to record the following external digital channel signals associated with transformer which shall be wired to differential relay apart from the digital signals pertaining to differential relay:
 - a) REF Protection Operated
 - b) HV Breaker Status (Main & Tie/Transfer both separately)
 - c) IV/LV Breaker status (Main & Tie/Transfer both separately)
 - d) Bucholz/OLTC/OTI/WTI alarm
 - e) Bucholz/ PRD/ SPR Trip
 - f) Group-A/ Group-B lockout relay trip

Necessary hardware and software, for automatic up loading of the data captured by disturbance recorder to the personal computer (DR Work Station) available in the sub station, shall be included in the scope.
- ix) The Relay shall have Reverse Power Protection feature.
- x) The Differential Relay shall be designed for the protection & control of 3 winding Transformer

2) Restricted Earth fault Protection:

The scheme shall have in-built restricted earth Fault (REF) for both the windings. The REF function shall be configurable to Auto Transformer also. This function should be provided to maximise the sensitivity of the protection of earth faults. **Both the Differential relay shall have inherent high impedance REF element.** The REF function should be able to share Current Transformers with the biased differential function. As in traditional REF protection s, the function should respond only to the fundamental frequency component of the currents. For star/star transformer, both the windings shall be protected through REF, as such relay shall have sufficient analogue channels to accommodate the same.

3) Over fluxing Protection:

- i) The over fluxing protection shall be built in the relay. By pairs of V/f and t, it shall be possible to plot the over fluxing characteristics so that accurate adaptation of the power transformer data is ensured.
- ii) In addition, the relay should have a definite time element for alarm.
- iii) The relay should monitor all the three phase voltages for calculation of V/f and should take the highest voltage for V/f calculation.

4) Thermal Overload Protection:

- i) Shall have two stages of thermal overload protection for alarm and trip condition with continuously adjustable setting range of 100-400% of rated current and time constant setting range of 1.0 to 10.00sec continuously.
- ii) Shall be single pole type.
- iii) Shall have a drop off/pick up ratio greater than 95%.
- iv) Shall have separately adjustable time delay relays for alarm having a setting range of 1 to 10 seconds continuously.

5) Over Current and Earth fault protection:

- i) The relay shall have three stages of definite time **Directional** over current protection as backup operating with separate measuring systems for the evaluation of the three phase currents, the negative sequence current and the residual current.
- ii) In addition, the relay shall have three stages of Inverse time **Directional** over current protection operating based on one measuring system each for the three phase currents, the negative sequence current and the residual current.
- iii) Shall have additional features to provide under/ over voltage protection.
- iv) Shall have additional features to provide under frequency protection.
- v) The Earth fault relay shall have directional IDMT characteristic with a definitive minimum time of 3.0 seconds at 10 times setting and have a variable setting range of 20-80% of rated current. (with selectable IEC Curves).
- vi) The Earth fault relay shall have low transient, overreach high set instantaneous unit of continuously variable setting range 200-800 % of rated current.

6) Transformer Neutral Current relay (for 400 KV class transformer only) shall

- i) Have directional IDMT characteristic with a definite minimum time of 3.0 seconds at 10 times setting and have a variable setting range of 20-80% of rated current. (with selectable IEC Curves)

14.16.4 Over Current and Earth Fault Relays

These relays shall be of numeric, single/multi pole, directional /non-directional type with high set element as specified. These relays shall have the following features/characteristics:

- (i) IDMT characteristic with definite minimum time of 3 second at 10 times setting.
- (ii) Other operating curves such as inverse, very inverse shall be selectable
- (iii) Adjustable setting range of 50-200 % and 20-80% of rated current for over current and earth fault relays respectively.

- (iv) The directional relays shall have a Maximum torque angle of 45° current leading for directional over current unit & 30 lag for directional earth fault. Other MTAs should be settable
- (v) Voltage polarizing coil: 63.5 or 110volt
- (vi) Must have faulty phase, type of fault identification
- (vii) The directional relays shall have over voltage/ under voltage & under frequency built in protection
- (viii) The relay shall have blocking scheme on Reverse Power Flow.
- (ix) Include LED indicators.

14.16.5 Reactor Protection

14.16.5.1 REACTOR DIFFERENTIAL PROTECTION RELAY Shall

- (i). Be triple pole type.
- (ii). Have operation time less than 25 milli-seconds at 5 times setting
- (iii). Be tuned to system frequency.
- (iv). Have an operating current sensitivity of at least 10% of nominal current
- (v). Have current setting range of 10 to 40% of 1 Amp. or a suitable voltage setting range
- (vi). Be high impedance / biased differential type.
- (vii). Have suitable non-linear resistors along with stabilizing resistor for CT Circuit to limit peak voltage during in-zone faults in case of high impedance type.
- (viii). Be stable for all external faults.

14.16.5.2 REACTOR RESTRICTED EARTH FAULT PROTECTION RELAY shall

- (i). Be single pole type.
- (ii). Be of current/voltage operated high impedance type.
- (iii). Have a current setting of 05-40% of 1 Amp. / have a suitable voltage setting range
- (iv). Be tuned to system frequency
- (v). Have a suitable non-linear resistor to limit the peak voltage to 1000 Volts.

14.16.5.3 REACTOR BACK UP IMPEDANCE PROTECTION RELAY shall

- (i). Be triple pole type, with faulty phase identification/ indication.
- (ii). Be single step polarized 'mho' distance/ impedance relay suitable for measuring phase to ground and phase to phase faults
- (iii). Have adequate ohmic setting range to cover at least 60% of the impedance of the reactor and shall be continuously variable
- (iv). Have an adjustable characteristic angle of 30-80 degree
- (v). Have a definite time delay relay with a continuously adjustable setting range of 0.2-2.0 seconds
- (vi). Include VT failure relay which shall block the tripping during VT fuse failure condition.
- (vii). Have Back Up over Current and Earth fault protection as built in function.

14.16.6 Circuit Breaker Protection

- a) **LOCAL BREAKER BACK-UP PROTECTION SCHEME** shall
- (i). Be triple pole type.
 - (ii). Have an operating time of less than 15 milli seconds
 - (iii). Have a resetting time of less than 15 milli seconds
 - (iv). Have three over current elements
 - (v). Be arranged to get individual initiation from the corresponding phase of main protections of line for each over current element. However, common three phase initiation is acceptable for other protections and transformer /reactor equipment protections
 - (vi). Have a setting range of 10-80% of rated current
 - (vii). Have a continuous thermal withstand two times rated current irrespective of the setting
 - (viii). Have a timer with continuously adjustable setting range of 0.1-1 seconds
 - (ix). Have necessary auxiliary relays to make a comprehensive Scheme
 - (x). Shall have re-trip feature for tripping its own CB after initiation with a set time delay.
 - (xi). Be acceptable as Built-in protection function of distributed bus bar protection scheme only; however in that case separate LBB relay shall be provided for tie bays.
- b) **NUMERICAL AUTO RECLOSING FUNCTION** (where specified) shall be an in built feature of Main-I and Main-II protection relay. The Auto Reclose shall
- (i). Have single phase and three phase reclosing facilities.
 - (ii). Have a continuously variable single-phase dead time range of 0.1-2 Seconds
 - (iii). Have a continuously variable three phase dead time range of 0.1-2 Seconds
 - (iv). Have a continuously variable reclaim time range of 5-300 seconds
 - (v). Incorporate a four-position selector switch/ from which single phase/three phase/single and three phase auto-reclosure and non-auto reclosure mode can be selected. Alternatively, the mode of auto reclosing can be selected through HMI of the relay or BCU & SAS.
 - (vi). Have facilities for selecting check synchronizing or dead line charging features. It shall be possible at any time to change the required feature by reconnection of links.
 - (vii). Be of single shot type
 - (viii). Have priority circuit to closing of both circuit breakers in case one and half breaker arrangements to allow sequential closing of breakers
 - (ix). Include check synchronizing relay which shall
 - Have a time setting continuously variable between 0.5-5 seconds with a facility of additional 10 seconds
 - Have a response time within 200 milli seconds with the timer disconnected.
 - Have a phase angle setting not exceeding 35 degree
 - Have a voltage difference setting not exceeding 10%
 - Include deadline charging relay, which shall
 - Have two sets of relays and each set shall be able to monitor the three-phase voltage where one set shall be connected to the line CVTs with a fixed setting of 20% of rated voltage and the other set shall be connected to the bus CVTs with a fixed setting of 80% of rated voltage.

- Incorporate necessary auxiliary relays and timers to give comprehensive scheme.

Auto Reclose function shall be an in-built feature of the BCU and the signal exchange for auto-reclose function from BCU to main relays and vice versa shall be achieved through hard wiring and GOOSE parallelly.

14.17 Bus Bar Protection Relay

- a) These relays shall also be of numeric type.
- b) Redundant (1+1) numerical low impedance biased differential Bus Bar protection scheme for each bus system (Bus1 +Bus2) for 400kV shall be provided. The scheme shall be engineered so as to ensure that operation of any one out of two schemes connected to main faulty bus shall result in tripping of the same.
- c) Single bus bar protection scheme shall be provided for each main bus (**Main I/Main II**) and transfer bus (as applicable) for 220KV and **132kV** voltage level.
- d) Each Bus Bar protection scheme shall
 - i) Have maximum operating time up to trip impulse to trip relay for all types of faults of 25 milli seconds at 5 times setting value.
 - ii) Operate selectively for each bus bar
 - iii) Give hundred percent security up to 63 KA for fault level for 400 KV , 50kA for 220 KV and 40 KA for 132 KV
 - iv) Incorporate continuous supervision for CT secondary against any possible open circuit and if it occurs, shall render the relevant zone of protection inoperative and initiate an alarm
 - v) Not give false operation during normal load flow in bus bars
 - vi) Incorporate clear zone indication
- e) It shall have End fault Protection & LBB function
- f). Be of phase segregated and triple pole type. The bus bar scheme may be Centralized or De-Centralized type and it must accommodate all future bays as per Project along with tripping relays.
- g) Provide independent zones of protection (including transfer bus if any). If the bus section is provided, then each side of bus section shall have separate set of bus bar protection schemes
- h) Include individual high speed electrically reset tripping relays for each feeder. However, in case of distributed Bus bar protection, individual trip relay shall not be required if bay unit is having trip duty contacts for breaker tripping.
- i) Be transient free in operation
- j) Include continuous D.C. supplies supervision
- k) Not cause tripping for the differential current below the load current of heaviest loaded feeder. Contractor shall submit application check for the same.
- l) Shall include necessary C.T. switching relays wherever C.T. switching is involved and have 'CT' selection incomplete alarm
- m) Include protection 'IN/OUT' switch for each zone
- n) Shall include trip relays, CT switching relays (if applicable) , auxiliary CTs (if applicable) as well as additional power supply modules, input modules etc. as may be

required to provide a Bus bar protection scheme for the complete bus arrangement i.e. for all the bays or breakers including future bays as per the Single line diagram for new substations. However, for extension of bus bar protection scheme in existing substations, scope shall be limited to the bay or breakers covered under this specification. Suitable panels (if required) to mount these are also included in the scope of the work.

- o) In case of distributed Bus bar Protection, the bay units for future bays may be installed in a separate panel and the same shall be located in switchyard panel room where bus bar protection panel shall be installed.

14.18 Tee Differential Protection Relays (If Applicable)

- 1) **TEE-1 DIFFERENTIAL (BIAS) PROTECTION RELAY** shall
 - (a) be triple pole type
 - (b) have an operating time less than 30 milliseconds at 5 times the rated current
 - (c) have three instantaneous high set over current units
 - (d) have an adjustable bias setting range of 20-50%
 - (e) have an operating current setting of 15% of 1 Amp or less
- 2) **TEE-2 DIFFERENTIAL (HIGH IMPEDANCE) PROTECTION RELAY** shall
 - (a) be triple pole type
 - (b) have operating time less than 25 milliseconds at 5 times setting
 - (c) be tuned to system frequency
 - (d) have current setting range of 20 to 80% of 1 Amp
 - (e) be voltage operated, high impedance type
 - (f) be stable for all external faults
 - (g) be provided with suitable nonlinear resistors across the relay to limit the peak voltage to 1000 volts

14.19 Trip Circuit Supervision Relay

- Trip circuit supervision relay shall be provided for each pole of the breaker for both trip coils with separate DC source.
- The relay shall be capable of monitoring the healthiness of each 'phase' trip-coil and associated circuit of circuit breaker during 'ON' and 'OFF' conditions.
- The relay shall have adequate contacts for providing connection to alarm and event logger.
- The relay shall have time delay on drop-off of not less than 200 milli seconds and be provided with operation indications for each phase.

14.20 Master Trip Relay

- High Speed Tripping Relay shall be instantaneous (operating time not to exceed 10 milli-seconds)
- The relays shall reset within 20 milli seconds
- The relay shall be re-settable/configurable from local SCADA.
- The relays shall be D.C. operated
- The relays shall have adequate contacts to meet the requirement of scheme, other functions like auto-reclose relay, LBB relay as well as cater to associated equipment like event logger, Disturbance recorder, fault Locator, etc.
- The relays shall be provided with operation indicators for each element/coil.

14.21 Other Trip Relays

- For transformer protection other trip relays for Buchholz, winding & oil temperature high, PRD etc. shall be provided as per requirement.
- These High-Speed Tripping Relays shall be instantaneous (operating time not to exceed 10 milli-seconds)
- The relays shall have adequate contacts to meet the requirement of scheme

14.22 DC Supply Supervision Relay

- The relay shall be capable of monitoring the failure of D.C. supply to which, it is connected.
- It shall have adequate potential free contacts to meet the scheme requirement.
- The relay shall have a 'time delay on drop-off' of not less than 100 milli seconds and the relays shall be provided with operation indicator/flag.

14.23 TIME SYNCHRONISATION EQUIPMENT:

- The equipment must be Type tested for Shock, Vibration, Dry heat, Radiated Emission, Electromagnetic field immunity, Electrostatic discharge immunity test in a Standard Laboratory. Type test report shall be submitted along with the bid. Type tests shall be more than five years as on opening of this bid.
- The equipment shall be compliant to IEC 61850 Protocol. It shall also support the network protocols like NTPv4, SNTP, SNMPv1,2,3, SNMP Trap, SSH2, Ipv6, DHCP, HTTP (S), eMail, FTP, TELNET and Syslog
- The Time synchronisation equipment shall receive the coordinated Universal Time (UTC) transmitted through Geo Positioning Satellite System (GPS) and synchronise equipment to the Indian Standard Time in a substation.
- Time synchronisation equipment shall include antenna, all special cables and processing equipment etc.
- It shall be compatible for synchronisation of Event Loggers, Disturbance recorders and SCADA at a substation through individual port or through Ethernet realised through optic fibre bus.
- Equipment shall operate up to the ambient temperature of 50 degree centigrade and 100% humidity.
- The synchronisation equipment shall have 20 nano second accuracy. Equipment shall give real time corresponding to IST (taking into consideration all factors like voltage, & temperature variations, propagation & processing delays etc.) including communication time for satellite link to achieve real time signal.
- Equipment shall meet the requirement of IEC 60255 for storage & operation.
- The system shall be able to track the satellites to ensure no interruption of synchronisation signal.
- The output signal from each port shall be programmable at site for either one hour, half hour, minute or second pulse, as per requirement.
- The equipment offered shall have six (6) output ports. Various combinations of output ports shall be selected by the customer, during detailed engineering, from the following:
 - 1) Voltage signal: Normally 0-5V with 50 milli Seconds minimum pulse duration. In case any other voltage signal required, it shall be decided during detailed engineering.
 - 2) Potential free contact (Minimum pulse duration of 50 milli Seconds.)

- 3) IRIG-B
- 4) RS232C
- 5) RJ 45
- 6) SNTP
- 7) Optical
- 8) IEEE 1588 PTP (Applicable only for process bus automation station)
- The equipment shall have a periodic time correction facility of one-second periodicity.
- Time synchronisation equipment shall be suitable to operate from 80V-250V DC supply available at the sub-station with voltage variation of + 10% and -15%.
- . Equipment shall have real time digital display in hour, minute, second (24-hour mode) & have a separate time display unit to be mounted on the top of control panels/SAS Panels having display size of approx. 100 mm height.
- The cable connecting Antenna and Time Synchronising unit should be run through HDPE pipe or GI pipe from the location of Antenna fixing to Time Synchronising panel with suitable fixtures and no provision to enter rainwater and should not be affected by atmospheric conditions.
- Time Synchronisation software shall be window base and it should be provided free of cost after commissioning.

14.24 BAY CONTROL UNIT (BCU)

- The BCU must be type tested at KEMA/Internationally or nationally accredited other testing laboratories for IEC 61850 and other tests as per relevant IEC standards. The bidder is to submit type test reports along with the bid. The validity of type test report shall be as per Clause 14.4.2(iii).
- The bay unit shall use industrial grade components. The BCU shall be modular type. The bay level unit, based on microprocessor technology, shall use numerical techniques for the calculation and evaluation of externally input analogue signals. These shall incorporate select- before-operate control principles as safety measures for operation via the HMI. These shall perform all bay related functions, such as control commands, bay interlocking, data acquisition, data storage, event recording and shall provide inputs for status indication and outputs for commands. These shall be directly connected to the switchgear. The bay unit shall acquire and process all data for the bay (Equipment status, fault indications, measured values, alarms etc.) and transmit these to the other devices in sub-station automation system. In addition, these shall receive the operation commands from station HMI and SLDC. The bay unit shall have the capability to store all the data for at least 24 hours even if there is any power off conditions during the day. **The BCU shall have Auto Reclose, LBB, U/O voltage and Synchronization function. The BCU shall have redundant power supply card i.e. in case of failure of one source/Card fail, the redundant shall pick up instantly. Power supply card failure shall generate necessary alarm to local SCADA.**
- The BCU must have metering functions like phase current, phase voltages, active & apparent power, power factor, frequency etc. The metering functions shall be accurate for a minimum of 1% of rated current.
- BCU HMI shall display complete mimic of the respective bay, and operator shall be able to select the equipment in the mimic diagram for which operation of equipment is required. The control operation shall be password protected. For 33kV, the HMI should display one bay and control thereof.
- The mimic diagram shall indicate the live & dead portion of the Bay.

- The BCU shall be capable to generate password for maintenance shutdown.
- One Bay level unit shall be provided for supervision and control of each 400KV, 220KV, 132kV and 33kV bay (a bay comprises of one circuit breaker and associated disconnectors, earth switches and instrument transformer). If the 33kV bus section comprises isolator only, then the isolator shall be controlled from the transformer LV side bay and same is the case for Bus PT Isolator which shall be controlled by Transformer LV side BCU. The Bay level unit shall be equipped with analogue and binary inputs/outputs for handling the control, status monitoring and analogue measurement functions. All bay level interlocks are to be incorporated in the Bay level unit so as to permit control from the Bay level unit/ local bay mimic panel, with all bay interlocks in place, during maintenance and commissioning or in case of contingencies when the Station HMI is out of service.
- The BCU shall have sufficient number of BI/BO as per the scheme requirement with additional 30% spare BI/BO.
- The Bay level units shall be installed in the control and relay panels located in the control room.
- The Bay level unit shall meet the requirements for withstanding electromagnetic interference according to relevant parts of IEC 61850. Failure of any single component within the equipment shall neither cause unwanted operation nor lead to a complete system breakdown.
- **Input / Output (I/O) modules**

The I/O modules shall form a part of the bay level unit and shall provide coupling to the substation equipment. The I/O modules shall acquire all switchgear information (i.e. data coming directly from the switchgear or from switchgear interlocking devices) and transmit commands for operation of the switchgear.

The measured values of SF6 Gas Pressures, Operating Mechanism Pressures, WTIs, OTI etc. are received through transducers to Bay Level Unit

The digital inputs shall be acquired by exception with 1 ms resolution. Contact bouncing in digital inputs shall not be assumed as change of state.

- **Operator Interface**

The HMI of BCU shall display the following informations

- i) the bay name
- ii) the date and time
- iii) the Local / Remote/Maintenance bay mode
- iv) the auto-recloser function status (on / off),
- v) the synchrocheck function status (on / off),
- vi) the interlock function status (on / off),
- vii) a list of measurements (in real value)
- viii) the bay graphical representation
- ix) the bay events classified in a chronological order
- x) the bay alarms
- xi) the list of disturbance records available
- xii) Bay interlock diagram

In addition, it shall be possible to plug a PC laptop on the Bay and get the full substation operator interface.

14.25 SWITCHED ETHERNET COMMUNICATION INFRASTRUCTURE:

The bidder shall provide the redundant managed switched optical Ethernet communication infrastructure for SAS against PRP architecture. The necessary switches are provided for communication infrastructure as follows.

14.25.1 One switch shall be provided to connect all IEDs for 1 Bay in LAN –I and the second optical port of Bay IEDs shall be connected to other Ethernet Switch in LAN-2. The maximum number of bays may be connected to these Ethernet Switch shall be two bays for 400KV, 220kV and 132kV. However, for 33kV, 3 numbers bay may be connected to one Ethernet Switch in this PRP architecture. The exact no of Ethernet switches required for complete implementation of the scheme shall decided during detailed engineering.

14.25.2 The managed Ethernet switch shall have minimum 20% port redundancy (Both Fibre & Copper ports).

14.25.3 Ethernet Switches shall have redundant power card.

14.25.4 Port monitoring softwares for Ethernet Switches are to be provided.

14.25.5 The make of the Ethernet switches shall be Ruggedcom/Hirschman/ABB.

14.26 FAULT RECORDER:

14.26.1 The fault recorder shall be provided for transmission line and the fault recorder as in-built feature of line distance relay is also acceptable provided the requirements of following clauses are met.

14.26.2 Fault recorder shall be capable to record the graphic form of instantaneous values of voltage and current in all three phases, open delta voltage & neutral current, open or closed position of relay contacts and breakers during the system disturbances.

14.26.3 The Fault recorder shall consist of individual acquisition units, one for each feeder and an Evaluation unit (as described in section sub-station automation through bus conforming to IEC 61850) which is common for the entire Substation. Necessary hardware and software shall also be supplied for online transfer of data from all acquisition units to Evaluation unit.

14.26.4 Fault recorder shall have at least 8 analogue and 16 digital channels for each feeder.

14.26.5 Acquisition units shall acquire the Disturbance data for the pre fault and post fault period and transfer them to Evaluation unit automatically to store in the hard disk. The acquisition units shall be located in the protection panels of the respective feeders.

14.26.6 The acquisition unit shall be suitable for inputs from current transformers with 1A rated secondary and capacitive voltage transformers with 63.5V (phase to neutral voltage) rated secondary. Any device required for processing of input signals in order to make the signals compatible to the Fault recorder equipment shall form an integral part of it. However, such processing of input signals shall in no way distort its waveform.

14.26.7 The equipment shall be carefully screened, shielded, earthed and protected as may be required for its safe functioning. Also, the Fault recorder shall have stable software, reliable hardware, simplicity of maintenance and immunity from the effects of the hostile environment of EHV switchyard which are prone to various interference signals typically from large switching transients.

- 14.26.8 The evaluation unit hardware shall be as described in clause no. 4.0 of section sub-station automation.
- 14.26.9 Necessary software for transferring the data automatically from local evaluation unit to a remote station and receiving the same at the remote station through owner's PLCC/VSAT/LEASED LINE shall be provided.
- 14.26.10 Evaluation software shall be provided for the analysis and evaluation of the recorded data made available in the PC under WINDOWS environment. The Software features shall include repositioning of analog and digital signals, selection and amplification of time and amplitude scales of each analogue and digital channel, calculation of MAX/MIN frequency, phase difference values, recording of MAX/MIN values etc. of analogue channel, group of signal to be drawn on the same axis etc, listing and numbering of all analogue and digital channels and current, voltage, frequency and phase difference values at the time of fault/tripping. Also, the software should be capable of carrying out Fourier /Harmonic analysis of the current and voltage wave forms. The Disturbance records shall also be available in COMTRADE format (IEEE standard- Common Format for Transient data Exchange for Power System)
- 14.26.11 The Evaluation unit shall be connected to the printer to obtain the graphic form of disturbances whenever desired by the operator.
- 14.26.12 Fault recorder acquisition units shall be suitable to operate from 220V DC as available at sub-station Evaluation unit along with the printer shall normally be connected to 230V, single phase AC supply. In case of failure of AC supply, Evaluation unit and printer shall be switched automatically to the station DC through Inverter of adequate capacity which shall form a part of Distance recorder system. The inverter of adequate capacity shall be provided to cater the requirement specified in section sub-station automation clause no. 8.0 and DR evaluation unit.
- 14.26.13 The acquisition unit shall have the following features:
- i) Facility shall exist to alarm operator in case of any internal faults in the acquisition units such as power supply fail, processor / memory fail etc. and same shall be wired to annunciation system.
 - ii) The frequency response shall be 5 Hz on lower side and 250 Hz or better on upper side.
 - iii) Scan rate shall be 1000 Hz/channel or better.
 - iv) Pre-fault time shall not be less than 100 milliseconds and the post fault time shall not be less than 2 seconds (adjustable). If another system fault occurs during one post-fault run time, the recorder shall also be able to record the same. However, the total memory of acquisition unit shall not be less than 5.0 seconds.
 - v) The open delta voltage and neutral current shall be derived either through software or externally by providing necessary auxiliary transformers.
 - vi) The acquisition unit shall be typically used to record the following digital channels:
 - 1. Main CB R phase open
 - 2. Main CB Y phase open
 - 3. Main CB B phase open
 - 4. Main-1 carrier received
 - 5. Main-1 protection operated
 - 6. Main/Tie /TBC Auto reclosed operated
 - 7. Over Voltage -Stage-1 /2 operated
 - 8. Reactor / Stub/TEE-1/2/UF protection operated
 - 9. Direct Trip received
 - 10. Main-2 carrier received

11. Main- 2/ Back Up protection operated
12. Bus bar protections operated
13. LBB operated of main /tie/TBC circuit breaker
14. Tie/TBC CB R phase open
15. Tie/TBC CB Y phase open
16. Tie/TBC CB B phase open

- vii) In case the Fault recorder is in-built part of line distance protection, above digital channels may be interfaced either externally or internally.
- viii) Any digital signal can be programmed to act as trigger for the acquisition unit. Analogue channels should have programmable threshold levels for triggers and selection for over or under levels should be possible.
- 14.26.14 The printer shall be compatible with the desktop PC and shall use Plain paper. The printout shall contain the Feeder identity, Date and time (in hour, minute and second up to 100th of a second), identity of trigger source and Graphic form of analogue and digital signals of all the channels. Two packets of paper (500 sheets in each packet) suitable for printer shall be supplied.
- 14.26.15 Each Fault recorder shall have its own time generator and the clock of the time generator shall be such that the drift is limited to +0.5 seconds/day, if allowed to run without synchronization. Further, Fault recorder shall have facility to synchronize its time generator from Time Synchronization Equipment having output of following types.
- i) Voltage signal: (0-5V continuously settable, with 50m Sec. minimum pulse duration).
 - ii) Potential free contact (Minimum pulse duration of 50 m Sec.)
 - iii) IRIG-B/SNTP
 - iv) **RS232C/RS485/RJ 45/Optical port.**

The recorder shall give annunciation in case of absence of synchronizing within a specified time.

14.27 DISTANCE TO FAULT LOCATOR:

- 14.27.1 The Distance to Fault Locator shall be provided for transmission line and the fault locator as in-built feature of line distance relay is also acceptable provided the requirements of following clauses are met.
- 14.27.2 Distance to Fault Locator shall be electronic or microprocessor based and 'Online' type with built-in display unit.
- 14.27.3 The display shall be directly in percent of line length or kilometers without requiring any further calculations.
- 14.27.4 It shall have an accuracy of 3% or better for the typical conditions defined for operating timings measurement of distance relays. The accuracy should not be impaired under the following conditions:
- i) presence of remote end in-feed
 - ii) predominant D.C. component in fault current
 - iii) high fault arc resistance
 - iv) severe CVT transients
- 14.27.5 It shall have mutual zero sequence compensation unit if fault locator is to be used on double circuit transmission line.

14.28 PROTECTION SCHEME FOR PANELS:

- **400KV Line Panel**

The following protections scheme shall be provided for Panels for 400 KV Transmission lines:

Main Protection Scheme I & II:

Distance protection scheme using Numerical Relay as specified in detail in Clause 14.15 and 14.16.2 shall be implemented. The summary of the scheme detailed in the above clauses have the following feature:

- (i) Permissive under reach/over reach/ blocking communication mode.
- (ii) Suitable for single cum three phase tripping.
- (iii) Power swing blocking and out of step protection.
- (iv) Single shot single-cum-three phase auto re-closing with check synchronising and deadline charging features.
- (v) Fuse failure protection.
- (vi) Weak end in feed feature.
- (vii) Over/Under Voltage Protection
- (viii) Directional Over current and Earth Fault protection
- (ix) Current reversal guard feature
- (x) Stub protection function
- (xi) Load encroachment blinder feature.
- (xii) Switch on to fault feature.
- (xiii) In built Broken Conductor detection feature.
- (xiv) Shall have df/dt functions
- (xv) Under frequency protection
- (xvi) Carrier Aided Tripping
- (xvii) Main 1 and Main 2 relay shall of different make **and model**.

- **220 KV Line Panel**

The following protections scheme shall be provided for Panels for 220 KV Transmission lines:

a) Main Protection Scheme I & II:

Distance protection scheme using Numerical Relay as specified in detail in Clause 14.15 and 14.16.2 shall be implemented. The summary of the scheme detailed in the above clauses have the following feature:

- (i) Permissive under reach/over reach/ blocking communication mode.
- (ii) Suitable for single cum three phase tripping.
- (iii) Power swing blocking and out of step protection.
- (iv) Single shot single-cum-three phase auto re-closing with check synchronising and deadline charging features.
- (v) Fuse failure protection.
- (vi) Weak end in feed feature.

- (vii) Over/Under Voltage Protection
- (viii) Directional Over current and Earth Fault protection
- (ix) Current reversal guard feature
- (x) Stub protection function
- (xi) Load encroachment blinder feature.
- (xii) Switch on to fault feature.
- (xiii) In built Broken Conductor detection feature.
- (xiv) Shall have df/dt functions
- (xv) Under frequency protection
- (xvi) Main 1 and Main 2 relay shall of different **make and model**.

- **132 KV Line Panel**

The following protections scheme shall be provided for Panels for 132 kV Transmission lines:

- a) Main Protection Scheme I:

Distance protection scheme using Numerical Relay as specified in Clause 14.15 and 14.16.2.

- b) Backup Protection:

The backup protection shall be provided with directional single/ multi pole relays as specified in Clause 14.16.4. One triple pole over current relays for phase faults and one Earth Fault Relay for Earth Faults without high set elements shall be provided.

- **33KV Feeder Protection Panel**

The 33kV Feeder Panels shall be provided non directional single/ multi pole relays as specified in Clause 14.16.4. One triple pole over current relays for phase faults and one Earth Fault Relay for Earth Faults with high set elements shall be provided.

- **Power and Auto Transformer Protection Panel**

Integrated Transformer protection scheme as detailed in Clause 14.16.3 of the BID shall be provided for Panels for all Power and Auto Transformers:

- (a) Main Protection -1

Biased transformer differential protection employing relay type specified in Clause 14.32. The scheme shall include also following:

- (i) Second and fifth harmonic restraint feature.
- (ii) The relay shall also provide Restricted Earth Fault Protection
- (iii) The scheme shall have suitable input and output for transformer auxiliary protection like Buchholz, oil temperature, winding temperature etc.
- (iv) Over-fluxing protection
- (v) The relay shall have Back up protection features i.e Directional over current and earth fault with high set element. The high set unit should not operate due to transformer in-rush current.

- (b) Main Protection - 2

Protection function shall be same as Main Protection – I.

(c) Backup Protection: The backup protection shall be provided with Directional relays as specified in Clause 14.16.3. One triple pole over current relays for phase faults and one Earth Fault Relay for Earth Faults with high set elements shall be provided. The high set unit should not operate due to transformer in-rush current.

- **Bus Bar Differential Protection Panel:**
- The Bus Bar Protection shall be provided as detailed in Clause 14.17 of the BID for 400kV, 220kV and 132kV Voltage Level.
- **Reactor Protection Panel:**
The Reactor Protection shall be provided as detailed in Clause 14.16.5 of the BID.

14.29 RELAY MAINTENANCE TOOL KIT

MAINTENANCE TOOL KIT

- The bidder shall supply a complete maintenance tool kit set. The tool kit shall have generally current jack, card extender, card puller, required crimping tool, screw drivers, pliers etc.
- The tool kit shall contain test plugs, test leads, clips for maintenance and testing of relays supplied. Further detailing will be done during detail engineering.
- The Maintenance Tool Kit shall be of Universal type.

14.30 TESTS

- The supplier shall carryout all tests as per relevant standards as all associated equipment including relays, meters, instruments etc. The supplier shall submit all that reports to Employer for approval before despatching the control and relay panels. The Bidder shall also submit along with the bid type test reports for relays instruments, meters and other devices of the type and class being offered. Bidder has to submit KEMA test certificate for Numeric relay on interoperability compliance of IEC 61850 in general and GOOSE messaging and publishing in particular along with the bid.
- Control and relay panels shall be subjected to the following tests:
 - a. Mechanical operation test.
 - b. Verification of degree of protection.
 - c. High voltage test (2000 volts for 1 minute)
 - d. Electrical control interlock and sequential operation test.
 - e. Verification of wiring as per approved schematic.
 - f. Interoperability test as per IEC 61850 (interoperability with ABB, AREVA, SIEMENS, GE and SEL)

14.31 PRE-COMMISSIONING TESTS

- The contractor shall have to perform following minimum Pre-commissioning tests for commissioning of the C&R panels. For this purpose, the contractor shall arrange all required tools and testing equipment at site

- (i). IR values of all circuits
- (ii). Measurement of burden in CT & PT circuits
- (iii). Primary current injection of CT circuits with connected burden
- (iv). Energisation of PTs at suitable low voltage and measurement of PT inputs at all measuring points
- (v). Secondary ac current injection of relays, dynamic testing of all numeric relays. Tracing of zone curves, limits. Checking of relay timings, inherent or set values. For this testing, the contractor shall bring 'Omicron' or equivalent test kit.
- (vi). Testing of voltage related elements like directional element, over fluxing, over/ under frequency, over/ under voltage features, tracing of curves and checking limits of set values and associated timings
- (vii). Checking of Boolean logic gates, BI/BO points of the numeric relays, checking conformity to specification and checking of set logics
- (viii). Checking of stability and sensitivity of differential zones by suitably applying 3-phase low voltages and shorting of primary circuits. Measurements of voltage and current inputs to all relays.
- (ix). Checking stability & sensitivity of bus differential relay zones by suitably injecting current
- (x). Primary injection of REF connected CTs, measurements of relay inputs and checking of stability and sensitivity of REF scheme
- (xi). Checking registration of event and disturbance records in the numeric relays and downloading
- (xii). Testing of carrier aided protection schemes and simulation with regard to transmission and receipt of protection signalling
- (xiii). Testing of AR schemes
- (xiv). Checking of healthiness of each dc circuit of panels
- (xv). Simulation of faults like Buchholz, OTI, WTI and other relays and checking of tripping of breaker and connected annunciation
- (xvi). Operation of master trip relays, tripping of breaker through each trip coil and checking of interlocks
- (xvii). Simulation of faults like low gas, air pressure and checking operation of interlocks. Checking anti pumping scheme of CB
- (xviii). Simulation to Check Checking of PT selection schemes
- (xix). Simulation to Check interlocks of all CB and isolator interlocks
- (xx). Simulation to Check annunciation of all events in BCU (Bay control unit) as well as SAS (Sub-station Automation System)
- (xxi). Simulation to Check of logic of BCU
- (xxii). Operation of tap changing of transformer through SAS
- (xxiii) The pre-commissioning checklist will be further developed by the contractor and will seek approval prior to commencement of pre-commissioning tests from the DGM, MRT Circle, AEGCL. The tests will be witnessed and approved by him or by his authorized officers.

14.32 TECHNICAL DATA SHEET FOR THE RELAY AND CONTROL PANELS

- Features to be provided in various Relay and Control panels are indicated below. Description below are only indicative; the Contractor shall ensure that all items are included in their offer to complete the schemes described in the Specification whether such items are specifically mentioned or not.

400kV and 220kV Feeder Panels:

SL NO	ITEM	RATINGS AND PARTICULARS	
		400KV Panel with 1 1/2 Breaker Scheme	220KV Panel with Main I & Main II
I	II	III	IV
A	LINE PANELS		
1	Protection and relays:		
	(a) Distance Protection Scheme I	1 No.	1 No.
	(b) Distance Protection Scheme II	1 no	1 no
	(c) LBB Protection Scheme.	Can be function of BCU/IEDs	Can be function of BCU/IEDs
	(d) Trip Circuit Supervision Relay for pre and post-closing	Supervision for 6 trip coils (2 trip coils per pole or phase)	Supervision for 6 trip coils (2 trip coils per pole or phase)
	(e) DC Supply healthy monitoring scheme for two separate DC source	2 No.	2 No.
	(e 1) DC Changeover Relay	2 Nos	2 Nos
	(f) AC Supply healthy monitoring scheme	1 No.	1 No.
	(g) High Speed Trip relay (1 & 3 pole)	2 sets.(each set will comprise of 3 Nos of 1ph trip relay and 1 No of 3ph trip relay)	2 sets.(each set will comprise of 3 Nos of 1ph trip relay and 1 No of 3ph trip relay)
	(h) PT-CVT Selection Scheme with PT1-PT2 –CVT selection relay	1 Set. Complete Bus PT1-Bus PT2- CVT Selection Scheme	1 Set. Complete Bus PT1-Bus PT2-CVT Selection Scheme
	(i) Auxiliary relay, timer relay for healthiness of relays, auto reclose communication link etc.	As required (Can be function of BCU)	As required (Can be function of BCU)
	(j) Trip Transfer Relay	-	2 sets
	(j) Fault Recorder	1 set (shall be function of IED)	1 set (shall be function of IED)
	(k) Distance to fault locator	1 set (shall be function of IED)	1 set (shall be function of IED)
	(l) Under Voltage protection relay for isolator/earth switch Interlock	2 nos	2 nos
	(m) Over Voltage Protection Scheme	1 set (maybe function of IED)	1 Set (maybe function of IED)
2	Meters		
	(a) ABT tri-vector Meter (SAMAST Compliant) with TTB	1No	1No

3	Controls/ Status indication/ Annunciation		
	Bay control unit (IED)	1No. (Function of BCU/ SAS)	1No. (Function of BCU/ SAS)

132kV and 33kV feeder Panels:

SL NO	ITEM	RATINGS AND PARTICULARS	
		132 kV Panel with Main & Transfer Bus Scheme	33 kV feeder panel with single bus system
		V	VI
A	LINE PANELS		
1	Protection and relays:		
	(a) Distance Protection Scheme	1 No.	-.
	(b) Back up directional over current and earth fault scheme	1 Set	-
	(c) Back up non directional over current and earth fault scheme	-	1 set
	(d) LBB Protection Scheme.	Can be function of BCU/IEDs	Can be function of BCU/IEDs
	(e) Trip Circuit Supervision Relay for pre and post-closing	Supervision for 2 trip coils	Supervision for 2 trip coils
	(f) DC Supply healthy monitoring scheme, for two DC source	2 No.	2 No.
	(f 1) DC Changeover	2 Nos	2 Nos
	(g) AC Supply healthy monitoring Scheme	1 No.	1 No.
	(h) High Speed Trip relay	2 No.	2 No.
	(h1) High Speed Trip Relay for LBB	1 No	1 No
	(i) Auxiliary relay, timer relay for healthiness of relays, auto reclose communication link etc.	As required (Can be function of BCU)	As required (Can be function of BCU)
	(j) Trip Transfer Relay	2 sets	2 sets
	(j) Line CVT-Bus PT selection relay	1 No	-
	(k) 33kV Incomer PT selection	-	-
	(l) Distance to Fault Locator	1 set (shall be function of IED)	-
	(m) Fault Recorder	1 set (shall be function of IED)	
	(l) Under Voltage protection relay	2 nos (function of IED)	

	for isolator/earth switch Interlock		
	(m) Over Voltage Protection Scheme	1 set (maybe function of IED)	
2	Meters		
	(a) ABT tri-vector Meter (SAMAST Compliant) with TTB	1 No	1 No
3	Controls/ Status indication/ Annunciation		
	Bay Control Unit (IED with HMI)	1No. (Function of BCU/ SAS)	1No.

Transformer Protection Panels

SL NO	ITEM	RATINGS AND PARTICULARS			
		400/220/33 kV Transformer Panel	220/132 kV Transformer Panel	220/33 kV Transformer Panel	132/33kV Transformer Panel
		VII	VIII	IX	X
B	TRANSFORMER PANELS				
1	Protection and Relays:				
	(a) Differential Protection Scheme	2 No.	2 No.	2 No.	2 No.
	(b) Restricted Earth Fault Protection Scheme	(inherent High imp REF)	(inherent High imp REF)	(inherent High imp REF)	(inherent High imp REF)
	(c) Back up directional over current scheme and earth fault scheme for HV side.	Could be feature of relay	Could be feature of relay	Could be feature of relay	Could be feature of relay
	(d) Back up directional over current and earth fault scheme for MV/LV Side.	Could be feature of relay	Could be feature of relay	Could be feature of relay	Could be feature of relay
	(e) LBB Protection Scheme.	Can be function of BCU/IEDs	Can be function of BCU/IEDs	Can be function of BCU/IEDs	Can be function of BCU/IEDs
	(f) Over Fluxing Protection scheme	Can be function of IED	Can be function of IED	Can be function of IED	Can be function of IED
	(g) Overload protection scheme	Can be function of IED	Can be function of IED	Can be function of IED	Can be function of IED
	(g.1) Tertiary Side O/C and Open Delta Voltage Protection	1 set	1 set	-	-
	(h) Trip Circuit Supervision Relay Scheme for ascertaining pre and post-closing healthiness.	Supervision for 4/12 trip coils(2trip	Supervision for 4/8 trip coils(2 tripcoils per	Supervision for 4/8 trip coils(2 tripcoils per	Supervision for 4 trip coils(2 tripcoils per breaker on

		coils per pole/ breaker on each side)	pole/ breaker on each side)	pole/ breaker on each side)	each side)
	(i) DC Supply healthy monitoring scheme	2 No.	2 No..	2 No.	2 No.
	(i1) DC Changeover Relay	2 No.	2 No.	2 No.	2 No.
	(j) AC Supply healthy monitoring scheme	1 No.	1 No.	1 No.	1 No.
	(k) High Speed Trip relay (HV Side)	2 No.	2 No.	2 No.	2 No.
	(l) High Speed Trip relay (MV/LV Side)	2 No.	2 No.	2 No.	2 No.
	(m) Trip Transfer Relay	2 sets	2 sets	2 sets	2 sets
	(m) PT Selection Scheme on HV / MV/LV Side as applicable	1No. Complete Bus PT Selection Scheme (Can be function of BCU)	1No. Complete Bus PT Selection Scheme (Can be function of BCU)	1No. Complete Bus PT selection scheme (can be function of BCU)	1No. Complete Bus PT selection scheme (can be function of BCU)
	(m1) PT Selection Relay	3 Nos for HV/ 2 Nos for LV	2 Nos for HV/ 2 No for MV	2 Nos for HV/ 2 No for LV	1 No for HV/ 2 No for LV
	(n) Tripping relay for Bucholtz, PRD, WTI, OTI , OSR etc.	As required	As required	As required	As required
	(o) Alarm auxiliary for Bucholtz, PRD, WTI, OTI, MOG , Air Cell leakage etc.	As required (Can be a function of BCU)	As required (Can be a function of BCU)	As required (Can be a function of BCU)	As required (Can be a function of BCU)
	(p) Transformer tap position status/ raise & lower	Can be a function of BCU	Can be a function of BCU	Can be a function of BCU	Can be a function of BCU
	(q) Reverse Power Protection	Can be function of IED	Can be function of IED	Can be function of IED	Can be function of IED
2	Meters				
	(a) ABT tri-vector Meter (SAMAST Compliant) With TTB	2 No. (on 400kV and 220 kV side)	2No. (on 220 kV and 132 kV side)	2No. (on 220 kV and 33kV side)	2 Nos. (132 kV & 33 kV side)
3	Controls / interlocks / Status indication/ Annunciation				
	Bay Control Unit (IED), one no each for HV & LV side.	2 Nos. (Function of BCU/ SAS)	2 Nos. (Function of BCU/ SAS)	2 Nos. (Function of BCU/ SAS)	2 Nos. (Function of BCU/ SAS)

Reactor Protection Panel

The Reactor Protection Panel shall consist of following protection features/schemes:

SL. NO	Description	400 kV
		XI
1	Reactor Differential Protection scheme	1 No
2	Restricted Earth fault Protection scheme:	1 No
3	Reactor back up impedance protection scheme	1 Set
4	Three phase trip relays (Only for Bus Reactor)	2 Nos.
5	CVT selection relay as per scheme requirement	Lot

400kV, 220 kV and 132 kV Bus Coupler / Bypass Breaker Panel

SL NO	ITEM	RATINGS AND PARTICULARS	
		220 kV Panel with Main I & Main II Scheme	132 kV Panel with Main 1 & Transfer Bus Scheme
		XII	XIII
A	BUS COUPLER PANEL		
1	Protection and relays:		
	(a) Back up directional over current and earth fault scheme	1 Set	1 Set
	(b) Bus Bar differential protection	Main I and Main II	Applicable, where specified in BoQ
	(c) LBB Protection Scheme.	Can be function of BCU/IEDs	Can be function of BCU/IEDs
	(d) Trip Circuit Supervision Relay for pre and post-closing	Supervision for 6 trip coils (2 trip coil for each Phase)	Supervision for 2 trip coils
	(e) DC Supply healthy	2 No.	2 No.

	monitoring scheme		
	(e)DC Changeover Relay	2 No.	2 No.
	(f)AC Supply healthy monitoring scheme	1 No.	1 No.
	(g) High Speed Trip relay	2 Sets. .(each set will comprise of 3 Nos of 1ph trip relay and 1 No of 3ph trip relay)	2 No.
	(h) PT Selection Scheme	1No. Complete Bus PT Selection Scheme (Can be function of BCU)	Not applicable
	(i) Auxiliary relay, timer relay scheme	As required	As required
2	Metering	Function of BCU/ SAS	Function of BCU/ SAS
3	Controls/Annunciation/Status indication		
	Bay control unit (IED)	1 No. (Function of BCU/ SAS)	1 No. (Function of BCU/ SAS)

400kV Tie Breaker Panel

SL NO	ITEM	Ratings and Particulars	
		4000 kV Panel with 1 ^{1/2} Breaker Scheme	
		XIV	
B	TIE PANEL		
1	Protection and relays:		
	(a) Back up directional over current and earth fault scheme		
	(b) Bus Bar differential protection		
	(c) LBB Relay.	1 No	
	(d) Trip Circuit Supervision Relay for pre and post-closing	Supervision for 6 trip coils (2 trip coils per pole or phase)	
	(e)DC Supply healthy monitoring scheme	2 No.	
	(f) DC Changeover Relay	2 No	
	(f)AC Supply healthy monitoring scheme	1 No.	
	(g) High Speed Trip relay	2Sets. (each set will comprise of 3 Nos of 1ph trip relay and 1 No of 3ph trip relay)	

	(h) Auxiliary relay, timer relay scheme	As required
2	Metering	Function of BCU/ SAS
3	Controls/Annunciation/Status indication	
	Bay control unit (IED)	1 No.

14.33 Monitoring, Control & Protection for Auxiliary Transformer

Suitable monitoring, control (operation of associated Circuit breaker and isolator) and protection for LT Auxiliary Transformer, connected to tertiary winding of auto transformer for the purpose of auxiliary supply shall be provided by the contractor. Overcurrent and open delta protection is required to be provided for the auxiliary transformer. These control and protection shall also be acceptable as built in feature either in the bay controller to be provided for the auxiliary system or in the control and protection IEDs to be provided for the auto transformer.

NOTE: 1) The relays (main / auxiliary) not covered within the above table shall be considered for complete commissioning of the protection scheme.

2) In Case of incomplete Diameter (D and I type layouts), control panel shall be equipped fully as if the Diameter is complete, unless otherwise specified. Annunciation relays shall also be provided for the same and if required, necessary panel shall be supplied to accommodate the same.

3) Relay setting template (in editable document format) shall be provided by the Contractor for each typical protection IEDs for relay setting purpose.

4) For GIS Sub Stations, GIS Gas Zone trip signals, if provided, for each gas tight compartments (gas zone) in the GIS LCC shall be integrated in the protection schematics to provide electrical isolation of faulty Gas Zone by tripping/ inter tripping its adjacent circuit breakers. The scheme shall be implemented through protection IEDs and auxiliary relay as required.

CHAPTER 15: SUB STATION AUTOMATION SYSTEM

15.1 GENERAL

The substation automation system shall be offered from a manufacturer who must have designed, manufactured, tested, installed and commissioned substation automation system ***which must be in satisfactory operation for at least 3 (three) years as on the date of bid opening.*** KEMA/ Internationally and nationally accredited certificate for all IEDs and Ethernet switches conforming to IEC 61850 is to be furnished as qualification requirement.

Standards

Environment Standards

All these standards are applicable to elements like HMI, Ethernet network and elements, Gateways, IEDs.

Type Test Name	Type Test Standard	Conditions
Insulation Resistance	IEC 60255-5	100 MΩ at 500 Vdc (CM & DM)
Dielectric Withstand	IEC60255-5 IEEE C37.90	50 Hz, 1mn, 2kV (CM), 1kV (DM)
		50 Hz, 1mn, 1kV (CM)
		G 1.4 & 1.5 500V CM G 6 :1,5 kV CM
High Voltage Impulse Test	IEC 60255-5	5kV (CM), 3kV (DM)
		2kV (CM)
		Groups 1 to 6 :5 kV CM & 3 kV DM(1)
		Not on 1.4 & 1.5 : 5 kV CM & 3 kV DM(1)
Free Fall Test Free Fall Packaging Test	IEC 60068-2-31 IEC 60068-2-32	Test Ec : 2 falls from 5cm Test Ed : 2 falls from 0,5m
		2 falls of 5 cm (Computer not powered)
		25 falls of 50 cm (1) (2) (Packaging computer)
Vibration Response – Powered On	IEC 60255-21-1	Class 2 : 1g from 2 to 150Hz
		Classe 2 : Acceleration : 1g from 10 (1) to 150Hz
Vibration Response – Not Powered On	IEC 60255-21-1	Class 2 : 2g from 2 to 500Hz
		Classe 2 : Acceleration : 2g from 10 (1) to 500Hz
Vibration Endurance – Not Powered On	IEC 80068-2-6	Class 2 : 1g from 10 to 150Hz
		Class 2 : Acceleration : 1g from 10 (1) to 500Hz

Shocks – Not Powered On	IEC 60255-21-2	Class 1 : 15g, 11 ms
Shocks – Powered On	IEC 60255-21-2	Class 2 : 10g, 11 ms
Bump Test – Not Powered On	IEC 60255-21-2	Class 1 : 10g, 16ms, 2000/axis
Seismic Test – Powered On	IEC 60255-21-3	Class 1 : Axis H : 3,5mm – 2g Axis V : 3,5mm – 1g
		Classe 2 : Acceleration : 2g Displacement : 7,5mm selon axe H Acceleration : 1g Displacement : 3,5mm selon axe V
Damp Heat Test - Operating	IEC 60068-2-3	Test Ca : +40°C / 10 days / 93% RH
Cold Test - Operating	IEC 60068-2-1	Test Ab : -10°C / 96h
		Test Ab : - 25°C / 96 H
Cold Test - Storage	IEC60068-2-1	Test Ad : -40°C / 96h Powered On at –25°C (for information) Powered On at –40°C (for information)
Dry Heat Test – Operating	IEC 60068-2-2	Test Bd : 55°C / 96h
		70°C / 2h
		70°C / 24 H
Dry Heat Test – Storage	IEC 60068-2-1	Test Bd : +70°C / 96h Powered On at +70°C
Enclosure Protection	IEC 60529	Front : IP=52 Rear : IP=30
Inrush current (start-up)		T < 1,5 ms / I < 20 A T < 150 ms / I < 10 A T > 500 ms / I < 1,2 In
Supply variation	IEC 60255-6	Vn +/- 20% Vn+30% & Vn-25% for information
Overvoltage (peak withstand)	IEC 60255-6	1,32 Vn max 2 Vn during 10 ms (for information)

Supply interruption	IEC 60255-11	From 2,5 ms to 1 s at 0,8 Vn 50 ms at Vn, no malfunction (for information)
40 s interruption	IEC 60255-11	
Ripple (frequency fluctuations)	IEC 60255-11	12% Vn at f=100Hz or 120Hz 12% Vn at f=200Hz for information
Supply variations	IEC 60255-6	Vn +/- 20%
AC Voltage dips & short interruptions	EN 61000-4-11	2ms to 20ms & 50ms to 1s 50 ms at Vn, no malfunction (for information)
Frequency fluctuations	IEC 60255-6	50 Hz : from 47 to 54 Hz 60 Hz : from 57 to 63 Hz
Voltage withstand		2 Vn during 10 ms (for information)
High Frequency Disturbance	IEC 60255-22-1 IEC 61000-4-12 IEEE C37.90.1	Class 3 : 2.5kV (CM) / 1kV (DM)
		Class 2 : 1kV (CM)
Electrostatic discharge	IEC 60255-22-2 IEC 61000-4-2	Class 4 : 8kV contact / 15 kV air
Radiated Immunity	IEC 60255-22-3 IEC 61000-4-3	Class 3 : 10 V/m – 80 to 1000 MHz & spot tests
	IEEE C37.90.2	35 V/m – 25 to 1000 MHz
Fast Transient Burst	IEC 60255-22-4 IEC 61000-4-4 IEEE C37.90.1	Class 4 : 4kV – 2.5kHz (CM & DM)
		Class 3 2 kV - 2,5 kHz MC
		Class 3 : 2kV – 5kHz (CM)
Surge immunity	IEC 61000-4-5	Class 4 : 4kV (CM) – 2kV (DM)
		Class 3 : 2kV (CM) on shield
		Class 4 : 4kV (CM) for information

		Class 3 : 1 kV MC
High frequency conducted immunity	IEC 61000-4-6	Class 3 : 10 V, 0.15 – 80 MHz
Harmonics Immunity	IEC 61000-4-7	5% & 10% de H2 à H17
Power Frequency Magnetic Field Immunity	IEC 61000-4-8	Class 4 : 50 Hz – 30 A/m permanent – 300 A/m short time
		Class 5 : 100A/m for 1mn 1000A/m for 3s
Power Frequency	IEC 61000-4-16	CM 500 V / DM 250 V via 0.1 μ F
Conducted emission	EN 55022	Gr. I, class A and B : from 0.15 to 30 MHz
Radiated emission	EN 55022	Gr. I, class A and B : from 30 to 1000 MHz, 10m

Communication Standards

UCA2:

CASM 1.6 - Common Application Service Models and Mapping to MMS

GOMSFE 0.91 - Generic Object Models for Substation & Feeder Equipment

IEC 61850:

IEC 61850-8-1: *Communication networks and systems in substations – Part 8-1: Specific communication service mapping (SCSM) – Mapping to MMS(ISO/IEC 9506 Part 1 and Part 2*

Telecontrol protocol:

IEC 608670-5-101

IEC 608670-5-104.

Legacy protection protocol

IEC 60870-5-103 *International standards – First release 1997-12*

MODBUS

Automation Standard

IEC 61131-3

The Substation Automation System (SAS) shall be installed, tested and commissioned to control and monitor all the sub-station equipment from remote control center (SCADA) as well as from local SCADA.

The SAS shall contain the following main functional parts:

- Bay control Intelligence Electronic Devices (IEDs) for Control and Monitoring.
- Bay Protection Intelligent Electronic device (IEDs) for Protection as detailed in previous chapter
- Metering server (Industrial Grade) and protocol converter.
- Station Main & Hot Standby Redundant Human Machine Interface (HMI)

- Redundant managed switched Ethernet Local Area Network communication infrastructure with hot standby.
- The managed Ethernet switch shall have sufficient port redundancy (Both Fibre & Copper ports).
- The IED shall have two fiber optic ports for connecting Ethernet Switch of each LAN i.e. (PRP,architecture).
- Integrated Switches (built-in bay IEDs) are not acceptable. All the IEDs shall be directly connected to the Ethernet Interbay LAN without the use of any gateways.
- Gateway for remote control via industrial grade hardware (to SLDC) through IEC60870-5-101 & 104 protocol. All the IEDs shall be directly connected to the Ethernet PRP LAN without use of any gateways.
- The communication protocol between the bays, with the Gateway and HMI shall be UCA2/IEC 61850 in order to permit 100 Mbps peer-to-peer communications.
- Within a bay it shall be UCA2/IEC 61850 protocol.
- All IEDs shall have redundant power card.
- Gateway for Control from Remote end and State Load Dispatch Center (SLDC). The gateway should be able to communicate with SLDC on IEC 60870-5-101 & 104 protocol. The specific protocol to be implemented shall be handed over to successful bidder. It shall be the bidder's responsibility to integrate his offered system with existing SLDC system for exchange of desired data. The bidder shall ensure that proposed automation system is compatible with the existing SCADA network. Equipment required for data transfer to the existing SCADA network to interface communication equipment is in the bidder's scope of work and it will be included in the bid price.
- Gateway shall also have redundancy and redundant Gateway shall not be housed in a single cabinet. The Gateway shall also have sufficient future expandability and this shall excludes data **for all future provision bays as per Project Requirement**. The Gateways shall have redundant power cards.
- The communication link (PLCC / Fiber Optic) to SLDC is not in the scope of the bidder. However, the bidder will provide required modem both for PLCC and Fibre Optic communications to the nearest Wide Band Locations of STU/CTU which are connected to SLDC. It shall be the bidder's responsibility to integrate the offered system for desired exchange of telemetry data to SLDC.
- Redundant Local HMI & DR Work Station.
- Peripheral equipment like printers, display units, key boards, Mouse etc. 3.4.1.5. It shall enable local station control via a PC by means of human machine interface (HMI) and control software package, which shall contain an extensive range of supervisory control and data acquisition (SCADA) functions.
- Gateway IEDs shall have redundant power card.
- Gateway shall also have 100% redundancy for it's all functions like power, AI & BI/BO card etc. The Gateway shall also have sufficient future expandability and this shall excludes **data for all future provision bays as per Project Requirement**. The Gateways shall have redundant power cards
- **License of 15 years for the commissioned Sub Station Automation System (SAS) shall be provided.**
- **Vulnerability Audit and Penetration Testing by CERT-In empanelled firm: After successful commissioning of SAS, the successful Bidder shall do cyber Audit of the system by a CERT-In empanelled Cyber Security Auditor (to be approved by AEGCL). For that the company shall do Vulnerability assessment and**

Penetration testing of the SAS system and submit the report to AEGCL. The company shall fix any vulnerabilities found during the VA/PT.

It shall include communication gateway, intelligent electronic devices (IED) for bay control and inter IED communication infrastructure. **A model architecture drawing for SAS is enclosed at the end of this chapter as Annexure I.**

Bay level intelligent electronic devices (IED) for protection and control and the Managed Ethernet Switch shall be provided in the C&R panels installed in the local control room. Each IED will be directly connected to the Hot-standby Server PC (HMI) of the Station Automation System through a **PRP** Ethernet LAN on fiber optic medium and shall communicate as per the IEC61850 standard.

The communication gateway shall facilitate the information flow with SLDC/Remote Control Centre.

The bay level intelligent electronic devices (IED) for protection and control shall provide the direct connection to the switchgear without the need of interposing components and perform control, protection, and monitoring functions.

The Integration of IEC61850 communication based monitoring equipment like Online Insulating Oil drying system, Digital RTCC Relays etc with substation automation system shall be carried out and shall be included in the scope of work.

Further the Gateways shall have licenses sufficient for all the bays covered in the present scope as well as all the mentioned future bays.

All the numerical IEDs must be fully IEC 61850 compliant and must have the following features.

- Have peer-to-peer communication using GOOSE messages (IEC 61850) for interlocking.
- Should be interoperable with third party IEC 61850 compliant devices
- Should generate XML file for integration/engineering with vendor independent SCADA systems.
- **Should be directly connected to the inter bay bus on IEC 61850 without the use of any gateways.** Connections of bay protection IEDs to the IEC 61850 bus through the bay control units is not acceptable.

15.2. SYSTEM DESIGN

General System Design

- The Substation Automation System (SAS) shall be suitable for operation and monitoring of the complete substation including **all future extensions as per Project Requirement..**
- The systems shall be of the state-of-the art architecture and shall be suitable for operation under electrical environment present in Extra high voltage substations, follow the latest engineering practice, ensure long-term compatibility requirements and continuity of equipment supply and the safety of the operating staff.
- The offered SAS shall support remote control and monitoring from remote SCADA via gateways.
- The system shall be designed such that personnel without any background knowledge in Microprocessor-based technology are able to operate the system. The operator interface shall be intuitive such that operating personnel shall be able to operate the system easily after having received some basic training.

- The system shall incorporate the control, monitoring and protection functions specified, self-monitoring, signaling and testing facilities, measuring as well as memory functions, event recording and evaluation of disturbance records.
- Maintenance, modification or extension of components may not cause a shutdown of the whole substation automation system. Self-monitoring of components, modules and communication shall be incorporated to increase the availability and the reliability of the equipment and minimize maintenance.
- **Bidder shall offer the Bay level unit (a bay comprises of one circuit breaker and associated isolator, earth switches and instrument transformer), bay mimic along with relay and protection panels and Station HMI in Control Room building for overall optimization.**

15.3. Ethernet Switches

Ethernet switches that fulfill the hardened requirements concerning temperature, power supply (80-250 V DC from the Station Battery) **and complying to IEC 61850** suitable to be installed in substations shall be provided, i.e. the same data as common for numerical protection. **The Managed Ethernet Switch shall have dual Power supply provision.** The use of Ethernet Hubs is not permitted as they do not provide collision free transmission. Suitable port monitoring software shall be provided for monitoring of ports healthiness and should generate alarm in SAS.

15.4. SYSTEM ARCHITECTURE

- The SAS shall be based on a PRP architecture and on a concept of bay-oriented, distributed intelligence.
- The main process information of the station shall be stored in distributed databases. The typical SAS architecture shall be structured in two levels, i.e. in a station and a bay level.
- At bay level, the IEDs shall provide all bay level functions regarding control, monitoring and protection, inputs for status indication and outputs for commands. The IEDs should be directly connected to the switchgear without any need for additional interposition or transducers. But incase of Circuit Breaker SF6 Gas Pressure, Operating Mechanism Pressure (i.e. Air/ Pneumatic, Hydraulic and Nitrogen Pressures), if SF6 CTs are Utilizing the Pressure of SF6 Gas, Transformer Oil/ Winding temperatures, fire fighting or any Other with Transformer management Relay and OLTC Tap Position & Operation can be interfaced with BCU or any Other device interface through Transducers. The tap changing operation, synchronization of sources and trip transfer operation shall be performed through the BCU in addition to above. These parameters shall appear in Substation Automation System at Local HMI.

In GIS Sub Stations, all the gas tight chambers are required to be monitored individually phase wise for their SF6 gas density status by the bay control unit in a bay. Sufficient numbers of inputs are required to be provided in the BCU for the all the signals from the GIS Bays. In case there is any limitation of number of inputs in the BCU, additional BCUs or additional Cards(In case of Modular BCU) are required to be provided without any cost implication to AEGCL. These inputs shall be used for necessary monitoring, control and protection purpose.

The Sub-station Automation system being offered shall generally conform to provision of IEC 62351, IEEE1686 and NERC CIP (applicable part such as CIP 003, CIP-005, and CIP-007) for cyber security.

- **Tagging for Report generation shall be provided for sufficient number of signals for incorporation of all present and future bays, including 20% spare.**
- Each bay control IED shall be independent from each other and its functioning shall not be affected by any fault occurring in any of the other bay control units of the station.
- The data exchange between the electronic devices on bay and station level shall take place via the communication infrastructure. This shall be realized using fiber optic cables, thereby guaranteeing disturbance free communication. Data exchange is to be realized using IEC 61850 protocol with a redundant managed switched Ethernet communication infrastructure.
- The communication shall be in parallel mode, and such that failure of one set of fiber shall not affect the normal operation of the SAS. However, it shall be alarmed in SAS. Each fiber optic cable shall have four (4) spare fibers. IED shall have two fibre ports and one port shall be connected to individual Ethernet Switch of each LAN.
- At station level, the entire station shall be controlled and supervised from the station HMI. It shall also be possible to control and monitor the bay from the bay level equipment at all times.
- Clear control priorities shall prevent operation of a single switch at the same time from more than one of the various control levels, i.e. RCC, station HMI, bay level or apparatus level. **The priority shall always be on the lowest enabled control level.**
- The station level contains the station-oriented functions, which cannot be realized at bay level, e.g. alarm list or event list related to the entire substation, gateway for the communication with remote control centers.
- The GPS time synchronizing signal for the synchronization of the entire system with redundancy shall be provided.
- The SAS shall contain the functional parts as described in para above.

15.5. FUNCTIONAL REQUIREMENTS

The high-voltage apparatus within the station shall be operated from different places:

- ✓ Remote control centers/SLDC
- ✓ Station HMI.
- ✓ Local Bay controller IED

Operation shall be possible by only one operator at a time.

The operation shall depend on the conditions of other functions, such as interlocking, synchro check etc.

Select-before-Execute

For security reasons the command is always to be given in two stages: selection of the object and command for operation under all mode of operation except emergency operation. Final execution shall take place only when selection and command are actuated.

Command Supervision

Bay/station interlocking and blocking

Software Interlocking is to be provided to ensure that inadvertent incorrect operation of switchgear causing damage and accidents in case of false operation does not take place.

It shall be a simple layout, easy to test and simple to handle when upgrading the station with future bays. For software interlocking the bidder shall describe the scenario while an IED of another bay is switched off or fails.

A software interlock override function shall be provided which can be enabled to bypass the interlocking function.

Run Time Command Cancellation

Command execution timer (configurable) must be available for each control level connection. If the control action is not completed within a specified time, the command should get cancelled.

Self-supervision

Continuous self-supervision function with self-diagnostic feature shall be included.

User Configuration

The monitoring, controlling and configuration of all input and output logical signals and binary inputs and relay outputs for all built-in functions and signals shall be possible both locally and remotely.

It shall also be possible to interconnect and derive input and output signals, logic functions, using built-in functions, complex voltage and currents, additional logics (AND-gates, OR gates and timers). (Multi-activation of these additional functions should be possible).

The Functional requirement shall be divided into following levels:

- a). Bay (a bay comprises of one circuit breaker and associated disconnectors, earth switches and instrument transformer) Level Functions
- b). System Level Functions

15.6. BAY LEVEL FUNCTIONS

In a decentralized architecture the functionality shall be as close to the process as possible. In this respect, the following functions can be allocated at bay level:

- Bay control functions **including data collection in bay control / protection unit.**
- Bay protection functions with support of Numerical Relays defined in CRP Section.

15.7. Bay Control Functions

Overview

Functions:

- Control mode selection
- Select-before-execute principle
- Command supervision:
 - ✓ Interlocking and blocking
 - ✓ Double command
- Synchro-check, voltage selection
- Run Time Command cancellation
- Transformer Tap Changer control (raise / lower tap) (for Power Transformer bays)
- Operation counters for Circuit Breakers and Pumps.
- Transformer cooling gear, pump control and runtime supervision
- Operating pressure Monitoring & supervision (CB SF6 Gas Pressure, CB Operating Pneumatic Pressure / spring status).
- Display of interlocking and blocking
- Breaker position indication (per phase for single pole)
- Alarm annunciation
- Measurement display. (Electrical Parameters & Transformer Parameters)
- Local HMI (local guided, emergency mode)
- Interface to the station HMI.
- Data storage for at least 500 events

- Extension possibilities with additional I/O's inside the unit or via fiber optic communication and process bus

Control mode selection**Bay level Operation:**

As soon as the operator receives the operation access at bay level the operation is normally performed via bay control IED. During normal operation bay control unit allows the safe operation of all switching devices via the bay control IED.

EMERGENCY Operation

It shall be possible to close or open the selected Circuit Breaker with ON or OFF push buttons even during the outage of bay IED.

REMOTE mode

Control authority in this mode is given to a higher level (Remote SCADA) and the installation can be controlled only remotely. Control operation from lower levels shall not be possible in this operating mode.

Synchronism and energizing check

The synchronism and energizing check functions shall be bay-oriented and distributed to the bay control and/or protection devices. These features are:

- Settable voltage, phase angle, and frequency difference.
- Energizing for dead line - live bus, live line - dead bus or dead line – dead bus with no synchro-check function.
- Synchronizing between live line and live bus with synchro-check function

Voltage selection

The voltages relevant for the Synchro-check functions are dependent on the station topology, i.e. on the positions of the circuit breakers and/or the isolators. The correct voltage for synchronizing and energizing is derived from the auxiliary switches of the circuit breakers, the isolator, and earthing switch and shall be selected automatically by the bay control and protection IEDs.

Transformer Tap Changer control

Raise and lower operation of OLTC taps of Transformer shall be facilitated through Bay controller IED.

Protection Transfer Control

From BCU, necessary control shall be provided for transferring bay to TBC.

15.8. Bay Protection Functions**General**

The Protection functions are independent of Bay Control function. The Protection shall be provided by separate Protection IEDs (numerical relays) and other Protection devices as per section Relay & Protection.

IEDs shall be connected to the communication infrastructure for data sharing and meet the real-time communication requirements for automatic functions. The data presentation and the configuration of the various IEDs shall be compatible with the overall system communication and data exchange requirements.

Event and disturbance recording function

Each IED should contain an event recorder capable of storing at least 200 time-tagged events. This shall give alarm if 70% memory is full. The disturbance recorder function shall be as detailed in section C&R.

Bay Monitoring Functions

Analogue inputs for voltage and current measurements shall be connected directly to the voltage transformers (VT) and the current transformers (CT) without intermediate transducers. The values of active power (W), reactive power (VAR), frequency (Hz), and the rms values for voltage (U) and current (I) shall be calculated in the Bay control/protection unit.

15.9. SYSTEM LEVEL FUNCTIONS

Status Supervision

- Continuous monitoring of switching objects i.e. the position of each switchgear, e.g. Circuit Breaker, Isolator, Earthing Switch, Transformer tap changer etc., shall be supervised continuously. Every detected change of position shall be immediately displayed in the single-line diagram on the station
- HMI screen, recorded in the event list, and a hard copy printout shall be produced. Alarms shall be initiated in the case of spontaneous position changes.
- The switchgear positions shall be indicated by two auxiliary switches, normally closed (NC) and normally open (NO), which shall give ambivalent signals. An alarm shall be initiated if these position indications are inconsistent or if the time required for operating mechanism to change position exceeds a predefined limit.
- The SAS shall also monitor the status of sub-station auxiliaries. The status and control of auxiliaries shall be done through dedicated one or more IED and all alarm and analogue values shall be monitored and recoded through this IED.

Measurements

Analogue inputs for voltage and current measurements shall be connected directly to the voltage transformers (VT) and the current transformers (CT) without intermediate transducers. The values of active power (W), reactive power (VAR), frequency (Hz), and the rms, Max / Min values for voltage (U) and current (I) shall be calculated.

In case of Circuit Breaker SF6 Gas Pressure, Operating Mechanism Pressure (i.e. Pneumatic, Spring), if SF6 CTs are Utilizing the Pressure of SF6 Gas, Transformer Oil/ Winding temperatures, Firefighting or any Other with Transformer management Relay and OLTC Tap Position can be interfaced with BCU through Transducers. Max / Min values for the above parameters shall be calculated. These parameters shall appear in Substation Automation System at Local HMI and can monitor regularly.

The measured values shall be displayed locally on the station HMI and in the control center. The abnormal values must be discarded. The analogue values shall be updated every 2 seconds.

Threshold limit values shall be selectable for alarm indications.

The SAS shall also poll data from the Meter Server to gateway for onward communication to RCC.

Event and alarm handling

Events and alarms are generated either by the switchgear, by the control IEDs, or by the station level unit. They shall be recorded in an event list in the station HMI. Alarms shall be recorded in a separate alarm list and appear on the screen. All, or a freely selectable group of events and alarms shall also be printed out on an event printer. The alarms and events

shall be time-tagged with a time resolution of 1 ms. **The tentative list of event/ alarm for various feeders and systems are enclosed as Annexure-II and is not exhaustive, there may be addition during detail engineering or at the time of commissioning.**

15.10. Station HMI

Substation HMI Operation:

On the HMI the object has to be selected first. In case of a blocking or interlocking condition are not met; the selection shall not be possible and an appropriate alarm annunciation shall occur. If a selection is valid the position indication will show the possible direction, and the appropriate control execution button shall be pressed in order to close or open the corresponding object.

Control operation from other places (e.g. REMOTE) shall not be possible in this operating mode.

Presentation and dialogues

General

The operator station HMI shall be a redundant with hot standby and shall provide basic functions for supervision and control of the substation. The operator shall give commands to the switchgear on the screen via mouse clicks or keyboard commands.

The HMI shall give the operator access to alarms and events displayed on the screen. Aside from these lists on the screen, there shall be a printout of alarms or events in an event log.

An acoustic alarm shall indicate abnormalities, and all unacknowledged alarms shall be accessible from any screen selected by the operator.

The following standard pictures shall be available from the HMI:

- ✓ Single-line diagram showing the switchgear status, Pressure values (wherever required) and measured values (current, voltage, apparent power, freq & pf) including OLTC Tap Position, WTI, OTI & Analog set values.
- ✓ Control dialogues with interlocking and blocking details. This control dialogue shall tell the operator whether the device operation is permitted or blocked & Select before Execute.
- ✓ Measurement dialogues, Statistics & Trends
- ✓ Bay wise interlock status display and failure of any interlock within the bay by generating alarm and indication in Interlock diagram window.
- ✓ Alarm list, station / bay-oriented
- ✓ Event list, station / bay-oriented
- ✓ Substation Auxiliaries
- ✓ System status
- ✓ Printing of sequence of event list, hardcopy and reports. The reports shall be freely configurable using Crystal Report

List of signals to be configured in SAS is mentioned in Annexure-II of this chapter.

HMI design principles

Consistent design principles shall be adopted with the HMI concerning labels, colours, dialogues and fonts. Non-valid selections shall be dimmed out.

The object status shall be indicated using different status colours for:

- ✓ Selected object under command
- ✓ Selected on the screen

- ✓ Not updated, obsolete values, not in use or not sampled
- ✓ Alarm or faulty state
- ✓ Warning or blocked
- ✓ Update blocked or manually updated
- ✓ Control blocked
- ✓ Normal state

Process status displays and command procedures

The process status of the substation in terms of actual values of currents, voltages, frequency, active and reactive powers as well as the positions of circuit breakers, isolators and transformer tap-changers shall be displayed in the station single-line diagram.

In addition to above Transformer WTIs, OTI, SF6 gas Pressures of Circuit breakers , CTs and CB Operating mechanism Pressures shall also be displayed.

In order to ensure a high degree of security against undesired operation, a "select-before-execute" command procedure shall be provided. After the "selection" of a switch, the operator shall be able to recognize the selected device on the screen, and all other switchgear shall be blocked. As communication between control centre and device to be controlled is established, the operator shall be prompted to confirm the control action and only then final execute command shall be accepted. After the "execution" of the command the operated switching symbol shall flash until the switch has reached its new position.

The operator shall be in a position to execute a command only, if the switch is not blocked and if no interlocking condition is going to be violated. The interlocking statements shall be checked by the interlocking scheme implemented at bay and station level.

After command execution the operator shall receive a confirmation that the new switching position has been reached or an indication that the switching procedure was unsuccessful with the indication of the reason for non-functioning.

System Supervision and Display

The SAS system shall be comprehensively self-monitoring such that faults are immediately indicated to the operator, possibly before they develop into serious situations. Such faults are recorded as a faulty status in a system supervision display. This display shall cover the status of the entire substation including all switchgear, IEDs, communication infrastructure, protection couplers and remote communication links, and printers at the station level, etc.

Event List

The event list shall contain events that are important for the control and monitoring of the substation.

The event and associated time (with 1ms resolution) of its occurrence has to be displayed for each event.

The operator shall be able to call up the chronological event list on the monitor at any time for the whole substation or sections of it.

A printout of each display shall be possible on the hard copy printer/Dot matrix Printer / Line Printer of 132 Column.

The events shall be registered in a chronological event list in which the type of event and its time of occurrence are specified. It shall be possible to store all events in the computer for at least one month. The information shall be obtainable also from a printed event log.

The chronological event list shall contain:

- Position changes of circuit breakers, isolators and earthing devices
- Indication of protective relay operations
- Fault signals from the switchgear
- Indication when analogue measured values exceed upper and lower limits. Suitable provision shall be made in the system to define two level of alarm on either side of the value or which shall be user defined for each measurand.

- Loss of communication.
- Hourly time Stamping

Filters for selection of a certain type or group of events shall be available. The filters shall be designed to enable viewing of events grouped per:

- Date and time
- Bay
- Device
- Function e.g. trips, protection operations etc.
- Alarm class

Alarm List

Faults and errors occurring in the substation shall be listed in an alarm list and shall be immediately transmitted to the control centre. The alarm list shall substitute a conventional alarm tableau, and shall constitute an evaluation of all station alarms. It shall contain unacknowledged alarms and persisting faults. The date and time of occurrence shall be indicated.

The alarm list shall consist of a summary display of the present alarm situation. Each alarm shall be reported on one line that contains:

- The date and time of the alarm
- The name of the alarming object
- A descriptive text
- The acknowledgement state.

Whenever an alarm condition occurs, the alarm condition must be shown on the alarm list and must be displayed in a flashing state along with an audible alarm. After acknowledgement of the alarm, it should appear in a steady (i.e. not flashing) state and the audible alarm shall stop. The alarm should disappear only if the alarm condition has physically cleared and the operator has reset the alarm with a reset command. The state of the alarms shall be shown in the alarm list (Unacknowledged and persistent, Unacknowledged and cleared, Acknowledged and persistent).

Filters for selection of a certain type or group of alarms shall be available as for events.

Object picture

When selecting an object such as a circuit breaker or isolator in the single line diagram, the associated bay picture shall be presented first. In the selected object picture, all attributes like

- Type of blocking
 - Authority
 - Local / remote control
 - SLDC / SAS control
 - Errors
- etc. shall be displayed.

Control dialogues

The operator shall give commands to the system by means of mouse click located on the single-line diagram. It shall also be possible to use the keyboard for command activation. Data entry is performed with the keyboard. Dedicated control dialogues for controlling at least the following devices shall be available:

- Breaker and Disconnecter
- Transformer tap-changer

User-authority levels

It shall be possible to restrict activation of the process pictures of each object (bays, apparatus...) within a certain user authorization group. Each user shall then be given access rights to each group of objects, e.g.:

- Display only
- Normal operation (e.g. open/close of switchgear), Shift wise operator's pass word for 3 shift in a day.
- Restricted operation (e.g. by-passed interlocking)
- System administrator
- For maintenance and engineering purposes of the station HMI, the following authorization levels shall be available:
- No engineering allowed
- Engineering/configuration allowed
- Entire system management allowed

The access rights shall be defined by passwords assigned during the login procedure. Only the system administrator shall be able to add/remove users and change access rights.

15.11. Reports

The reports shall provide time-related follow-ups of measured and calculated values. The data displayed shall comprise:

Trend reports:

- Day (mean, peak)
- Month (mean, peak)
- Semi-annual (mean, peak)
- Year (mean, peak)
- Historical reports of selected analogue Values:
- Day (at 15 minutes interval)
- Week
- Month
- Year

It shall be possible to select displayed values from the database in the process display on-line. Scrolling between e.g. days shall be possible. Unsure values shall be indicated. It shall be possible to select the time period for which the specific data are kept in the memory.

Following printouts shall be available from the printer and shall be printed on demand:

- i. Daily voltage and frequency curves depicting time on X-axis and the appropriate parameters on the Y-axis. The time duration of the curve is 24 hours.
- ii. Weekly trend curves for real and derived analogue values.
- iii. Printouts of the maximum and minimum values and frequency of occurrence and duration of maximum and minimum values for each analogue parameter for each circuit in 24 hr period.
- iv. Provision shall be made for logging information about breaker status like number of operation with date and time indications.
- v. Equipment operation details shift wise and during 24 hours.
- vi. Printout on adjustable time period as well as on demand for MW, MVAR, Current, Voltage on each feeder and transformer as well as Tap Positions, temperatures (WTIs, OTI) and status of pumps and fans for transformers.
- vii. Printout on adjustable time period as well as on demand system frequency and average frequency.
- viii. Reports in specified formats which shall be developed by the contractor.

Trend Display (historical data)

It shall be possible to illustrate all types of process data as trends – input and output data, binary and analogue data. The trends shall be displayed in graphical form as column or

curve diagrams with a maximum of 10 trends per screen. Adjustable time span and scaling ranges must be provided.

It shall be possible to change the type of value logging (direct, mean, sum, or difference) on-line in the window. It shall also be possible to change the update intervals on-line in the picture as well as the selection of threshold values for alarming purposes.

Automatic Disturbance File Transfer

All recorded data from the IEDs with integrated disturbance recorder as well as dedicated disturbance recording systems shall be automatically uploaded (event triggered or once per day) to a dedicated computer and be stored on the hard disc.

Disturbance Analysis

The PC-based work station shall have necessary software to evaluate all the required information for proper fault analysis.

IED Parameter Setting

It shall be possible to access all protection and control IEDs for reading the parameters (settings) from the station HMI or from a dedicated monitoring computer. The setting of parameters or the activation of parameter sets shall only be allowed after entering a password.

Automatic Sequences

The available automatic sequences in the system should be listed and described, (e.g. sequences related to the bus transfer). It must be possible to initiate pre-defined automatic sequences by the operator and also define new automatic sequences.

15.12. GATEWAY

Communication Interface

The Substation Automation System shall have the capability to support simultaneous communications with SLDC,

The Substation Automation System shall have communication ports as follows:

- (a) Two Ports for RCC & State Load Dispatch Centre from each Gateway.
- (b) The redundant Gateway shall work as hot stand by.

The communication interface to the SAS shall allow scanning and control of defined points within the substation automation system. The substation automation system shall simultaneously respond to independent scans and commands from employer's control centers (SLDC).

SLDC Communication Interface

Employer will supply communication channels between the Substation Automation System and the SLDC. The communication channels provided by Employer will consist either of power line carrier or optical fiber.

Interface equipment:

The Contractor shall provide interface equipment for communicating between Substation Automation system and State Load Dispatch Centre (PLCC/ FO).

In case of PLCC communication any modem supplied shall not require manual equalization and shall include self-test features such as manual mark/space keying, analogue loop-back, and digital loop-back. The modems shall provide for convenient adjustment of output level and receive sensitivity. **The modem should be stand alone complete in all respects including power supply to interface the SAS with communication channel.** The configuration of tones and speed shall be programmable and maintained in non-volatile memory in the modem. All necessary hardware and software shall also be in the scope of

bidder except the communication link along with communication equipment between substation control room and SLDC.

Communication Protocol

The communication protocol for gateway to control centre must be open protocol and shall support IEC 60870-5-101,104 and IEC 61850 for all levels of communication for sub-station automation such as Bay to station HMI, gateway to remote station etc.

15.13. SYSTEM HARDWARE

Redundant Station HMI, and Disturbance Recorder Work station).

The contractor shall provide redundant station HMI in hot standby mode. **The servers used in these work stations shall be of industrial grade.**

It shall be capable to perform all functions for entire substation including future requirements as indicated in the SLD. It shall use industrial grade components. Processor and RAM shall be selected in such a manner that during normal operation not more than 30% capacity of processing and memory are used. Supplier shall demonstrate these features. The RAM, Hard Disk and Bus should latest and with maximum Values.

The capacity of hard disk shall be selected such that the following requirement should occupy less than 50% of disk space:

- 1) Storage of all analogue data (at 15 Minutes interval) and digital data including alarm, event and trend data for thirty (30) days,
- 2) Storage of all necessary software,
- 3) 500GB space for EMPLOYER'S use.

Supplier shall demonstrate that the capacity of hard disk is sufficient to meet the above requirement.

HMI (Human Machine Interface)

The VDU shall show overview diagrams (Single Line Diagrams) and complete details of the switchgear with a colour display. All event and alarm annunciation shall be selectable in the form of lists. Operation shall be by a user-friendly function keyboard and a cursor positioning device. The user interface shall be based on WINDOWS concepts with graphics & facility for panning, scrolling, zooming, decluttering etc.

For 400kV,220kV, 132kV Substations 70mm VDU high resolution screen showing total SLD, alarm, bay wise real time data to be displayed as shown in the model SAS architecture.

Visual Display Units/TFT's (Thin Film Technology)

The contractor shall provide three display units, one for station HMI, one for redundant HMI and one for DR work station. These shall have high resolution and reflection protected picture screen. High stability of the picture geometry shall be ensured. The screen shall be at least 25" diagonally (3:4) in size or more and capable of colour graphic displays.

The display shall accommodate resolution of 1280 X 1024 pixels or more.

Printer

It shall be robust & suitable for operation with a minimum of 132 characters per line for Line Printer and Dot Matrix Printer. The printing operation shall be quiet with a noise level of less than 45 dB suitable for location in the control room. Printer shall accept and print all ASCII characters via master control computer unit interface.

The printer shall have in built testing facility. Failure of the printer shall be indicated in the Station HMI. The printer shall have an off line mode selector switch to enable safe maintenance. The maintenance should be simple with provisions for ease of change of print head, ribbon changing, paper insertion etc.

All printers mounted in the control room shall be provided with printer enclosure. The enclosure shall be designed to permit full enclosure of the printers at a convenient level. Plexiglas windows shall be used to provide visual inspection of the printers and ease of reading. The printer enclosures shall be designed to protect the printers from accidental external contact & each should be removable from hinges at the back and shall be provided with lock at the front.

All reports and graphics prints shall be printed on **laser printer**

One Dot Matrix Printer (DMP) shall be exclusively used for hourly log printing.

Line printer for Events and Alarms Printing

All printers shall be continuously online through directly or printer server.

Mass Storage Unit

The mass storage unit shall be built-in to the Station HMI. All operational measured values, and indications shall be stored in a mass-storage unit of CD-ROM & DVD-ROM with 5GB or more capacity i.e CD Writer & DVD Writer (Both). The unit should support at least Read (48X), Write (24X), and Re-Write (10X) operations, with Multi-Session capability. It should support ISO9660, Rockridge and Joliet File systems. It should support formatting and use under the operating system provided for Station HMI. The monthly back up of data shall be taken on disc. The facility of back up of data shall be inherent in the software.

All the data pertaining to Substation is to store in a system year/ month / day wise. The daily data is stored in a day file of Particular Month and Year automatically from 00.00Hrs to 24.00Hrs.

Auxiliary BCU

One BCU shall be put in Station level for monitoring Station Auxiliary Supply (AC & DC), Battery Chargers, Nitrogen Fire Fighting System, Fire alarm etc.

Furniture required for HMIs, Printers, and Operators etc. The make of furniture shall be of Godrej or better.

15.14. EXTENSIBILITY IN FUTURE

Offered substation automation system shall be suitable for extension in **future for all Future Bays as per Project Requirement**. During such requirement, all the drawings and configurations, alarm/event list etc. displayed shall be designed in such a manner that its extension shall be easily performed by the employer. During such event, normal operation of the existing substation shall be unaffected and system shall not require a shutdown. The contractor shall provide all necessary software tools along with source codes to perform addition of bays in future and complete integration with SAS by the user. These software tools shall be able to configure IED, add additional analogue variable, alarm list, event list, modify interlocking logics etc. for additional bays/equipment which shall be added in future..

15.15. SOFTWARE STRUCTURE

The software package shall be structured according to the SAS architecture and strictly divided in various levels. Necessary firewall shall be provided at suitable points in software to protect the system. An extension of the station shall be possible with lowest possible efforts. Maintenance, modification or an extension of components of any feeder shall not force a shut-down of the parts of the system which are not affected by the system adaptation.

15.16. Station Level Software

Human-Machine Interface (HMI)

The base HMI software package for the operator station shall include the main SAS functions and it shall be independent of project specific hardware version and operating

system. It shall further include tools for picture editing, engineering and system configuration. The system shall be easy to use, to maintain, and to adapt according to specific user requirements. Systems shall contain a library with standard functions and applications.

15.17. Bay Level Software

System Software

The system software shall be structured in various levels. This software shall be placed in a non-volatile memory. The lowest level shall assure system performance and contain basic functions, which shall not be accessible by the application and maintenance engineer for modifications. The system shall support the generation of typical control macros and a process database for user specific data storage. In case of restoration of links after failure, the software along with hardware shall be capable of automatically synchronising with the remaining system without any manual interface. This shall be demonstrated by contractor during integrated system test.

Application software

In order to ensure robust quality and reliable software functions, the main part of the application software shall consist of standard software modules built as functional block elements. The functional blocks shall be documented and thoroughly tested. They form part of a library.

The application software within the control/protection devices shall be programmed in a functional block language.

Simulation

Simulation tools shall be provided with the system to emulate a missing equipment on UCA2/IEC61850.

The simulation tools shall be set up by the system configuration tool and be able to execute scenario defined by the user.

15.18. Network Management System

The contractor shall provide a network management system software for following management functions:

- a. Configuration Management
- b. Fault Management
- c. Performance Monitoring

This system shall be used for management of communication devices and other IEDs in the system. This NMS can be loaded in DR work-station and shall be easy to use, user friendly and menu based. The NMS shall monitor all the devices in the SAS and report if there is any fault in the monitored devices. The NMS shall

- (a) Maintain performance, resource usage, and error statistics for all managed links and devices and present this information via displays, periodic reports and on demand reports.
- (b) Maintain a graphical display of SAS connectivity and device status.
- (c) Issue alarms when error conditions occur
- (d) Provide facility to add and delete addresses and links

The bidder shall provide each software in two copies in CD to load into the system in case of any problem related with Hardware/Communication etc.

15.18(a) Cyber Security features

wherever applicable All Intelligent electronic equipment, Numerical relays, Bay control units, Bay protection units, Gateways, Transformer Tap controller/changer, etc. with IEC 61850 communication protocol shall be cyber security compliant as per latest "CEA (Cyber security in power sector) Guidelines". Specifications shall also be compliant to latest revision of IEEE 1686

15.19. TESTS

The substation automation system offered by the bidder shall be subjected to following tests to establish compliance with IEC 61850 for EHV substation equipment and specified conditions:

Type Tests:**Control IEDs and Communication Equipment:****a. Power Input:**

- i. Auxiliary Voltage
- ii. Current Circuits
- iii. Voltage Circuits
- iv. Indications

b. Accuracy Tests:

- i. Operational Measured Values
- ii. Currents
- iii. Voltages
- iv. Time resolution

c. Insulation Tests:

- i. Dielectric Tests
- ii. Impulse Voltage withstand Test

d. Influencing Quantities

- i. Limits of operation
- ii. Permissible ripples
- iii. Interruption of input voltage

e. Electromagnetic Compatibility Test:

- i. 1 MHZ. burst disturbance test
- ii. Electrostatic Discharge Test
- iii. Radiated Electromagnetic Field Disturbance Test
- iv. Electrical Fast transient Disturbance Test
- v. Conducted Disturbances Tests induced by Radio Frequency Field
- vi. Magnetic Field Test
- vii. Emission (Radio interference level) Test.
- viii. Conducted Interference Test

f. Function Tests:

- i. Indication
- ii. Commands
- iii. Measured value Acquisition
- iv. Display Indications

g. Environmental tests:

- i. Cold Temperature
- ii. Dry Heat
- iii. Wet heat
- iv. Humidity (Damp heat Cycle)
- v. Vibration
- vi. Bump
- vii. Shock

Factory Acceptance Tests:

The supplier shall submit a test specification for factory acceptance test (FAT) and commissioning tests of the station automation system for approval. For the individual bay level IED's applicable type test certificates shall be submitted.

The manufacturing phase of the SAS shall be concluded by the factory acceptance test (FAT). The purpose is to ensure that the Contractor has interpreted the specified requirements correctly and that the FAT includes checking to the degree required by the

user. The general philosophy shall be to deliver a system to site only after it has been thoroughly tested and its specified performance has been verified, as far as site conditions can be simulated in a test lab. If the FAT comprises only a certain portion of the system for practical reason, it has to be assured that this test configuration contains at least one unit of each and every type of equipment incorporated in the delivered system.

If the complete system consists of parts from various suppliers or some parts are already installed on site, the FAT shall be limited to sub-system tests. In such a case, the complete system test shall be performed on site together with the site acceptance test (SAT).

Integrated Testing

The integrated system tests shall be performed as detailed in subsequent clauses as per following configuration:

- Redundant Station HMI, DR work station, two switches (i.e. for two diameter) along with all IEDs for the Dia and printers.

All other switches for complete sub-station shall be simulated as needed.

Hardware Integration Tests:

The hardware integration test shall be performed on the specified systems to be used for Factory tests when the hardware has been installed in the factory. The operation of each item shall be verified as an integral part of system. Applicable hardware diagnostics shall be used to verify that each hardware component is completely operational and assembled into a configuration capable of supporting software integration and factory testing of the system. The equipment expansion capability shall also be verified during the hardware integration tests.

Integrated System Tests:

Integrated system tests shall verify the stability of the hardware and the software. During the tests all functions shall run concurrently and all equipment shall operate a continuous 100 Hours period. The integrated system test shall ensure the SAS is free of improper interactions between software and hardware while the system is operating as a whole.

Site Acceptance Tests:

The site acceptance tests (SAT) shall completely verify all the features of SAS hardware and software. **The successful bidder shall submit the detailed SAT procedure and SAT procedure shall be read in conjunction with the specification.**

15.20. SYSTEM OPERATION

Substation Operation

NORMAL OPERATION

Operation of the system by the operator from the remote SLDC or at the substation shall take place via industry standard HMI (Human Machine interface) subsystem consisting of graphic colour VDU, a standard keyboard and a cursor positioning device (mouse). The coloured screen shall be divided into 4 fields :

- i) Message field with display of present time and date
- ii) Display field for single line diagrams
- iii) Navigation bar with alarm/condition indication
- iv) Real time bus energization status with distinguishable colours i.e. for live & dead section of SLD.

For display of alarm annunciation, lists of events etc a separate HMI View node. shall be provided.

All operations shall be performed with mouse and/or a minimum number of function keys and cursor keys. The function keys shall have different meanings depending on the

operation. The operator shall see the relevant meanings as function tests displayed in the command field (i.e. operator prompting). For control actions, the switchgear (i.e. circuit breaker etc.) requested shall be selectable on the display by means of the cursor keys. The switching element selected shall then appear on the background that shall be flashing in a different color. The operator prompting shall distinguish between:-

- Prompting of indications e.g. fault indications in the switchgear, and
- Prompting of operational sequences e.g. execution of switching operations

The summary information displayed in the message field shall give a rapid display of alarm/message of the system in which a fault has occurred and alarm annunciation lists in which the fault is described more fully.

Each operational sequence shall be divided into single operation steps which are initiated by means of the function keys/WINDOW command by mouse. Operator prompting shall be designed in such a manner that only the permissible keys are available in the command field related to the specific operation step. Only those switching elements shall be accessed for which control actions are possible. If the operation step is rejected by the system, the operator prompting shall be supported by additional comments in the message field. The operation status shall be reset to the corresponding preceding step in the operation sequence by pressing one of the function keys. All operations shall be verified. Incorrect operations shall be indicated by comments in the message field and must not be executed.

The offer shall include a comprehensive description of the system. The above operation shall also be possible via WINDOWS based system by mouse.

15.21. POWER SUPPLY

Power for the substation automation system shall be derived from substation 220/110V DC system.

Inverter of suitable capacity shall be provided for station HMI and its peripheral devices e.g. printer etc. In the event of Power failure, necessary safeguard software shall be built for proper shutdown and restart.

15.22. DOCUMENTATION

The following documents shall be submitted for employer's approval during detailed engineering:

- (a) System Architecture Drawing
- (b) Hardware Specification
- (c) Sizing Calculations of various components
- (d) Response Time Calculation
- (e) Functional Design Document
- (f) Clear procedure describing how to add an IED/ bay in future covering all major suppliers

The following documentation to be provided for the system in the course of the project shall be consistent, CAD supported, and of similar look / feel. All CAD drawings to be provide in "dxf" format and also acrobat format.

- List of Drawings
- Substation Automation System Architecture
- Block Diagram
- Guaranteed Technical parameters, Functional Design Specification and Guaranteed availability and reliability
- Calculation for power supply dimensioning
- I/O Signal lists
- Schematic diagrams
- List of Apparatus
- List of Labels
- Logic Diagram (hardware & software)
- Control Room Lay-out
- Test Specification for Factory Acceptance Test (FAT)
- Product Technical Manuals

- Application Manuals
- Assembly Drawing
- Operator's Manual
- Testing and Commissioning Manuals
- Complete documentation of implemented protocols between various elements
- Listing of software and loadable in CD ROM
- Other documents as may be required during detailed engineering

Two sets of hard copy and Four sets of CD ROM containing all the as built documents/drawings shall be provided.

15.23. TRAINING, SUPPORT SERVICES, MAINTENANCE AND SPARES

Training at Contractor's Premises

The contractor shall arrange on its own cost all hardware and software training platform required for successful training and understanding in India. The Contractor shall provide all necessary training material. Each trainee shall receive individual copies of all technical manuals and all other documents used for training. These materials shall be sent to Employer at least two months before the scheduled commencement of the particular training course. Class materials, including the documents sent before the training courses as well as class handouts, shall become the property of Employer. Employer reserves the right to copy such materials, but for in-house training and use only. Hands-on training shall utilize equipment identical to that being supplied to Employer.

The contractor shall provide training comprehensively covering following courses.

S. No.	Name of Course	Participants from Employer	Duration
1	Computer System Hardware	2 per sub-station	7 day
2	Computer System Software	6 per sub-station	7 day
3	Application Software	2 per sub-station	7 day

A. Computer Hardware Course: The course will contain configuration of system hardware, equipment maintenance and diagnostic procedure of each element of the SAS including modems, routers, processors, technique for system expansion, and maintenance of IEDs. It will be a hand-on training.

B. Computer System Software Course: The course will cover programming language, OS software, network software, database software, system configuration, development of logic circuits. This will also be a hands-on training

C. Application Software: It will also a hands-on training and the course will contain application software and data flow, associated maintenance and expansion training, preparation and integration of new software etc.

Training offered shall be free of cost to the Employer except the logistic.

On Site Training:

After successful commissioning of the entire SAS, the contractor will impart on-site training in following areas:

S. No.	Name of Course	Participants from Employer	Duration
1	Computer System Hardware	2 per sub-station	7 day
2	Computer System Software	6 per sub-station	7 day
3	Application Software	2 per sub-station	7 day

Hands on training logic development, system configuration for extension of addition of bay, IED fault finding, trouble shooting, data analysis, changing of equipment parameters/ input data, preventive maintenance of each equipment

The site training will be also of similar nature as outlined in the previous clause, except that here the training will be on actual commissioned system and all aspects shall be covered. The training shall be conducted at each substation separately, covered in the package.

The Contractor shall submit the training modules for approval of the Employer. The training durations mentioned above is tentative only. Actual duration of the training shall be as per approved training module.

15.24. MAINTENANCE

Maintenance Responsibility during Pre-Commissioning and Commissioning Activities

During Pre-Commissioning and Commissioning activities, the Contractor shall take continual actions to ensure the guaranteed availability and shall make available all the necessary resources such as specialist personnel, spare parts, tools, test devices etc. for replacement or repair of all defective parts and shall have prime responsibility for keeping the system operational.

Maintenance Responsibility during Guarantee Period

During guarantee period as specified in tender document, contractor shall arrange bi-monthly visit of their representative to site to review the performance of system and in case any defect/shortcoming etc. is observed during the period, the same shall be set right by the contractor within 15 days free of any charge to the Employer.

15.25. RELIABILITY AND AVAILABILITY

The SAS shall be designed so that the failure of any single component, processor, or device shall not render the system unavailable. The SAS shall be designed to satisfy the very high demands for reliability and availability concerning:

- Mechanical and electrical design
- Security against electrical interference (EMI)
- High quality components and boards
- Modular, well-tested hardware
- Thoroughly developed and tested modular software
- Easy-to-understand programming language for application programming
- Detailed graphical documentation and application software
- Built-in supervision and diagnostic functions
- Security
- Experience of security requirements
- Process know-how
- Select before execute at operation
- Process status representation as double indications
- Distributed solution
- Independent units connected to the local area network
- Back-up functions
- Panel grounding immune against transient ground potential rise

Outage terms

1) Outage

The state in which substation automation system or a unit of SAS is unavailable for Normal Operation as defined in the clause above due to an event directly related to the SAS or unit of SAS. In the event, the Employer has taken any equipment/ system other than Sub-station Automation System for schedule/forced maintenance, the consequent outage to SAS shall not be considered as outage for the purpose of availability.

2) Actual outage duration (AOD)

The time elapsed in hours between the start and the end of an outage. The time shall be counted to the nearest 1/4th of an hour. Time less than 1/4th of an hour shall be counted as having duration of 1/4th of an hour.

3) Period Hours (PH)

The number of hours in the reporting period. In a full year the period hour are 8760h (8784h for a leap year).

4) Actual Outage hours (AOH)

The sum of actual outage duration within the reporting period $AOH = \Sigma AOD$

5) Availability

Each SAS shall have a total availability of 99.98 % i.e. the ratio of total time duration minus the actual outage duration to total time duration.

15.26. GUARANTEES REQUIRED

The availability for the complete SAS shall be guaranteed by the Contractor. Bidder shall include in their offer the detailed calculation for the availability. The contractor shall demonstrate their availability guaranteed by conducting the availability test on the total sub-station automation system as a whole during the pre-commissioning and commissioning periods. The test shall verify the reliability and integrity of all sub-systems. Under these conditions the test shall establish an overall availability of 99.98%. After the lapse of 700 Hours of cumulative test time, test records shall be examined to determine the conformance with availability criterion. In case of any outage during the availability test, the contractor shall rectify the problem and after rectification, the 700 Hours period start after such rectification. If test object has not been met the test shall continue until the specified availability is achieved.

The contractor has to establish the availability in a maximum period of three months from the date of commencement of the availability test.

After the satisfactory conclusion of test both contractor and employer shall mutually agree to the test results and if these results satisfy the availability criterion, the test is considered to be completed successfully. After that the system shall be taken over by the employer and then the guarantee period shall start along with the whole facilities.

15.27. SPARES**Consumables**

All consumables such as paper, cartridges shall be supplied by the contractor till the SAS is taken over by the Employer.

Availability Spares:

In addition to mandatory spares as listed in below for SAS, the bidder is required to list the recommended spares along with unit prices, which may be required for ensuring the guaranteed availability of the system. During the entire guarantee period including the pre-commissioning and commissioning periods, the successful contractor will have to make available at site his recommended spares.

Based on the requirement of recommended spares during the entire guarantee period, the Employer will decide the final list of spares that the Employer will procure for safe running of the system after the guaranteed period. The contractor is bound to supply these spares promptly.

LIST OF MANDATORY SPARES

(a) FO cables with terminations for each type and length between IEDs (One FO cable for each type/length).

(b) Patch/Cu cable with terminations of each type and length between IEDs of Station level (One cable for each type/length)

- (c) Any interface/Protocol converter (One for each type).
- (d) BI/BO card for each type of IED (one no each).
- (e) Power card for each type of IED (one no each).
- (f) Transducers of each type (one no each)
- (g) Industrial grade computer. (one number)

15.28. Major Component of SAS

Following minimum equipment shall comprise the Substation Automation System.

- i) Station HMI & Redundant Station HMI (in Hot-stand by mode) of Latest Configuration and Latest OS Software with CD & DVD Multilayer Read, write, Rewrite with Possible all types of formats, Hard disk capacity of 1TB, Key Board, Optical Mouse, integrated VGA, Integrated LAN, 25" or More TFT Monitor (4:3 Screen).
- ii) Engineering Station & Disturbance Recorder Work Station (Maintenance HMI)
- iii) Gateways with PLCC/Fibre Optic Modem
- iv) Required Inverter/UPS for 3 hour back up
- v) List of Printers with / without Printer server
 - 1. Colour Laser Printer– 1 No. (Print, Scan, Fax & Xerox) (For Reports & Disturbance records),
 - 2. Line Printer - (For Alarms and Sequence of Event recorder)
 - 3. Dot matrix printer Multi sheet paper Model – For log sheets, regular parameters at 15 min duration).
- vi) All interface equipment for gateway to SLDC.
- vii) Communication infrastructure between Bay level units, Station HMI, Printers, gateways, redundant LAN etc. as required. (Armoured FO and Cu Cables) as required.
- viii) BCUs for Sub Station Auxiliaries.
- ix) Any other equipment as necessary.

For all the SAS equipment, the power supply unit shall have dual mode i.e. main & redundant card, in case of any one card fail, the IED/Component of SAS shall have to switch over to redundant card and to generate alarm for the outage of the card.

All the type of cables used for LAN (Bay level & Station level) shall be Armoured type.

15.29. Erection, Testing & Commissioning

- a) **The bidder shall depute their Engineer to the various sites for carrying out the testing and commissioning of C&R panel.**

15.30. GUARANTEES REQUIRED

The availability for the complete SAS shall be guaranteed by the Contractor.

The Guarantee period will be stipulated for 1 year and beyond which Annual Maintenance Contract (AMC) will come into force.

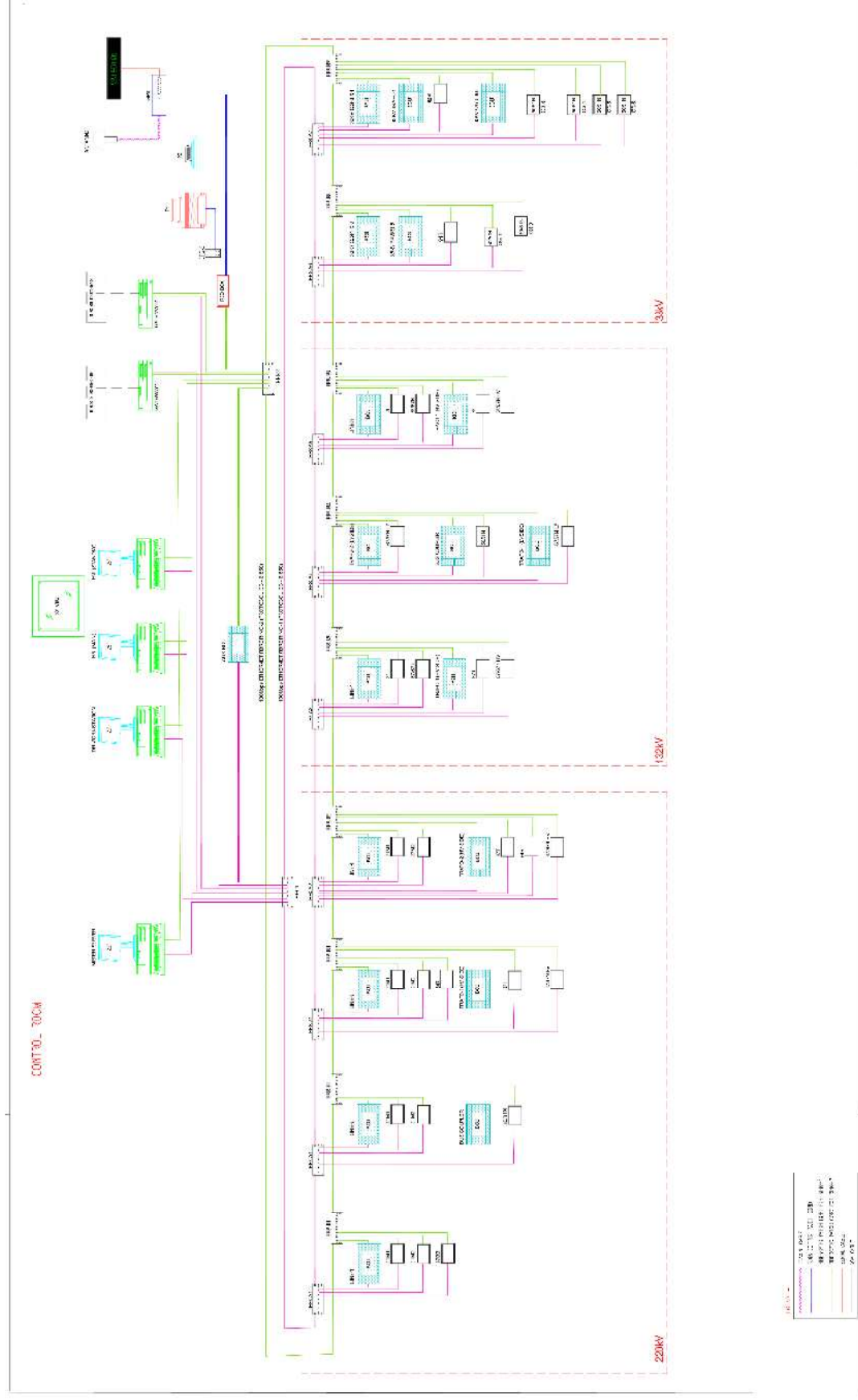
Bidder shall include in their offer the detailed calculation for the availability. The contractor shall demonstrate their availability guaranteed by conducting the availability test on the total sub-station automation system as a whole during the pre-commissioning and commissioning periods. The test shall verify the reliability and integrity of all sub-systems. Under these conditions the test shall establish an overall availability of 99.98%. After the lapse of 700 Hours of cumulative test time, test records shall be examined to determine the conformance with availability criterion. In case of any outage during the availability test, the contractor shall rectify the problem and after rectification, the 700 Hours period start after such rectification. If test object has not been met the test shall continue until the specified availability is achieved.

The contractor has to establish the availability in a maximum period of three months from the date of commencement of the availability test.

After the satisfactory conclusion of test both contractor and employer shall mutually agree to the test results and if these results satisfy the availability criterion, the test is considered to be completed successfully. After that the system shall be taken over by the employer and then the guarantee period shall start along with the whole facilities.

AMC shall be started after warranty period is over. During AMC, Manufacturer Engineer shall have to visit half yearly or as and when defects are developed. For any defects developed, Engineers are to attend the defects within three (3) working days of reporting. **The entire cost incurred for attending the issues raised/the regular yearly, half yearly visits shall be covered under the AMC. Manufacturer has the responsibility to take care of replacement of all items if required to restore the system.** During AMC, if any element is added up, integration of same is the responsibility of Manufacturer without any cost involvement to Employer.

ANNEXURE-I: SAS Architecture



Notes:

- 1) The redundant managed bus shall be realized by high speed optical bus using industrial grade components and shall be as per IEC 61850.
- 2) The IEDs for control, protection & metering (ABT compliant electronic TVM) shall be installed in the swing type simplex C & R panels inside the control room, all connections shall be realized as per IEC 61850 protocol.
- 3) Required Inverter of Numeric make, 3 KVA capacity shall be provided by the bidder.
- 4) Necessary furniture for installation of complete equipment of SAS is also in the scope of supply. The successful bidder shall submit list of complete furniture including enclosure for printers.**
- 5) For gateway, it shall communicate with Remote Control Centre and State Load Despatch Centre (SLDC) on IEC 60870-5-101 & 104 protocol.
- 6) The SLD displayed in the HMI shall be capable of distinguishing the Bus for different voltage level, bus live & dead status, bay equipment live & dead status and future extension indicating through different colours.
- 7) The printers shall be connected to station bus directly and can be managed from station HMI, as well as disturbance recorder work station.

The above Architecture is typical. The contractor is to consider the SLD of respective substation for detail BoQ, particularly for Ethernet Switches & BCUs.

ANNEXURE II

List of Analogue and Digital Inputs/ Outputs for SAS

1. Basic Monitoring requirements are:

- o Switchgear status indication
- o Measurements (U, I, P, MVA Q, f, sequence components, pf, phase angle, THD & TDD, Synchrocheck information i.e. ΔF , ΔV , $\Delta \phi$; Active & Reactive energy)
- o Event
- o Alarm
- o Winding temperature if transformers/ reactors
- o Ambient temperature
- o Status and display of station auxiliary ac & dc supply
- o Status display of transformer fire protection system
- o Acquisition of all counters in PLCC panels
- o from PLCC or independently by counting the receive/send commands
- o Acquisition of alarm and fault record from protection relays
- o Disturbance records
- o Monitoring the state of batteries by displaying DC voltage, charging current and load current etc for both 220/110-volt station & communication 48-volt batteries
- o Tap-position of Transformer

2. List of Inputs: The list of input for typical bays is as below:-

1) Analogue inputs

- For line R, Y, B phase line currents & R-N, Y-N, B-N phase voltages
- For transformers □□R, Y, B phase line currents for HV & LV
 - OTI & WTI
 - Tap position
- For bus coupler R, Y, B phase line currents
- Common
 - R-N, Y-N, B-N phase voltages for all buses
 - Frequency of all buses
 - Outside ambient temperature
 - LT ac voltages
 - 220/ 110-volt station battery voltage
 - 48-volt battery voltage

2) Digital inputs

- Line bays
 - Status of each pole of CB
 - Status of isolator, earth switch
 - CB trouble
 - CB operation / closing lock out
 - Pole discrepancy operated
 - Trip circuit faulty
 - LBB operated
 - Bus bar protection trip operated
 - Breaker auto reclosure operated
 - Tie/ transfer breaker auto reclosure operated

- AR lock out
 - Trip transfer sent/ received
 - Main I / II DPR operated
 - Directional E/F operated
 - Fuse failure alarm
 - PSB alarm
 - Broken Conductor alarm
 - Under voltage alarm
 - SOTF trip
 - Carrier aided trip
 - Main I/ II Zone 2/ Zone III trip
 - Back up O/C or E/F operated
 - PLCC protection channel I/ II failed
 - PLCC speech failed
 - BCU/ BPU failed
- Transformer bays
- Status of CB, isolator, earth switch
 - CB trouble
 - CB operation/ closing lock out
 - Pole discrepancy operated
 - Trip circuit I/ II faulty
 - BCU/ BPU failed
 - LBB operated
 - Bus bar protection operated
 - REF operated
 - Differential operated
 - Over flux alarm/ trip
 - OTI/ WTI alarm/ trip
 - Buchholz alarm/ trip
 - OLTC OSR trip
 - Low oil alarm
 - PRD I/ II operated
 - Back up O/C or E/F operated
 - Zero sequence current
 - Discrimination of PT fuse fail and circuit dead
- Bus bar Protection
- Bus bar main I/ II trip
 - Bus bar zone I/II open
 - Bus protection relay fail
 - BCU/ BPU failed

Other Signal to be incorporated in DR/SAS:

Standard DR Signal

1. For transmission Line (One & half breaker scheme)

	<u>MAIN-1</u>	-
A	Configuration of ANALOG CHANNELS	
S.No.	Channel Description	Standardized Channel Name
1	R Phase Current	I-R PH.
2	Y Phase Current	I-Y PH.
3	B Phase Current	I-B PH.
4	Neutral Current	I-N PH.
5	R Phase Voltage	V-R PH.
6	Y Phase Voltage	V-Y PH.
7	B Phase Voltage	V-B PH.
8	Open Delta Voltage	V-N (Open Delta)

B	Configuration of Digital Channels for 32 channels				
S.No.	Channel Description	(Limited to 16 Characters)	7 characters	Triggers	COMMENTS
1	MAIN CB R-PHASE OPEN	MAIN_CB_R_OPEN	M CB_RO	Y	
2	MAIN CB Y-PHASE OPEN	MAIN_CB_Y_OPEN	M CB_YO	Y	
3	MAIN CB B-PHASE OPEN	MAIN_CB_B_OPEN	M CB_BO	Y	
4	TIE CB R-PHASE OPEN	TIE_CB_R_OPEN	T CB_RO	Y	
5	TIE CB Y-PHASE OPEN	TIE_CB_Y_OPEN	T CB_YO	Y	
6	TIE CB B-PHASE OPEN	TIE_CB_B_OPEN	T CB_BO	Y	
7	MAIN1 TRIP	MAIN1_TRIP	M1_TRIP	Y	
8	MAIN2 TRIP	MAIN2_TRIP	M2_TRIP	Y	MAIN-2
9	AUTO RECLOSE OPTD MAIN CB	MAIN_CB_A/R_OPTD	M CB_AR	Y	
10	MAIN CB AR LOCKOUT	MAIN CB AR LO	MCB AR LO	N	
11	AUTO RECLOSE OPTD TIE	TIE_CB_A/R_OPTD	T CB_AR	Y	

CHAPTER 15: SUBSTATION AUTOMATION SYSTEM

B	Configuration of Digital Channels for 32 channels				
S.No	Channel Description	(Limited to 16 Characters)	7 characters	Triggers	COMMENTS
	CB				
12	TIE CB AR LOCKOUT	TIE CB A/R_LO	AR_L/O	N	
13	MAIN1/2 CARRIER RECEIVE	MAIN1/2_CARR_RECE	M1/2_CR	N	MAIN-1/2
14	DT RECEIVE CHANNEL-1/2	DT_REC_CH1/2	DTRC1/2	Y	
15	3 PH. GROUP A/B OPERATED	3PH_GR_A/B_OPTD	GRA/B_OPD	Y	
16	OVER VOLTAGE STAGE-1 OPERATED	O/V_STG1_OPTD	O/V_ST1	Y	
17	OVER VOLTAGE STAGE-2 OPERATED	O/V_STG2_OPTD	O/V_ST2	Y	
18	POWER SWING BLOCK OPERATED	PS BLK OPTD	PSB_OP	N	
19	STUB/TEED OPERATED	STUB_OPTD	SB_OPD	Y	Where ever Applicable
20	BUSBAR OPERATED (M1/M2)	BUSBAR_OPTD	BB_OPD	Y	
21	MAIN/TIE LBB OPERATED	M/T_LBB_OPTD	M/T_LBB	Y	
22	MAIN 1 ZONE-1 OPTD.	MAIN1_Z1_OPTD	M1Z1_OP	Y	
23	MAIN 1 ZONE-2 START	MAIN1_Z2_START	M1Z2_ST	N	
24	MAIN 1 ZONE-2 OPTD.	MAIN1_Z2_OPTD	M1Z2_OP	Y	
25	MAIN 1 ZONE-3 START	MAIN1_Z3_START	M1Z3_ST	N	
26	MAIN 1 ZONE-3 OPTD.	MAIN1_Z3_OPTD	M1Z3_OP	Y	
27	MAIN 1 REVERSE ZONE OPTD	MAIN1_ZR_OPTD	M1ZR_OP	Y	
28	MAIN 1/2 SOTF OPTD	M1/2_SOTF_OPD	M12SOTF	Y	
29	MAIN 1/2 DEF OPTD	DEF_OPD	DEF_OPD	Y	MAIN-1/2
30	MAIN1/2 CARR. SEND	M1/2 CARR. SEND	M12CRSD	N	MAIN-1/2
31	DIRECT TRIP SEND	DIR_TR SEND	DT_SEND	Y	
32	CARRIER AIDED TRIP	CARR_AID_TRIP	CAR_AID	Y	

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	MAIN-2	
A	Configuration of ANALOG CHANNELS	
S.No	Channel Description	Standardized Channel Name
1	R Phase Current	I-R PH.
2	Y Phase Current	I-Y PH.
3	B Phase Current	I-B PH.
4	Neutral Current	I-N PH.
5	R Phase Voltage	V-R PH.
6	Y Phase Voltage	V-Y PH.
7	B Phase Voltage	V-B PH.
8	Open Delta Voltage	V-N (Open Delta)

B	Configuration of Digital Channels for 32 channels				
S.No	Channel Description	(Limited to 16 Characters)	7 characters	Triggers	COMMENTS
1	MAIN CB R-PHASE OPEN	MAIN_CB_R_OPEN	M CB_RO	Y	
2	MAIN CB Y-PHASE OPEN	MAIN_CB_Y_OPEN	M CB_YO	Y	
3	MAIN CB B-PHASE OPEN	MAIN_CB_B_OPEN	M CB_BO	Y	
4	TIE CB R-PHASE OPEN	TIE_CB_R_OPEN	T CB_RO	Y	
5	TIE CB Y-PHASE OPEN	TIE_CB_Y_OPEN	T CB_YO	Y	
6	TIE CB B-PHASE OPEN	TIE_CB_B_OPEN	T CB_BO	Y	
7	MAIN1 TRIP	MAIN1_TRIP	M1_TRIP	Y	MAIN-1
8	MAIN2 TRIP	MAIN2_TRIP	M2_TRIP	Y	
9	MAIN 2 ZONE-1 OPTD.	MAIN2_Z1_OPTD	M2Z1_OP	Y	
10	MAIN 2 ZONE-2 START	MAIN2_Z2_START	M2Z2_ST	N	
11	MAIN 2 ZONE-2 OPTD.	MAIN2_Z2_OPTD	M2Z2_OP	Y	
12	MAIN 2 ZONE-3 START	MAIN2_Z3_START	M2Z3_ST	N	
13	MAIN 2 ZONE-3 OPTD.	MAIN2_Z3_OPTD	M2Z3_OP	Y	
14	MAIN 2 REVERSE ZONE START	MAIN2_ZR_START	M2ZR_ST	N	
15	MAIN 2 REVERSE ZONE OPTD	MAIN2_ZR_OPTD	M2ZR_OP	Y	

CHAPTER 15: SUBSTATION AUTOMATION SYSTEM

B	Configuration of Digital Channels for 32 channels				
S.No	Channel Description	(Limited to 16 Characters)	7 characters	Triggers	COMMENTS
16	POWER SWING DET.	PS_DETECTED	PS_DET	N	
17	POWER SWING BLOCK OPERATED	PS BLK OPTD	PSB_OP	N	
18	OVER VOLTAGE STAGE-1 OPERATED	O/V_STG1_OPTD	O/V_ST1	Y	
19	OVER VOLTAGE STAGE-2 OPERATED	O/V_STG2_OPTD	O/V_ST2	Y	
20	MAIN/TIE CB POLE DISCREPANCY	M/T_CB_POLE_DISC	M/T_PLDSC	N	
21	CARRIER AIDED TRIP	CAR_AID_TRP	CAR_TRP	Y	
22	MAIN-1 VT FUSE FAIL	VT_FUS_FAIL_M1	VT_FF_M1	N	MAIN-1
23	MAIN-2 VT FUSE FAIL	VT_FUS_FAIL_M2	VT_FF_M2	N	
24	MAIN-2 CARRIER RECEIVE	MAIN2_CARR_REC	M2_CR_RC	N	
25	OPTIONAL				
26	OPTIONAL				
27	OPTIONAL				
28	OPTIONAL				
29	OPTIONAL				
30	OPTIONAL				
31	OPTIONAL				
32	OPTIONAL				

	MAIN-1/2			
Configuration of Digital Channels for 16 channels				
S.No.	DIGITAL CHANNELS	(Limited to 16 Characters)	7 characters	Triggers
1	MAIN CB R-PHASE OPEN	MAIN_CB_R_OPEN	M CB_RO	Y
2	MAIN CB Y-PHASE OPEN	MAIN_CB_Y_OPEN	M CB_YO	Y
3	MAIN CB B-PHASE OPEN	MAIN_CB_B_OPEN	M CB_BO	Y

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4	TIE CB R-PHASE OPEN	TIE_CB_R_OPEN	T CB_RO	Y
5	TIE CB Y-PHASE OPEN	TIE_CB_Y_OPEN	T CB_YO	Y
6	TIE CB B-PHASE OPEN	TIE_CB_B_OPEN	T CB_BO	Y
7	MAIN1 TRIP	MAIN1_TRIP	M1_TRIP	Y
8	MAIN2 TRIP	MAIN2_TRIP	M2_TRIP	Y
9	AUTO RECLOSE OPTD M/T CB	M/T_CB_A/R_OPTD	M/TCBAR	Y
10	MAIN1/2 CARRIER RECEIVE	MAIN1/2_CARR_REC	M1/2_CR	N
11	MAIN 1/2 DEF OPTD	DEF_OPD	DEF_OPD	Y
12	DT RECEIVE CHANNEL-1/2	DT_REC_CH-1/2	DTRC1/2	Y
13	OVER VOLTAGE STAGE-1/2 OPERATED	O/V_STG1/2_OPTD	OVST1/2	Y
14	STUB/TEED/SOTF OPERATED	ST_TEE_SOTF_OPTD	STF_OPD	Y
15	BUSBAR OPERATED (M1/M2)	BUSBAR_OPTD	BB_OPD	Y
16	MAIN/TIE CB LBB OPERATED	M/T_LBB_OPTD	M/T_LBB	Y

2. DR for Transmission Line (Double Bus cum Transfer)

Main 1

A	Configuration of ANALOG CHANNELS	
S.No.	Channel Description	Standardized Channel Name
1	R Phase Current	I-R PH.
2	Y Phase Current	I-Y PH.
3	B Phase Current	I-B PH.
4	Neutral Current	I-N PH
5	R Phase Voltage	V-R PH.
6	Y Phase Voltage	V-Y PH.
7	B Phase Voltage	V-B PH.
8	Open Delta Voltage	V-N-Open Delta

B	Configuration of Digital Channels for 32 channels
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S.No.	Channel Description	(Limited to 16 Characters)	7 characters	Triggers	COMMENTS
1	MAIN CB R-PHASE OPEN	MAIN_CB_R_OPEN	M CB_RO	Y	
2	MAIN CB Y-PHASE OPEN	MAIN_CB_Y_OPEN	M CB_YO	Y	
3	MAIN CB B-PHASE OPEN	MAIN_CB_B_OPEN	M CB_BO	Y	
4	TBC CB R-PHASE OPEN	TBC_CB_R_OPEN	T CB_RO	Y	
5	TBC CB Y-PHASE OPEN	TBC_CB_Y_OPEN	T CB_YO	Y	
6	TBC CB B-PHASE OPEN	TBC_CB_B_OPEN	T CB_BO	Y	
7	MAIN1 TRIP	MAIN1_TRIP	M1_TRIP	Y	
8	MAIN2 TRIP	MAIN2_TRIP	M2_TRIP	Y	MAIN-2
9	AUTO RECLOSE OPTD MAIN CB	MAIN_CB_A/R_OPTD	M CB_AR	Y	
10	MAIN CB AR LOCKOUT	MAIN CB AR LO	MCB AR LO	N	
11	AUTO RECLOSE OPTD TBC CB	TBC_CB_A/R_OPTD	T CB_AR	Y	
12	TBC CB AR LOCKOUT	TBC_CB_A/R_LO	AR_L/O	N	
13	MAIN1/2 CARRIER RECEIVE	MAIN1/2_CARR_RE C	M1/2_CR	N	MAIN-1/2
14	DT RECEIVE CHANNEL- 1/2	DT_REC_CH1/2	DTRC1/2	Y	
15	3 PH. GROUP A/B OPERATED	3PH_GR_A/B_OPTD	GRA/B_OP D	Y	
16	OVER VOLTAGE STAGE- 1 OPERATED	O/V_STG1_OPTD	O/V_ST1	Y	
17	OVER VOLTAGE STAGE- 2 OPERATED	O/V_STG2_OPTD	O/V_ST2	Y	
18	POWER SWING BLOCK OPERATED	PS BLK OPTD	PSB_OP	N	
19	MAIN-1 VT FUSE FAIL	VT_FUS_FAIL_M1	VT_FF_M1	N	
20	BUSBAR OPERATED (M1/M2)	BUSBAR_OPTD	BB_OPD	Y	
21	MAIN/TBC LBB OPERATED	M/T_LBB_OPTD	M/T_LBB	Y	
22	MAIN 1 ZONE-1 OPTD.	MAIN1_Z1_OPTD	M1Z1_OP	Y	
23	MAIN 1 ZONE-2 START	MAIN1_Z2_START	M1Z2_ST	N	

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24	MAIN 1 ZONE-2 OPTD.	MAIN1_Z2_OPTD	M1Z2_OP	Y	
25	MAIN 1 ZONE-3 START	MAIN1_Z3_START	M1Z3_ST	N	
26	MAIN 1 ZONE-3 OPTD.	MAIN1_Z3_OPTD	M1Z3_OP	Y	
27	MAIN 1 REVERSE ZONE OPTD	MAIN1_ZR_OPTD	M1ZR_OP	Y	
28	MAIN 1/2 SOTF OPTD	M1/2_SOTF_OPD	M12SOTF	Y	
29	MAIN 1/2 DEF OPTD	DEF_OPD	DEF_OPD	Y	MAIN-1/2
30	MAIN1/2 CARR. SEND	M1/2 CARR. SEND	M12CRSD	N	MAIN-1/2
31	DIRECT TRIP SEND	DIR_TR SEND	DT_SEND	Y	
32	CARRIER AIDED TRIP	CARR_AID_TRIP	CAR_AID	Y	

	MAIN-2	
A	Configuration of ANALOG CHANNELS	
S.No.	Channel Description	Standardized Channel Name
1	R Phase Current	I-R PH.
2	Y Phase Current	I-Y PH.
3	B Phase Current	I-B PH.
4	Neutral Current	I-N PH.
5	R Phase Voltage	V-R PH.
6	Y Phase Voltage	V-Y PH.
7	B Phase Voltage	V-B PH.
8	Open Delta Voltage	V-N (Open Delta)

B	Configuration of Digital Channels for 32 channels				
S.No.	Channel Description	(Limited to 16 Characters)	7 characters	Triggers	COMMENTS
1	MAIN CB R-PHASE OPEN	MAIN_CB_R_OPEN	M CB_RO	Y	
2	MAIN CB Y-PHASE OPEN	MAIN_CB_Y_OPEN	M CB_YO	Y	
3	MAIN CB B-PHASE OPEN	MAIN_CB_B_OPEN	M CB_BO	Y	
4	TBC CB R-PHASE OPEN	TBC_CB_R_OPEN	T CB_RO	Y	
5	TBC CB Y-PHASE OPEN	TBC_CB_Y_OPEN	T CB_YO	Y	
6	TBC CB B-PHASE OPEN	TIE_CB_B_OPEN	T CB_BO	Y	

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B	Configuration of Digital Channels for 32 channels				
S.No.	Channel Description	(Limited to 16 Characters)	7 characters	Triggers	COMMENTS
7	MAIN1 TRIP	MAIN1_TRIP	M1_TRIP	Y	MAIN-1
8	MAIN2 TRIP	MAIN2_TRIP	M2_TRIP	Y	
9	MAIN 2 ZONE-1 OPTD.	MAIN2_Z1_OPTD	M2Z1_OP	Y	
10	MAIN 2 ZONE-2 START	MAIN2_Z2_START	M2Z2_ST	N	
11	MAIN 2 ZONE-2 OPTD.	MAIN2_Z2_OPTD	M2Z2_OP	Y	
12	MAIN 2 ZONE-3 START	MAIN2_Z3_START	M2Z3_ST	N	
13	MAIN 2 ZONE-3 OPTD.	MAIN2_Z3_OPTD	M2Z3_OP	Y	
14	MAIN 2 REVERSE ZONE START	MAIN2_ZR_START	M2ZR_ST	N	
15	MAIN 2 REVERSE ZONE OPTD	MAIN2_ZR_OPTD	M2ZR_OP	Y	
16	POWER SWING DET.	PS_DETECTED	PS_DET	N	
17	POWER SWING BLOCK OPERATED	PS BLK OPTD	PSB_OP	N	
18	OVER VOLTAGE STAGE-1 OPERATED	O/V_STG1_OPTD	O/V_ST1	Y	
19	OVER VOLTAGE STAGE-2 OPERATED	O/V_STG2_OPTD	O/V_ST2	Y	
20	MAIN/TBC CB POLE DISCREPANCY	M/T_CB_POLE_DISC	M/T_PLDSC	N	
21	CARRIER AIDED TRIP	CAR_AID_TRP	CAR_TRP	Y	
22	DIRECT TRIP SEND	DIR_TR SEND	DT_SEND	Y	
23	MAIN-2 VT FUSE FAIL	VT_FUS_FAIL_M2	VT_FF_M2	N	
24	MAIN-2 CARRIER RECEIVE	MAIN2_CARR_REC	M2_CR_RC	N	
25	OPTIONAL				
26	OPTIONAL				
27	OPTIONAL				
28	OPTIONAL				
29	OPTIONAL				
30	OPTIONAL				

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B	Configuration of Digital Channels for 32 channels				
S.No.	Channel Description	(Limited to 16 Characters)	7 characters	Triggers	COMMENTS
31	OPTIONAL				
32	OPTIONAL				

Configuration of Digital Channels for 16 channels				
S.No.	DIGITAL CHANNELS	(Limited to 16 Characters)	7 characters	Triggers
1	MAIN CB R-PHASE OPEN	MAIN_CB_R_OPEN	M CB_RO	Y
2	MAIN CB Y-PHASE OPEN	MAIN_CB_Y_OPEN	M CB_YO	Y
3	MAIN CB B-PHASE OPEN	MAIN_CB_B_OPEN	M CB_BO	Y
4	TBC CB R-PHASE OPEN	TBC_CB_R_OPEN	T CB_RO	Y
5	TBC CB Y-PHASE OPEN	TBC_CB_Y_OPEN	T CB_YO	Y
6	TBC CB B-PHASE OPEN	TBC_CB_B_OPEN	T CB_BO	Y
7	MAIN1 TRIP	MAIN1_TRIP	M1_TRIP	Y
8	MAIN2 TRIP	MAIN2_TRIP	M2_TRIP	Y
9	AUTO RECLOSE OPTD M/T CB	M/T_CB_A/R_OPTD	M/TCBAR	Y
10	MAIN1/2 CARRIER RECEIVE	MAIN1/2_CARR_REC	M1/2_CR	N
11	MAIN 1/2 DEF OPTD	DEF_OPD	DEF_OPD	Y
12	DT RECEIVE CHANNEL-1/2	DT_REC_CH-1/2	DTRC1/2	Y
13	OVER VOLTAGE STAGE-1/2 OPERATED	O/V_STG1/2_OPTD	OVST1/2	Y
14	SOTF OPERATED	SOTF_OPTD	STF_OPD	Y
15	BUSBAR OPERATED (M1/M2)	BUSBAR_OPTD	BB_OPD	Y
16	MAIN/TBC CB LBB OPERATED	M/T_LBB_OPTD	M/T_LBB	Y

3. DR for Transformer (one and half breaker scheme)

A	Configuration of ANALOG CHANNELS		
S.No.	Channel Description	Standardized Channel Name	COMMENTS
1	HV R Phase Current	I-R PH. HV	

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2	HV Y Phase Current	I-Y PH. HV	
3	HV B Phase Current	I-B PH. HV	
4	HV Neutral Current	I-N HV	
5	IV R Phase Current	I-R PH. IV	
6	IV Y Phase Current	I-Y PH. IV	
7	IV B Phase Current	I-B PH. IV	
9	IV Neutral Current	I-N IV	
10	R Phase DIFFERENTIAL Current (CALCULATED)	IR DIFF	
11	Y Phase DIFFERENTIAL Current (CALCULATED)	IY DIFF	
12	B Phase DIFFERENTIAL Current (CALCULATED)	IB DIFF	
13	LV R Phase Current	L-R PH. IV	OPTIONAL
14	LV Y Phase Current	L-Y PH. IV	OPTIONAL
15	LV B Phase Current	L-B PH. IV	OPTIONAL
16	LV Neutral Current	L-N IV	OPTIONAL
17	HV R Ph Voltage	V-R PH HV	OPTIONAL
18	HV Y Ph Voltage	V-Y PH HV	OPTIONAL
19	HV B Ph Voltage	V-B PH HV	OPTIONAL

B Configuration of Digital Channels for 32 channels					
S.No.	Channel Description	(Limited to 16 Characters)	7 characters	Triggers	COMMENTS
1	MAIN CB OPEN (HV SIDE)	HV_M_CB_OPEN	HV_MCBO	Y	
2	TIE CB OPEN (HV SIDE)	HV_T_CB_OPEN	HV_TCBO	Y	
3	MAIN CB OPEN (IV SIDE)	IV_M_CB_OPEN	IV_MCBO	Y	
4	TIE/TBC CB OPEN (IV SIDE)	IV_T_CB_OPEN	IV_TCBO	Y	
5	DIFFERENTIAL PROTECTION OPERATED	DIFF_PROTN_OPTD	DIF_OPD	Y	
6	REF PROTECTION OPERATED	REF_PROTN_OPTD	REF_OPD	Y	
7	HV OC PROTECTION OPERATED	HV_B/U_PROTN_OPD	HVBUOPD	Y	
8	HV EF PROTN OPERATED	HV_EF_PROTN_OPD	HVEFOPD	Y	

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9	HV OVER FLUXING OPERATED	HV_OVERFLUX_OPTD	HVOFOPD	Y	
10	IV OVER FLUXING OPERATED	IV_OVERFLUX_OPTD	IVOFOPD	Y	
11	PRV TRIP	PRV_TRIP	PRV_TRP	Y	
12	WTI TRIP	WTI_TRIP	WTI_TR	Y	HV/IV/LV
13	OSR TRIP	OSR_TRIP	OSR_TRP	Y	
14	OTI TRIP	OTI_TRIP	OTI_TRP	Y	
15	BUCHHOLZ TRIP	BUCHHOLZ_TRIP	BCZ_TRP	Y	
16	3 PH. GROUP A OPERATED	3PH_GR_A_OPTD	GRA_OPD	Y	
17	3 PH. GROUP B OPERATED	3PH_GR_B_OPTD	GRB_OPD	Y	
18	MAIN CB (HV SIDE) LBB OPTD.	HV_MAIN_LBB_OPTD	H_M_LBB	Y	
19	MAIN CB (IV SIDE) LBB OPTD.	IV_MAIN_LBB_OPTD	I_M_LBB	Y	
20	TIE CB (HV SIDE) LBB OPTD.	HV_TIE_LBB_OPTD	H_T_LBB	Y	
21	TIE/TBC CB (IV SIDE) LBB OPTD.	IV_T_LBB_OPTD	I_T_LBB	Y	
22	BUSBAR OPERATED	BUSBAR_OPTD	BB_OPD	Y	
23	DTOC OPTD	DTOC_OPTD	DTOCOPD	Y	IF APPLICABLE
24	OLTC OIL SURGE TRIP	OLTC_OIL SGTR	OL_SR_TR	Y	
25	HV VT FUSE FAIL ALARM	HVVT_FUS_FAIL	HVVT_FF	N	
26	WTI ALARM	WTI_ALARM	WTI_AL	N	HV/IV/LV
27	OTI ALARM	OTI_ALARM	OTI_AL	N	
28	OVER LOAD ALARM	OL_ALARM	OL_AL	N	
29					OPTIONAL
30					OPTIONAL
31					OPTIONAL
32					OPTIONAL

Configuration of Digital Channels for 16 channels

S.No.	DIGITAL CHANNELS	(Limited to 16 Characters)	7 characters	Triggers
1	MAIN CB OPEN (HV SIDE)	HV_M_CB_OPEN	HV_MCBO	Y
2	TIE CB OPEN (HV SIDE)	HV_T_CB_OPEN	HV_TCBO	Y

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3	MAIN CB OPEN (IV SIDE)	IV_M_CB_OPEN	IV_MCBO	Y
4	TBC/TIE CB OPEN (IV SIDE)	IV_T_CB_OPEN	IV_TCBO	Y
5	DIFFERENTIAL PROTECTION OPERATED	DIFF_PROTN_OPTD	DIF_OPD	Y
6	REF PROTECTION OPERATED	REF_PROTN_OPTD	REF_OPD	Y
7	HV BACKUP PROTECTION OPERATED	HV_B/U_PROTN_OPD	HVBUOPD	Y
8	HV/IV OVER FLUXING OPERATED	HV/IV_O/F_OPD	O/F_OPD	Y
9	PRV TRIP	PRV_TRIP	PRV_TRP	Y
10	OTI/WTI TRIP	OTI/WTI_TRIP	OT/WT_T	Y
11	BUCHHOLZ/OSR TRIP	BUCH/OSR_TRIP	B_OSR_T	Y
12	MAIN/TIE CB (HV SIDE) LBB OPTD.	M/T_HV_LBB	HV_LBB	Y
13	MAIN/TBC CB (IV SIDE) LBB OPTD.	M/T_IV_LBB	IV_LBB	Y
14	BUSBAR OPERATED	BUSBAR_OPTD	BB_OPD	Y
15	DTOC OPTD	DTOC_OPTD	DTOCOPD	Y
16	3 PH. GROUP A/B OPERATED	3PH_GR_A/B_OPTD	GRA/B_OPD	Y

4. DR for Bus/Line Reactor for one and half breaker scheme

a. For back up Impedance Relay

A	Configuration of ANALOG CHANNELS		
S.No.	Channel Description	Standardized Channel Name	COMMENTS
1	R Phase Current	I-R PH.	
2	Y Phase Current	I-Y PH.	
3	B Phase Current	I-B PH.	
4	Neutral Current	I-N PH.	
5	R Phase Voltage	V-R PH.	
6	Y Phase Voltage	V-Y PH.	
7	B Phase Voltage	V-B PH.	

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8	Neutral voltage	V-N PH.	
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B	Configuration of Digital Channels for 32 channels			
S.No.	Channel Description	(Limited to 16 Characters)	7 characters	Triggers
1	MAIN CB OPEN	MAIN_CB_OPEN	M_CB_O	Y
2	TIE CB OPEN	TIE_CB_OPEN	T_CB_O	Y
3	DIFFERENTIAL PROTECTION OPERATED	DIFF_PROTN_OPTD	DIF_OPD	Y
4	REF PROTECTION OPERATED	REF_PROTN_OPTD	REF_OPD	Y
5	BACKUP IMPEDANCE PROTN OPERATED	BU_IMP_PROTN_OPD	BUIMPOP	Y
6	PRV TRIP	PRV_TRIP	PRV_TRP	Y
7	WTI TRIP	WTI_TRIP	WTI_TRP	Y
8	WTI ALARM	WTI_ALARM	WTI_AL	Y
9	OTI TRIP	OTI_TRIP	OTI_TRP	Y
10	OTI ALARM	OTI_ALARM	OTI_AL	Y
11	BUCHHHOLZ TRIP	BUCHHHOLZ_TRIP	BCZ_TRP	Y
12	BUCHHHOLZ ALARM	BUCHHHOLZ_ALARM	BCZ_AL	Y
13	MAIN LBB OPERATED	MAIN_LBB_OPD	MLBBOPD	Y
14	TIE LBB OPERATED	TIE_LBB_OPD	TLBBOPD	Y
15	BUS BAR OPERATED	BUSBAR_OPTD	BB_OPD	Y
16	3 PH. GROUP A OPERATED	3PH_GR_A_OPTD	GRA_OPD	Y
17	3 PH. GROUP B OPERATED	3PH_GR_B_OPTD	GRB_OPD	Y
18	NGR PROTECTION OPERATED	NGR_PROTN_OPTD	NGR_OPD	Y
19	TEED PROTECTION OPERATED	TEED_PROTN_OPTD	TEE_OPD	Y
20	VT FUSE FAIL ALARM	VT_FUS_FAIL	VT_FF	N

B	Configuration of Digital Channels for 16 channels			
S.No.	Channel Description	(Limited to 16 Characters)	7 characters	Triggers
1	MAIN CB OPEN	MAIN_CB_OPEN	M_CB_O	Y

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2	TIE CB OPEN	TIE_CB_OPEN	T_CB_O	Y
3	DIFFERENTIAL PROTECTION OPERATED	DIFF_PROTN_OPTD	DIF_OPD	Y
4	REF PROTECTION OPERATED	REF_PROTN_OPTD	REF_OPD	Y
5	BACKUP IMPEDANCE PROTN OPERATED	BU_IMP_PROTN_OPD	BUIMPOP	Y
6	PRV TRIP	PRV_TRIP	PRV_TRP	Y
7	WTI TRIP	WTI_TRIP	WTI_TRP	Y
8	TEED PROTECTION OPERATED	TEED_PROTN_OPTD	TEE_OPD	Y
9	OTI TRIP	OTI_TRIP	OTI_TRP	Y
10	BUCHHHOLZ TRIP	BUCHHHOLZ_TRIP	BCZ_TRP	Y
11	MAIN LBB OPERATED	MAIN_LBB_OPD	MLBBOPD	Y
12	TIE LBB OPERATED	TIE_LBB_OPD	TLBBOPD	Y
13	BUS BAR OPERATED	BUSBAR_OPTD	BB_OPD	Y
14	3 PH. GROUP A OPERATED	3PH_GR_A_OPTD	GRA_OPD	Y
15	3 PH. GROUP B OPERATED	3PH_GR_B_OPTD	GRB_OPD	Y
16	NGR PROTECTION OPERATED	NGR_PROTN_OPTD	NGR_OPD	Y

b. For Main Differential Relay

A	Configuration of ANALOG CHANNELS	
S.No.	Channel Description	Standardized Channel Name
1	R Phase Current	I-R PH.
2	Y Phase Current	I-Y PH.
3	B Phase Current	I-B PH.
4	Neutral Current	I-N PH.
5	R Phase Current NEUTRAL SIDE	I-RN PH.
6	Y Phase Current NEUTRAL SIDE	I-YN PH.
7	B Phase Current NEUTRAL SIDE	I-BN PH.
8	R Phase DIFFERENTIAL Current (CALCULATED)	IR DIFF
9	Y Phase DIFFERENTIAL Current (CALCULATED)	IY DIFF

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10	B Phase DIFFERENTIAL Current (CALCULATED)	IB DIFF
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B	Configuration of Digital Channels for 32 channels			
S.No.	Channel Description	(Limited to 16 Characters)	7 characters	Triggers
1	MAIN CB OPEN	MAIN_CB_OPEN	M_CB_O	Y
2	TIE CB OPEN	TIE_CB_OPEN	T_CB_O	Y
3	DIFFERENTIAL PROTECTION OPERATED	DIFF_PROTN_OPTD	DIF_OPD	Y
4	REF PROTECTION OPERATED	REF_PROTN_OPTD	REF_OPD	Y
5	BACKUP IMPEDANCE PROTN OPERATED	BU_IMP_PROTN_OPD	BUIMPOP	Y
6	PRV TRIP	PRV_TRIP	PRV_TRP	Y
7	WTI TRIP	WTI_TRIP	WTI_TRP	Y
8	WTI ALARM	WTI_ALARM	WTI_AL	Y
9	OTI TRIP	OTI_TRIP	OTI_TRP	Y
10	OTI ALARM	OTI_ALARM	OTI_AL	Y
11	BUCHHHOLZ TRIP	BUCHHHOLZ_TRIP	BCZ_TRP	Y
12	BUCHHHOLZ ALARM	BUCHHHOLZ_ALARM	BCZ_AL	Y
13	MAIN LBB OPERATED	MAIN_LBB_OPD	MLBBOPD	Y
14	TIE LBB OPERATED	TIE_LBB_OPD	TLBBOPD	Y
15	BUS BAR OPERATED	BUSBAR_OPTD	BB_OPD	Y
16	3 PH. GROUP A OPERATED	3PH_GR_A_OPTD	GRA_OPD	Y
17	3 PH. GROUP B OPERATED	3PH_GR_B_OPTD	GRB_OPD	Y
18	NGR PROTECTION OPERATED	NGR_PROTN_OPTD	NGR_OPD	Y
19	TEED PROTECTION OPERATED	TEED_PROTN_OPTD	TEE_OPD	Y

B	Configuration of Digital Channels for 16 channels			
S.No.	Channel Description	(Limited to 16 Characters)	7 characters	Triggers

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1	MAIN CB OPEN	MAIN_CB_OPEN	M_CB_O	Y
2	TIE CB OPEN	TIE_CB_OPEN	T_CB_O	Y
3	DIFFERENTIAL PROTECTION OPERATED	DIFF_PROTN_OPTD	DIF_OPD	Y
4	REF PROTECTION OPERATED	REF_PROTN_OPTD	REF_OPD	Y
5	BACKUP IMPEDANCE PROTN OPERATED	BU_IMP_PROTN_OPD	BUIMPOP	Y
6	PRV TRIP	PRV_TRIP	PRV_TRP	Y
7	WTI TRIP	WTI_TRIP	WTI_TRP	Y
8	TEED PROTECTION OPERATED	TEED_PROTN_OPTD	TEE_OPD	Y
9	OTI TRIP	OTI_TRIP	OTI_TRP	Y
10	BUCHHHOLZ TRIP	BUCHHHOLZ_TRIP	BCZ_TRP	Y
11	MAIN LBB OPERATED	MAIN_LBB_OPD	MLBBOPD	Y
12	TIE LBB OPERATED	TIE_LBB_OPD	TLBBOPD	Y
13	BUS BAR OPERATED	BUSBAR_OPTD	BB_OPD	Y
14	3 PH. GROUP A OPERATED	3PH_GR_A_OPTD	GRA_OPD	Y
15	3 PH. GROUP B OPERATED	3PH_GR_B_OPTD	GRB_OPD	Y
16	NGR PROTECTION OPERATED	NGR_PROTN_OPTD	NGR_OPD	Y

5. Standard list of Sequence of Events (SOE)

SCADA SIGNAL LIST FOR VARIOUS PROTECTION & CONTROL SIGNALS

REQUIRED SIGNALS FOR DISTANCE RELAYS			
SL. NO.	TYPE	EVENT/ALARM NAME	WHETHER ALARM TO BE GENERATED
1	SPI	OVERVOLATGE STAGE 1 START	
2	SPI	OVERVOLATGE STAGE 1 GEN TRIP	Y
3	SPI	OVERVOLATGE STAGE 2 GEN TRIP	Y
4	SPI	DEF START	
5	SPI	DEF GEN TRIP	Y

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6	SPI	STUB PROTECTION OPERATED	Y
7	SPI	SOTF OPERATED	Y
8	SPI	START, Z1 R PH	
9	SPI	START, Z1 Y PH	
10	SPI	START, Z1 B PH	
11	SPI	START, Z2	
12	SPI	START, Z3	
13	SPI	START, Z4	
14	SPI	START, Z5	
15	SPI	TRIP, Z1 R PH	Y
16	SPI	TRIP, Z1 Y PH	Y
17	SPI	TRIP, Z1 B PH	Y
18	SPI	GENERAL TRIP, Z2	Y
19	SPI	GENERAL TRIP, Z3	Y
20	SPI	GENERAL TRIP, Z4	Y
21	SPI	GENERAL TRIP, Z5	Y
22	SPI	CARRIER SEND	Y
23	SPI	CARRIER RECEIVE	Y
24	SPI	CARRIER AIDED SCHEME OPERATED	Y
25	SPI	POWER SWING DETECTED	Y
26	SPI	POWER SWING BLOCKING	Y
27	SPI	DISTANCE RELAY GENERAL TRIP	Y
28	DINT	FAULT LOCATOR DISTANCE	
29	SPI	CVT FUSE FAIL	Y
30	System Diagnosis (SON)	TIME SYNCHRONIZATION ERROR	Y
31	System Diagnosis (SON)	M1 IED UNHEALTHY	Y
32	SPI	START AR	

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33	SPI	LINE ISOLATOR OPEN FOR STUB ACTIVATION	
34	SPI	DT SEND CH 1	Y
35	SPI	DT SEND CH 1	Y
36	SPI	DT RECEIVE CH 1	Y
37	SPI	DT RECEIVE CH 2	Y
38	SPI	MAIN CB R PH OPEN	
39	SPI	MAIN CB Y PH OPEN	
40	SPI	MAIN CB B PH OPEN	
41	SPI	TIE CB R PH OPEN	
42	SPI	TIE CB Y PH OPEN	
43	SPI	TIE CB B PH OPEN	
44	SPI	TRIP RELAY 86 A HEALTHY (SUPERVISION)	
45	SPI	TRIP RELAY 86 B HEALTHY (SUPERVISION)	
46	SPI	GR A RELAY OPERATED	Y
47	SPI	GR B RELAY OPERATED	Y
48	SPI	CARRIER CHANNEL 1/2 OUT OF SERVICE	Y
49	SPI	CARRIER CHANNEL 1 FAIL	Y
50	SPI	CARRIER CHANNEL 2 FAIL	Y
51	SPI	MAIN 2/1 RELAY FAIL	Y
52	SPI	GOOSE RECEIPT FAIL/TROUBLE	Y
53		ANY ADDITIONAL SIGNAL AS PER SCHEME	

REQUIRED SIGNALS FOR ICT DIFFERENTIAL RELAYS			
SL. NO.	TYPE	EVENT/ALARM NAME	WHETHER ALARM TO BE GENERATED
1	SPI	OVEREXCITATION HV START	
2	SPI	OVEREXCITATION HV ALARM	Y
3	SPI	OVEREXCITATION HV TRIP	Y

REQUIRED SIGNALS FOR ICT DIFFERENTIAL RELAYS			
SL. NO.	TYPE	EVENT/ALARM NAME	WHETHER ALARM TO BE GENERATED
4	SPI	DIFFERENTIAL CURRENT ALARM	Y
5	SPI	DIFFERENTIAL PROTECTION TRIP	Y
6	INT	RESTRAINED MODE (RESTRAINED OR UNRESTRAINED)	
7	SPI	GENERAL TRIP	Y
8	System Diagnosis (SON)	TIME SYNCHRONIZATION ERROR	Y
9	System Diagnosis (SON)	DIFFERENTIAL IED UNHEALTHY	Y
10	SPI	DIFFERENTIAL RELAY GENERAL TRIP	Y
11	SPI	OTI ALARM	Y
12	SPI	WTI HV ALARM	Y
13	SPI	WTI IV ALARM	Y
14	SPI	WTI MV ALARM	Y
15	SPI	BUCCHOLZ TRIP	Y
16	SPI	OSR 1 TRIP	Y
17	SPI	PRD 1 TRIP	Y
18	SPI	FIRE PROTECTION OPERATED	Y
19	SPI	LOW OIL LEVEL	Y
20	SPI	OTI R PH ALARM	Y
21	SPI	OTI Y PH ALARM	Y
22	SPI	OTI B PH ALARM	Y
23	SPI	OTI SPARE ICT ALARM	Y
24	SPI	WTI HV R PH ALARM	Y
25	SPI	WTI HV Y PH ALARM	Y
26	SPI	WTI HV B PH ALARM	Y

REQUIRED SIGNALS FOR ICT DIFFERENTIAL RELAYS			
SL. NO.	TYPE	EVENT/ALARM NAME	WHETHER ALARM TO BE GENERATED
27	SPI	WTI HV SPARE ICT ALARM	Y
28	SPI	WTI MV R PH ALARM	Y
29	SPI	WTI MV Y PH ALARM	Y
30	SPI	WTI MV B PH ALARM	Y
31	SPI	WTI MV SPARE ICT ALARM	Y
32	SPI	WTI IV R PH ALARM	Y
33	SPI	WTI IV Y PH ALARM	Y
34	SPI	WTI IV B PH ALARM	Y
35	SPI	WTI IV SPARE ICT ALARM	Y
36	SPI	BUCCHOLZ R PH TRIP	Y
37	SPI	BUCCHOLZ Y PH TRIP	Y
38	SPI	BUCCHOLZ B PH TRIP	Y
39	SPI	BUCCHOLZ SPARE ICT TRIP	Y
40	SPI	OSR 1 R PH TRIP	Y
41	SPI	OSR 1 Y PH TRIP	Y
42	SPI	OSR 1 B PH TRIP	Y
43	SPI	OSR 1 SPARE ICT TRIP	Y
44	SPI	PRD 1 R PH TRIP	Y
45	SPI	PRD 1 Y PH TRIP	Y
46	SPI	PRD 1 B PH TRIP	Y
47	SPI	LOW OIL LEVEL R PH	Y
48	SPI	LOW OIL LEVEL Y PH	Y
49	SPI	LOW OIL LEVEL B PH	Y
50	SPI	LOW OIL LEVEL SPARE ICT	Y
51	SPI	FIRE PROTECTION R PH OPERATED	Y
52	SPI	FIRE PROTECTION Y PH OPERATED	Y
53	SPI	FIRE PROTECTION B PH	Y

REQUIRED SIGNALS FOR ICT DIFFERENTIAL RELAYS			
SL. NO.	TYPE	EVENT/ALARM NAME	WHETHER ALARM TO BE GENERATED
		OPERATED	
54	SPI	FIRE PROTECTION SPARE ICT OPERATED	Y
55	SPI	MAIN CB R PH OPEN	
56	SPI	MAIN CB Y PH OPEN	
57	SPI	MAIN CB B PH OPEN	
58	SPI	TIE CB R PH OPEN	
59	SPI	TIE CB Y PH OPEN	
60	SPI	TIE CB B PH OPEN	
61	SPI	TRIP RELAY 86 A HEALTHY (SUPERVISION)	Y
62	SPI	TRIP RELAY 86 B HEALTHY (SUPERVISION)	Y
63	SPI	GR A RELAY OPERATED	Y
64	SPI	GR B RELAY OPERATED	Y
65	SPI	REF RELAY FAIL	Y
66	SPI	GOOSE RECEIPT FAIL/TROUBLE	Y
67	SPI	ANY ADDITIONAL SIGNAL AS PER SCHEME	

REQUIRED SIGNALS FOR ICT REF RELAYS			
SL. NO.	TYPE	EVENT/ALARM NAME	WHETHER ALARM TO BE GENERATED
1	SPI	OVEREXCITATION MV START	
2	SPI	OVEREXCITATION MV ALARM	Y
3	SPI	OVEREXCITATION MV TRIP	Y
4	System Diagnosis (SON)	TIME SYNCHRONIZATION ERROR	Y

REQUIRED SIGNALS FOR ICT REF RELAYS			
SL. NO.	TYPE	EVENT/ALARM NAME	WHETHER ALARM TO BE GENERATED
5	System Diagnosis (SON)	DIFFERENTIAL IED UNHEALTHY	Y
6	SPI	REF RELAY ALARM	Y
7	SPI	REF TRIP	Y
8	SPI	GENERAL TRIP	Y
9	SPI	REF TRIP	Y
10	SPI	OTI TRIP	Y
11	SPI	WTI HV TRIP	Y
12	SPI	WTI MV TRIP	Y
13	SPI	WTI LV TRIP	Y
14	SPI	OSR 2 TRIP	Y
15	SPI	PRD 2 TRIP	Y
16	SPI	BUCCHOLZ ALARM	Y
17	SPI	OTI R PH TRIP	Y
18	SPI	OTI Y PH TRIP	Y
19	SPI	OTI B PH TRIP	Y
20	SPI	OTI SPARE ICT TRIP	Y
21	SPI	WTI HV R PH TRIP	Y
22	SPI	WTI HV Y PH TRIP	Y
23	SPI	WTI HV B PH TRIP	Y
24	SPI	WTI HV SPARE ICT TRIP	Y
25	SPI	WTI MV R PH TRIP	Y
26	SPI	WTI MV Y PH TRIP	Y
27	SPI	WTI MV B PH TRIP	Y
28	SPI	WTI MV SPARE ICT TRIP	Y
29	SPI	WTI IV R PH TRIP	Y
30	SPI	WTI IV Y PH TRIP	Y
31	SPI	WTI IV B PH TRIP	Y

REQUIRED SIGNALS FOR ICT REF RELAYS			
SL. NO.	TYPE	EVENT/ALARM NAME	WHETHER ALARM TO BE GENERATED
32	SPI	WTI IV SPARE ICT TRIP	Y
33	SPI	BUCCHOLZ R PH ALARM	Y
34	SPI	BUCCHOLZ Y PH ALARM	Y
35	SPI	BUCCHOLZ B PH ALARM	Y
36	SPI	BUCCHOLZ SPARE ICT ALARM	Y
37	SPI	OSR 2 R PH TRIP	Y
38	SPI	OSR 2 Y PH TRIP	Y
39	SPI	OSR 2 B PH TRIP	Y
40	SPI	OSR 2 SPARE ICT TRIP	Y
41	SPI	PRD 2 R PH TRIP	Y
42	SPI	PRD 2 Y PH TRIP	Y
43	SPI	PRD 2 B PH TRIP	Y
44	SPI	PRD 2 SPARE ICT TRIP	Y
45	SPI	GOOSE RECEIPT FAIL/TROUBLE	Y
46		ANY ADDITIONAL SIGNAL AS PER SCHEME	

REQUIRED SIGNALS FOR DIRECTIONAL OVERCURRENT AND EARTH FAULT RELAYS			
SL. NO.	TYPE	EVENT/ALARM NAME	WHETHER ALARM TO BE GENERATED
1	SPI	DEF START	
2	SPI	DEF GEN TRIP	Y
3	SPI	DIRECTIONAL OVERCURRENT START	Y
4	SPI	DIRECTIONAL OVERCURRENT TRIP	Y
5	SPI	GENERAL TRIP	Y

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6	System Diagnosis (SON)	TIME SYNCHRONIZATION ERROR	Y
7	System Diagnosis (SON)	M1 IED UNHEALTHY	Y
8	SPI	GOOSE RECEIPT FAIL/TROUBLE	Y
9		ANY ADDITIONAL SIGNAL AS PER SCHEME	

REQUIRED SIGNALS FOR REACTOR DIFFERENTIAL RELAYS			
SL.NO.	TYPE	EVENT/ALARM NAME	WHETHER ALARM TO BE GENERATED
1	SPI	DIFFERENTIAL PROTECTION TRIP	Y
2	SPI	DIFFERENTIAL CURRENT ALARM	Y
3	SPI	TEE DIFFERENTIAL PROTECTION TRIP	Y
4	System Diagnosis (SON)	TIME SYNCHRONIZATION ERROR	Y
5	System Diagnosis (SON)	DIFFRENTIAL IED UNHEALTHY	Y
6	SPI	DIFFERENTIAL RELAY GENERAL TRIP	Y
7	SPI	OTI ALARM	Y
8	SPI	WTI ALARM	Y
9	SPI	BUCCHOLZ TRIP	Y
10	SPI	OSR TRIP	Y
11	SPI	PRD TRIP	Y
12	SPI	FIRE PROTECTION OPERATED	Y
13	SPI	LOW OIL LEVEL	Y
14	SPI	OTI R PH ALARM	Y
15	SPI	OTI Y PH ALARM	Y

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16	SPI	OTI B PH ALARM	Y
17	SPI	OTI SPARE PH ALARM	Y
18	SPI	WTI R PH ALARM	Y
19	SPI	WTI Y PH ALARM	Y
20	SPI	WTI B PH ALARM	Y
21	SPI	WTI SPARE ICT ALARM	Y
22	SPI	BUCCHOLZ R PH TRIP	Y
23	SPI	BUCCHOLZ Y PH TRIP	Y
24	SPI	BUCCHOLZ B PH TRIP	Y
25	SPI	BUCCHOLZ SPARE PH TRIP	Y
26	SPI	OSR R PH TRIP	Y
27	SPI	OSR Y PH TRIP	Y
28	SPI	OSR B PH TRIP	Y
29	SPI	OSR SPARE ICT TRIP	Y
30	SPI	PRD R PH TRIP	Y
31	SPI	PRD Y PH TRIP	Y
32	SPI	PRD B PH TRIP	Y
33	SPI	LOW OIL LEVEL R PH	Y
34	SPI	LOW OIL LEVEL Y PH	Y
35	SPI	LOW OIL LEVEL B PH	Y
36	SPI	LOW OIL LEVEL SPARE ICT	Y
37	SPI	FIRE PROTECTION R PH OPERATED	Y
38	SPI	FIRE PROTECTION Y PH OPERATED	Y
39	SPI	FIRE PROTECTION B PH OPERATED	Y
40	SPI	FIRE PROTECTION SPARE ICT OPERATED	Y
41	SPI	MAIN CB R PH OPEN	Y
42	SPI	MAIN CB Y PH OPEN	Y
43	SPI	MAIN CB B PH OPEN	Y

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44	SPI	TIE CB R PH OPEN	Y
45	SPI	TIE CB Y PH OPEN	Y
46	SPI	TIE CB B PH OPEN	Y
47	SPI	TRIP RELAY 86 A HEALTHY (SUPERVISION)	Y
48	SPI	TRIP RELAY 86 B HEALTHY (SUPERVISION)	Y
49	SPI	GR A RELAY OPERATED	Y
50	SPI	GR B RELAY OPERATED	Y
51	SPI	REF RELAY FAIL	Y
52	SPI	REACTOR CB R PH OPEN	APPLICABLE FOR SWITCHABLE REACTOR APPLICATION
53	SPI	REACTOR CB Y PH OPEN	
54	SPI	REACTOR CB B PH OPEN	
55	SPI	REACTOR CB SPARE PH OPEN	
56	SPI	GR A RELAY OPERATED	Y
57	SPI	GR B RELAY OPERATED	Y
58	SPI	GOOSE RECEIPT FAIL/TROUBLE	Y
59	SPI	ANY ADDITIONAL SIGNAL AS PER SCHEME	

REQUIRED SIGNALS FOR REACTOR REF RELAYS			
SL. NO.	TYPE	EVENT/ALARM NAME	WHETHER ALARM TO BE GENERATED
1	System Diagnosis (SON)	TIME SYNCHRONIZATION ERROR	Y

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2	System Diagnosis (SON)	DIFFRENTIAL IED UNHEALTHY	Y
3	SPI	REF RELAY ALARM	Y
4	SPI	REF TRIP	Y
5	SPI	GENERAL TRIP	Y
6	SPI	REF TRIP	Y
7	SPI	OTI TRIP	Y
8	SPI	WTI TRIP	Y
9	SPI	BUCCHOLZ ALARM	Y
10	SPI	OTI R PH TRIP	Y
11	SPI	OTI Y PH TRIP	Y
12	SPI	OTI B PH TRIP	Y
13	SPI	OTI SPARE ICT TRIP	Y
14	SPI	WTI R PH TRIP	Y
15	SPI	WTI Y PH TRIP	Y
16	SPI	WTI B PH TRIP	Y
17	SPI	WTI SPARE PH TRIP	Y
18	SPI	BUCCHOLZ R PH ALARM	Y
19	SPI	BUCCHOLZ Y PH ALARM	Y
20	SPI	BUCCHOLZ B PH ALARM	Y
21	SPI	BUCCHOLZ SPARE PH ALARM	Y
22	SPI	GOOSE RECEIPT FAIL/TROUBLE	Y
23		ANY ADDITIONAL SIGNAL AS PER SCHEME	

REQUIRED SIGNALS FOR REACTOR BACKUP IMPEDANCE PROTECTION RELAY			
SL. NO.	TYPE	EVENT/ALARM NAME	WHETHER ALARM TO BE GENERATED
1	SPI	START Z1	
2	SPI	Z1 TRIP	Y

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3	SPI	GENERAL TRIP	Y
4	DINT	FAULT LOCATOR DISTANCE	
5	SPI	CVT FUSE FAIL	Y
6	System Diagnosis (SON)	TIME SYNCHRONIZATION ERROR	Y
7	System Diagnosis (SON)	M1 IED UNHEALTHY	Y
22	SPI	GOOSE RECEIPT FAIL/TROUBLE	Y
8		ANY ADDITIONAL SIGNAL AS PER SCHEME	

REQUIRED SIGNALS FOR BUS BAR PROTECTION RELAYS			
SL.NO.	TYPE	EVENT/ALARM NAME	WHETHER ALARM TO BE GENERATED
1	SPI	BUS ZONE 1 TRIP	Y
2	SPI	BUS ZONE 2 TRIP	Y
3	SPI	BUS BAR BLOCKED EXTERNAL	Y
4	SPI	BUS BAR BLOCKED DUE TO COMMUNICATIONN ERROR	Y
5	SPI	BUS BAR BLOCKED DUE TO INTERMEDIATE STATUS	Y
6		CT CIRCUIT ERROR	Y

REQUIRED SIGNALS FOR BREAKER FAILURE PROTECTION RELAY PROTECTION RELAY			
SL. NO.	TYPE	EVENT/ALARM NAME	WHETHER ALARM TO BE GENERATED
1	SPI	BREAKER FAILURE PROTECTION START	Y
2	SPI	BREAKER FAILURE TRIP	Y
3	SPI	BREAKER FAILURE RETRIP	Y

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4	System Diagnosis (SON)	TIME SYNCHRONIZATION ERROR	Y
5	System Diagnosis (SON)	M1 IED UNHEALTHY	Y
6	SPI	GOOSE RECEIPT FAIL/TROUBLE	Y
7			
8		ANY ADDITIONAL SIGNAL AS PER SCHEME	

REQUIRED SIGNALS FOR BAY CONTROL UNIT				
SL.NO	TYPE	EVENT/ALARM NAME	WHETHER ALARM TO BE GENERATED	ADDITIONAL REMARKS
1	INT	BCU IN LOCAL/ REMOTE		
2	SPI	CLOSE COMMAND FROM BCU FOR AUTORECLOSE		
3	SPI	BLOCK AUTORECLOSE FUNCTION	Y	

4	INT	STATUS 1 AUTORECLOSE FUNCTION READY		
		STATUS 2 AUTORECLOSE IN PROGRESS	Y	
		STATUS 3 AUTORECLOSE SUCCESSFUL	Y	
		STATUS 10 AUTORECLOSE UNSUCCESSFUL	Y	Available in Edition 2 IEDs, not in Edition 1 IEDs
5	CMD	BAY_CB_COMMAND		
6	SPI	BAY_CB_OPEN PERMITTED OR ENABLED		

REQUIRED SIGNALS FOR BAY CONTROL UNIT				
SL.NO	TYPE	EVENT/ALARM NAME	WHETHER ALARM TO BE GENERATED	ADDITIONAL REMARKS
7	SPI	BAY_CB_CLOSE PERMITTED OR ENABLED		
8	DPI	BAY_CB R PH POSITION		
9	DPI	BAY_CB Y PH POSITION		
10	DPI	BAY_CB B PH POSITION		
11	DPI	BAY_89A_ISOLATOR POSITION		
12	CMD	BAY_89A_ISO COMMAND		
13	SPI	BAY_89A_ISO OPEN PERMITTED OR ENABLED		
14	SPI	BAY_89A_CLOSE PERMITTED OR ENABLED		
15	DPI	BAY_89AE_ISOLATOR POSITION		IF BUS EARTH SWITCH IS IN THE BAY FOR WHICH THE ASSIGNMENT IS BEING DONE, CSWI3 SHALL BE USED FOR 89 AE 1, i.e. BUS EARTH SWITCH. FOR BAY SIDE EARTH SWITCH (89AE2) SEPARATE LOGICAL NODE CSWI 10 IS PROVIDED BELOW
16	CMD	BAY_89AE_ISO COMMAND		
17	SPI	BAY_89AE_ISO OPEN PERMITTED OR ENABLED		
18	SPI	BAY_89AE_CLOSE PERMITTED OR ENABLED		
19	DPI	BAY_89 B_ISOLATOR POSITION		
20	CMD	BAY_89 B_ISO COMMAND		
21	SPI	BAY_89 B_ISO OPEN PERMITTED OR ENABLED		
22	SPI	BAY_89 B_CLOSE PERMITTED OR ENABLED		
23	DPI	BAY_89 BE_ISOLATOR		

REQUIRED SIGNALS FOR BAY CONTROL UNIT				
SL.NO	TYPE	EVENT/ALARM NAME	WHETHER ALARM TO BE GENERATED	ADDITIONAL REMARKS
		POSITION		
24	CMD	BAY_89 BE_ISO COMMAND		
25	SPI	BAY_89 BE_ISO OPEN PERMITTED OR ENABLED		
26	SPI	BAY_89 BE_CLOSE PERMITTED OR ENABLED		
27	DPI	BAY_89 C/L/T_ISOLATOR POSITION		FOR 3 PHASE TRANSFORMER S CSWI7 MAY BE USED FOR 89 T BUT FOR SINGLE PHASE TRANSFORMER S SAME HAS BEEN SEPARATELY MENTIONED
28	CMD	BAY_89 C/L/T_ISO COMMAND		
29	SPI	BAY_89 C/L/T_ISO OPEN PERMITTED OR ENABLED		
30	SPI	BAY_89 C/L/T_CLOSE PERMITTED OR ENABLED		
31	DPI	BAY_89 CE/LE/TE_ISOLATOR POSITION		FOR 3 PHASE TRANSFORMER S CSWI7 MAY BE USED FOR 89 TE BUT FOR SINGLE PHASE TRANSFORMER S SAME HAS BEEN SEPARATELY MENTIONED
32	CMD	BAY_89 CE/LE/TE_ISO COMMAND		
33	SPI	BAY_89 CE/LE/TE_ISO OPEN PERMITTED OR ENABLED		
34	SPI	BAY_89 CE/LE/TE_CLOSE PERMITTED OR ENABLED		
35	DPI	BAY_89 R_ISOLATOR POSITION		
36	CMD	BAY_89 R_ISO COMMAND		
37	SPI	BAY_89 R_ISO OPEN PERMITTED OR ENABLED		
38	SPI	BAY_89 R_CLOSE PERMITTED OR ENABLED		
39	DPI	BAY_89 RE_ISOLATOR POSITION		

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REQUIRED SIGNALS FOR BAY CONTROL UNIT				
SL.NO	TYPE	EVENT/ALARM NAME	WHETHER ALARM TO BE GENERATED	ADDITIONAL REMARKS
40	CMD	BAY_89 RE_ISO COMMAND		
41	SPI	BAY_89 RE_ISO OPEN PERMITTED OR ENABLED		
42	SPI	BAY_89 RE_CLOSE PERMITTED OR ENABLED		
43	DPI	BAY_89AE 2_ISOLATOR POSITION		USED FOR SECOND EARTH SWITCH OF ISOLATOR, WHEN BUS EARTH SWITCH IS PROVIDED
44	CMD	BAY_89AE 2_ISO COMMAND		
45	SPI	BAY_89AE 2_ISO OPEN PERMITTED OR ENABLED		
46	SPI	BAY_89AE 2_CLOSE PERMITTED OR ENABLED		
THE LOGICAL NODES FOR ISOLATOR & EARTHSWITCHES FOR 3 PH ICTs & REACTORS , e.g 89 RR,RR1,RR2 & RE and for 89TR,TR1,TR2,TRE MAY BE ASSIGNED AS PER AVAILABILITY				
47	System Diagnosis (SON)	TIME SYNCHRONIZATION ERROR	Y	
48	System Diagnosis (SON)	BCU UNHEALTHY	Y	
49	SPI	CONDITIONS OK FOR SYNCHRONIZATION		
50	SPI	SPRING DISCHARGED	Y	ANNUNCIATION FOR CIRCUIT BREAKER
51	SPI	AC MOTOR SUPPLY FAIL	Y	
52	SPI	SF6 GAS LOW	Y	
53	SPI	OPERATION LOCKED OUT	Y	
54	SPI	CB READY FOR AUTORECLOSURE	Y	
55	SPI	DC SUPPLY FAIL	Y	
56	SPI	TC-1 FAIL	Y	

REQUIRED SIGNALS FOR BAY CONTROL UNIT				
SL.NO	TYPE	EVENT/ALARM NAME	WHETHER ALARM TO BE GENERATED	ADDITIONAL REMARKS
57	SPI	TC-2 FAIL	Y	
58	SPI	POLE DISCREPANCY RELAY OPTD	Y	
59	SPI	COMPRESSOR SUPPLY FAIL	Y	
60	SPI	AIR PRESSURE LOW	Y	
61	SPI	COMPRESSOR RUN TIME SUPERVISION	Y	
62	SPI	CSD FAIL	Y	
63	SPI	GAS COMPARTMENT n Alarm Stage n	Y	ANNUNCIATION FOR GIS BAYS
64	SPI	LCC PANEL AC SUPPLY FAIL	Y	
65	SPI	LCC PANEL DC SUPPLY FAIL	Y	
66	SPI	SELECTOR SWITCH POSITION LOCAL/REMOTE	Y	
67	SPI	BUS VT MCB TRIP	Y	FOR BCUs HAVING BUS VT INPUT
6	SPI	GOOSE RECEIPT FAIL/TROUBLE	Y	
68	SPI	ADDL SIGNALS FOR CB TROUBLE ETC AS PER SCHEME		

6. List of Signal for Station Auxiliaries Panel (SAS) 110V DC

1. Voltage of 110V DCDB-1
2. Voltage of 110V DCDB-2
3. Current from 110V Battery Set -1
4. Current from 110V Battery Set -2
5. Current from 110V Battery Charger -1
6. Current from 110V Battery charger 2
7. Battery 1 Output Voltage
8. Battery 2 Output Voltage
9. Charger Trouble 1
10. Charger Trouble 2
11. Charger 1 on Boost
12. Charger 1 on Float
13. Charger 1 Failure (Float)
14. Charger 1 Failure (FCBC)
15. Charger 2 on Boost

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16. Charger 2 on Float
17. Charger 2 Failure (Float)
18. Charger 2 Failure (FCBC)
19. Charger 1 Float Current
20. Charger 1 Boost Current
21. Charger 2 Float Current
22. Charger 2 Boost Current
23. Input MCCB Incomer-1 ON (DCDB)
24. Input MCCB Incomer-2 ON (DCDB)
25. DCDB Bus coupler MCCB OFF
26. DC Earth Fault Relay Operated Sec-I
27. DC Earth Fault Relay Operated Sec-II
28. 415 V AC Supply MCCB-1 Trip
29. 415 V AC Supply MCCB-2 Trip
30. Over Temperature Indication
31. DC Overvoltage and Undervoltage relay operated
32. AC Supply Trouble (Charger)

Separate Signal for both
Charger 1, Charger 2,
DCDB 1 and DCDB 2

48 V DC

1. Voltage of 48 V DCDB 1
2. Voltage of 48 V DCDB 2
3. Current from 48 V Battery set 1
4. Current from Battery Set 2
5. Current from 48 V Charger 1
6. Current from 48 V Charger 2
7. Battery 1 Output Voltage
8. Battery 2 Output Voltage
9. Charger Trouble 1
10. Charger Trouble 2
11. Charger 1 on Boost
12. Charger 1 on Float
13. Charger 1 Failure (Float)
14. Charger 1 Failure (FCBC)
15. Charger 2 on Boost
16. Charger 2 on Float
17. Charger 2 Failure (Float)
18. Charger 2 Failure (FCBC)
19. Charger 1 Float Current
20. Charger 1 Boost Current
21. Charger 2 Float Current
22. Charger 2 Boost Current
23. Input MCCB Incomer-1 ON (DCDB)
24. Input MCCB Incomer-2 ON (DCDB)
25. DCDB Bus coupler MCCB OFF
26. DC Earth Fault Relay Operated Sec-I
27. DC Earth Fault Relay Operated Sec-II
28. 415 V AC Supply MCCB-1 Trip
29. 415 V AC Supply MCCB-2 Trip
30. Over Temperature Indication
31. DC Overvoltage and Undervoltage relay operated
32. AC Supply Trouble (Charger)

DG Set

1. DG Set Breaker ON
2. DG Set Breaker OFF
3. Low Lube Oil Pressure

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4. High Water Temperature
5. Engine Over Speed
6. Low Fuel in Service Tank
7. Over load Trip
8. Voltage RY, YB and BR
9. Current from DG set R, Y and B

Fire Fighting

1. Zone 1 Fire
2. Zone 2 Fire
3. Zone 3 Fire
4. Zone 4 Fire
5. Zone 5 Fire

Other Signal

1. PLCC Exchange Fail
2. Time Synch. Signal Fail
3. GPS Signal Fail
4. Current from Station transformer
5. Voltage from Station Transformer
6. Isolator Status of Station Transformer
7. Ambient Temperature .